(NASA-CR-175714) OPERATION AND MAINTENANCE REQUIREMENTS OF THE AFMY FEMOLELY PILOTED VEHICLE (RPV) Final Report (Lynamics Research Corp.) 212 p HC A10/MF A01 N85-23755

CSCL 01C G3/05 21034

R-430U

OPERATION AND
MAINTENANCE
REQUIREMENTS
OF THE ARMY
REMOTELY PILOTED
VEHICLE (RPV)



PESEARCH ORC

# R-430U FINAL REPORT

JPL Contract Number 956-554

# OPERATION AND MAINTENANCE REQUIREMENTS OF THE ARMY REMOTELY PILOTED VEHICLE (RPV)

**OCTOBER 31, 1983** 

Prepared For:

# CALIFORNIA INSITUTE OF TECHNOLOGY

JET PROPULSION LABORATORY 4800 Oak G: ove Drive, Pasadena, California 91103

"This work was performed for the Jet Propulsion Laboratory, California Institute of Technology sponsored by **U.S. Department of Defense**, through an agreement with the National Aeronautics and Space Administration."

Prepared By:

DYNAMICS RESEARCH CORPORATION 60 Concord Street, Wilmington, Massachusetts 01887

#### PREFACE

DRC Report R-408U "Application of the HARDMAN Methodology to the Army Remotely Piloted Vehicle (RPV)", Volumes I and II, dated April 8, 1983, (Ref. 1) described the analytical methodology used to assess the manpower, personnel and training (MPT) requirements of the Army's proposed RPV system. Report R-408U reflected the MPT requirements for a number of operating scenarios based on a twelve (12) hour operating day.

This report, Final R430U, is a continuation of DRC's prior efforts and reflects iterative analyses of the MPT requirements for an RPV system configured to accommodate both a daylight television and a forward looking infrared (FLIR) mission payload subsystem (FMPS) and related support subsystems. Additionally, this analysis incorporates a 24 hour-a-day operational scenario. Therefore, the information presented herein was developed with a view towards delineating the differences (or "deltas") imposed by the new requirements resulting from FMPS/24 hour operating day functions. Readers are referred to DRC Report R-408U for reference to detailed specifics of the initial MPT requirements analysis that used a daylight television mission payload subsystem (TVMPS) operating in a 12 hour day.

The project effort was authorized under contract number 956554 with the California Institute of Technology, Jet Propulsion Laboratory (JPL). The contract monitors were Mr. Warren Apel and Mr. Joseph Gleason of the JPL. Work on the project was performed by members of the Man-Machine Systems

Department, Dynamics Research Corporation, Wilmington, Massachusetts. The contract Program Manager was Charles Vehlow. The Report Manager was John Glasier. Principal analysts and authors of the report were Robert Guptill, Paul Hunt, John Snow, Cecil Wakelin and Annemarie Walsh. Other contributors were Marjorie Bristol, Richard Mills, and Mark Scheerhoorn. The principal programming was accomplished by William Powers. Administrative support was provided by Donna Fentross, Sharon Doherty, Dianna DiGregorio, Mary Ann Kowalski, and Dori Boudreau.

The success of the project was due in large part to the cooperation of a number of government individuals and organizations who provided information and assistance but bear no responsibility for the results of the study. DRC is particularly grateful for the assistance provided by the staff of the Tactical Airborne Remotely Piloted Vehicle/Drone System Project Manager (DRCPM-RPV) U.S. Army Aviation Research and Development Command, St. Louis Missouri; the U.S. Army Night Vision and Electro-Optics Laboratory (DELNV-SE), Fort Belvoir, Virginia; Defense-Manpower Data Center, Santa Barbara, California; Tank Automotive Command (TACOM), Ground Vehicles, Warren, Michigan; and members of the RPV development team of the Lockheed Missile and Space Company, Inc., Sunnyvale, California.

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#### SECTION 1 - EXECUTIVE SUMMARY

#### 1.1 PURPOSE

In June 1982, Dynamics Research Corporation (DRC) was placed under contract by the California Institute of Technology's Jet Propulsion Laboratory (JPL). The purpose of this initial contract was to determine the manpower, personnel and training requirements for the Army's Remotely Piloted Vehicle (RPV) system. The analytical tools used to assess the human resource requirements for this emerging weapon system included the HARDMAN methodology. 1 (Hardware vs. Manpower) methodology is a subset of DRC's Front End Analysis Technology (FEAT). FEAT addresses overall logistic support requirements, and is applied to DoD weapon systems by a multi-disciplinary team of engineers, analysts and scientists. Thus, HARDMAN is an important and integral part of a larger supportability assessment capability.

As a result of the initial contract, numerous areas within the RPV system were identified as requiring clearer definition regarding human resource supportability. One of these areas included the total manpower, personnel and training (MPT) requirements for the operation and

The HARDMAN methodology here refers to the integrated family of models and data base management techniques developed and tested by DRC for the U.S. Army. Please see ARI Technical Report, dated September, 1982, Estimating the Manpower, Personnel, and Training Requirements of the Army's Corps Support Weapon System Using the HARDMAN Methodology.

maintenance of the RPV system in a 24 hour-a-day scenario utilizing alternative air vehicle (AV) payloads. While many alternative payloads have been proposed for the Aquila RPV system, the forward looking infrared (FLIR) mission payload subsystem was selected by the Program Office as most suitable for supportability analysis at this time. Thus, DRC was awarded a five morth contract in May, 1983 to determine the MPT requirements for the RPV system operating in an around-the-clock scenario while employing daylight television and FLIR mission payload packages.

#### 1.2 SCOPE OF THE STUDY

The Remotely Piloted Vehicle (RPV) system is being developed to provide the Army with a target acquisition, target location and laser designation capability significantly enhance the effectiveness of the artillery. This RPV system will provide important assistance in reducing the operational deficiencies which exist currently fielded and projected target acquisi' Its ability to see battlefield areas at longs systems. range or targets hidden from line-of-sight ground sensors, and to recognize and identify targets through use of its broad imaging sensors, is key to its utility.

The current Aquila RPV system configuration consists of seven ground vehicles per section. Five of the basic vehicles are the ground control station (GCS) which serves as the self contained command and control post for the RPV section, a launcher subsystem (LS), a recovery subsystem (RS), a maintenance shelter (MS), and an air vehicle handler (AVH). The five air vehicles (AV) organic to the RPV section

provide real-time video imagery and target location information via a jam resistant data link. Alternative mission payload packages for the AV currently incorporate a daylight television and a forward looking infrared (FLIR) capability. Thus the RPV system will be able to perform its target acquisition missions in a wide range of weather conditions, encompassing both day and night operations.

The RPV is in the dimonstration and validation phase of development. The present schedule calls for development testing (DT) II in Fiscal Year (FY) 84-85 with operational testing (OT) II to be conducted in FY 85. Regarding the FLIR mission payload, a request for proposal (RFP) will be issued to industry in November, 1983. Contract award is anticipated in early 1984. System Initial Operational Capability (ICC) is presently scheduled for March, 1989. The FLIR payload package will be provided to the RPY system as Government Furnished Equipment (GFE). Development of this equipment is under direction of the Army's Night Vision and Electro-Optics Laboratory, Fort Belvoir, Virginia.

Presently, there is no firm date set for the RPV system's Milestone II review by the Army Systems Acquisition Review Council (ASARC). The potential baseline solution for the equipment design has been evaluated: however, alternative operational scenarios and support concepts are still being investigated. As a result, the DRC program analysis team has, in conjunction with the program office, explicitly defined the RPV baseline system to be examined The scope of this study involved the during this study. following considerations:

o Consider those equipments found within the RPV section. Included within that equipment is the FLIR mission payload subsystem (FMPS) package

which can be used as an alternative payload package for the AV;

- Apply all six steps of the HARDMAN methodology. For a complete description of the HARDMAN methodology and the contents of each step of the analysis, see Section 2 of DRC's Report entitled "Application of the HARDMAN Methodology to the Army's Remotely Piloted Vehicle (RPV)"; dated April 8, 1983; (Ref. 1);
- o Determine manpower requirements for operators and maintainers of the above equipment;
- o Analyze crew, organizational and direct support levels of maintenance; and
- o Make a comparison of human resource requirements for the RPV system operating under a 12 hour per day/daylight-only scenario versus the 24 hour per day/alternative payload scenario.

#### 1.3 RESULTS

The thrust of this study concentrated on the human resource requirements of the RPV section. Important considerations involved an operational scenario which covered an entire 24 hour-a-day period, as well as the additional equipment necessary to support around-the-clock operation. This additional equipment consisted of the FMPS.

Table 1.3-1 presents the results of the study with respect to the reference and baseline systems analyzed for the RPV. (Readers are directed to the Glossary of Definitions/

Table 1.3-1. RPV System Summary

# MANPOWER

Level	Level Tempo		Requirements	
		Section	Platoon	Army
Crew	Workload Driven			
	• 0&0	.18	. 72	1008
;	• Sustained	17	68	952
	Contingency Manning			
	• 3 Shift	27	108	1512
	• 2 Outside/ 3 Inside	21	44	616
	• 3/2 Shift	20	40	560
	FQQPRI	18	72	1008
Direct	Baseline	-	20	280
Support	Reference	-	23	322

# PERSONNEL

	Reference	e System	Baseline	System
	Sustained	3/2 Shift	Sustained	3/2 Shift
Number of MOS	23	23	21	21
Personnel Requirement*	3,325	4,361	3,216	4,305
Annual Recruit Rate	1,243	1,590	1,200	1,546
TRAINING				
Annual Training Man-Days	86,550	106,923	75,507	93,870
Annual Instructor Requirements	r 95.9	112.0	83.1	98.4

<sup>\*</sup>Includes Platoon Headquarters Personnel

Acronyms for the definition of these systems.) Additionally, the details of the RPV contingency manning alternatives are contained in Section 3. A brief description of the contingency manning alternatives follow. The short title after each description refers to how that alternative will be referenced in the report.

- Three shifts All RPV section workload inside the ground control station (GCS) and outside the GCS is performed in three shifts. (Short title 3 shifts).
- o Three shifts in the GCS and 2 shifts outside the GCS All RPV section workload within the GCS is performed in three shifts; all workload outside of the GCS is performed in two shifts. (Short title 2 outside/3 inside).
- Three shifts in the GCS and two shifts outside the GCS with outside workload shared between GCS and outside personnel All RPV section workload within the GCS is performed in three shifts; all workload outside of the GCS is performed in two shifts, but with selected GCS personnel assisting/sharing the outside shifts. (Short title 3/2 shift).

Some of the more specific results are contained in the following paragraphs, and are discussed in more detail in the appropriate sections of the report.

#### Mission

o The equipment which defines the baseline RPV section is adequate to perform those target acquisition missions assigned to the RPV section operating in a 24 hour-a-day configuration.

#### System Analysis

- o The only major piece of equipment added to the previously examined RPV baseline system includes a FLIR mission payload package.
- o FQQPRI changes of moving corrective maintenance (CM) requirements to organizational support units transfers significant maintenance workload to that supporting unit.

#### Manpower

- o Manpower requirements of the RPV syste operating around-the-clock are driven more by contingency manning requirements than by workload considerations.
- Operational manning requirement accounts for over 78% of the section workload, regardless of the scenario.
- Optimal manning for the 24 hour-a-day scenario is three shifts in the GCS and two shifts outside the GCS with outside workload shared between GCS and outside personnel (3/2 shift). This contingency manning alternative requires 20 positions.

o Twenty positions at the section level (3/2 shift) permits 2 displacement cycles per day and 5 launches per day as a basic operations profile.

#### Personnel

- Occupational Specialties (MOS) than the baseline system (23 versus 21). These are the 26T and 45G. Both of these are found at the direct support level.
- o The 13T10 MOS availability for the RPV system projects a 31% personnel shortfall (based on FY 1984 estimates).

#### Praining

- A total of nine new or modified courses will be needed for the new and modified MOS's for the reference system. Six of these courses were modified for the baseline system and two others were deleted.
- The training of five existing maintenance MOS's must be modified to accommodate the RPV system. The new RPV enlisted MOS (13T) with the Additional Skill Identifier (ASI) P9 will result in the requirement for at least three new courses of instruction. The new Warrant Officer MOS (211B) will also require a new course of instruction.

- o The requirement may exist for both a system specific organizational maintenance MOS (rather than ASI P9) and a direct support maintenance MOS. This is based on the amount of training required by the 13TP9 and the criticality of built-in-test (BIT) to perform to design specifications.
- o The FQQPRI addition of the 13T40 at the section level greatly reduces RPV skill overload.

#### Impact

o RPV manpower requirements at IOC include MOS's already projected in Fiscal 1984 to be in short supply. Among the most critical of these are:

MOS		SHORTFALL
13T	-	3 1%
26B	-	24%
63J	-	24%
26L	_	19 %
6 3W	_	19 %

#### Tradeoffs

The tradeoff selected was an examination of the maintenance tasks associated with the FLIR mission payload subsystem (FMPS) at the direct support (DS), general support (GS), and depot maintenance levels. The tradeoff, thus, became a level of repair (LOR) analysis for the FMPS. Both a non-economic and an economic LOR analysis were conducted.

The non-economic analysis narrowed the choice to only the GS and depot levels as viable alternatives for performing actual test and repair. The restriction is based on the limitations of the present test stations to adequately test electro-optic (E-O) equipment combined with the need for a clean room atmosphere for handling and repair of E-O systems and their optics.

The economic analysis then concentrated on three alternatives:

- (1) A FLIR reference system that accomplished as much repair at the GS level as possible consistent with the design. The E-O replaceable units, the optics and gyroscopes, were sent to the depot for repair.
- (2) The three major FLIR assemblies being shipped to the depot for repair. GS level maintenance performed only fault isolation and removed the assembly needing repair.
- (3) All FLIR maintenance accomplished at the GS level with depot maintenance performed for any major assemblies not repairable at GS level. FLIR subassemblies were repaired at the depot.

A DRC developed life cycle cost model was used to make the analytic comparison using those cost elements involved in a LOR decision. The results of the analysis were that alternative 3 was the least costly. Alternative 2 cost the most. Alternative 1 is therefore the recommended choice. Although alternative 1 is not the least costly, it satisfies the non-economic constraints.

#### 1.4 FACTORS INFLUENCING STUDY RESULTS

The character of this study was influenced by a number of underlying assumptions and/or constraints. A brief summary of the most significant is provided below.

#### Force Structure

- o RPV will represent a complete addition to the Army's force structure, i.e., RPV will not replace an existing system.
- o Aggregated RPV MPT requirements are based on a total requirement for 14 RPV platoons within the active Army. Each platoon is composed of a platoon headquarters and four operational RPV sections.

#### System Design

o Each item of equipment selected for both the reference and the baseline system satisfied all projected RPV operational requirements specified in the Organizational and Operational (O&O) concept and other program documentation.

#### System Operation

o Mission profile/operational-mode information represents that obtained from RPV system documentation and from the RPV Program Office. In cases where operational information was not clearly defined, "best estimates" were made by DRC

personnel and then verified with the RPV Program Office.

#### Manpower

- o Allowances and constraints for estimating manpower using the Army Manpower Authorization Criteria (MACRIT) process, contained in Army Regulation 570-2, were incorporated into the analysis.
- DRC-developed IMAGES model, (Interactive 0 Manpower Aggregation Estimation System), was used to determine workload requirements from which manpower requirements are calculated. Besides determining workload, the model also accommodated sensitivit analysis of workload requirements variations key to in system parameters. These parameters included system concepts, equipment and operational considerations.

#### Personnel

o The DRC-developed IMPACT model (Interactive Manpower-Personnel Assessment and Correlation Technology), which computes system-specific personnel requirements, is driven by steady state manpower requirements. It was assumed that initial personnel requirements were therefore already filled.

#### Training

- o Training associated with the operational test and evaluation of the proposed system and training associated with the initial fielding of the system (e.g., new equipment training) were not estimated.
- o All established training is assumed to be adequately meeting existing system performance requirements.

#### 1.5 CONCLUSIONS AND RECOMMENDATIONS

The RPV section, while operating in a 24 hour-a-day scenario and utilizing both TVMPS and FMPS payload packages, is optimally manned if operated with 3 shifts in the GCS and 2 shifts outside the GCS, with outside workload shared. This manning configuration requires a total of 20 personnel at the section level, bringing each section position to 81% of workload capacity. Hence, this configuration best satisfies all workload and contingency manning requirements.

Based upon the study's results and above conclusion, a number of recommendations are made. First, a manpower, personnel and training and requirements assessment of an RPV section deployed in the central launch configuration (ground control station and remote ground terminal forward and support elements such as launcher subsystem, recovery subsystem, and associated handling and maintenance equipment in the rear area) should be conducted. The initial study identified the possibility that workload associated with maintenance actions at the section level could be

incorporated, or shifted, into existing direct support positions, or better performed in a rear area. This present identified all operator and maintainer associated with a 24 hour-a-day operation utilizing FMPS and The proposed investigation could also include a the sensitivity analysis regarding level at which operational and maintenance workload associated with this central launch concept is performed. This level of repair analysis should include depot level maintenance considerations.

Second, a detailed Training Resource Requirements Analysis (TRRA) should be performed to evaluate the training required by the 13T MOS and 13TP MOS. Having already identified the tasks and equipment necessary for the RPV MOS 13T percennel to perform their duties, a detailed TRRA would provide the interface between the task requirements of operators and maintainers and proposed simulators and training devices. A detailed TRRA, by developing the necessary courses of instruction for the RPV operators and maintainers, would greatly assist in finalizing the RPV Individual Training Plan (ITP).

Third, an assessment of the operation of the RPV section deployed in a nuclear, biological and chemical (NBC) environment should be conducted. Such an analysis would verify time to perform designated operator and maintainer tasks as well as determine the effectiveness of operating under NBC conditions. Additionally, as an integral part of the assessment, a human factors analysis of the ground control station should be performed. Operating within this controlled environment for extended periods of time would be key to the overall NBC evaluation.

#### SECTION 2 - SYSTEMS ANALYSIS

#### 2.1 COLLECT AND REVIEW FLIR/24 HOUR SCENARIO INFORMATION

For two main reasons, substantial documentation regarding the RPV system's design requirements, operational scenario and workload information exists in DRC's Consolidated Data Base (CDB): (1) the RPV system is in the demonstration and validation phase of the program's acquisition cycle, hence much documentation of system-specific information has been accomplished by the program office and the prime contractor, and (2) the products and findings of DRC's previous RPV study are included in the automated audit trail. With the exception of the FLIR mission payload subsystem (FMPS), information required for this human resource requirements analysis of the RPV was an update of the previous study's CDB. In the case of the FMPS, initial system information had to be collected and reviewed by DRC analysts and subsequently integrated into the RPV CDB.

The primary documents that provided an update of DRC's original RPV CDB were the Army's Basis of Issue Plan Feeder Data (BOIPFD), (Ref. 2) the Final Qualitative and Quantitative Personnel Requirements Information (FQQPRI), (Ref. 3) and the latest Logistic Support Analysis Record (LSAR) (Ref. 4) summaries for the RPV system. Documentation from the Army's Night Vision and Electro-Optics Laboratory, the Navy's Maintenance and Material Management (3-M) system and a commercial vendor of FLIR equipment plus interviews with RPV program office subject matter experts, assisted in identifying viable FLIR information.

#### 2.2 PERFORM SYSTEM ANALYSIS

#### 2.2.1 System Functional Requirements Analysis

The RPV function/task listing found in Appendix A of Volume II of DRC's initial RPV report (Ref. 1) as well as the RPV task taxonomy contained in Appendix B of that report were reviewed and updated. This revision encompassed not only FLIR mission payload/24 hour scenario considerations but addressed any maintenance task changes luded in the FQQPRI documentation. Section 3.1 of report will detail the updated information regarding and failure rate data.

#### 2.2.2 System Engineering Analysis

In order to delineate the hardware of an RPV FLIR mission payload subsystem (FMPS), an equipment description of the generic RPV FMPS at the major assembly level used in the engineering analysis is included in this section. The mission payload compartment (see Figure 2.2-1) contains the payload, one segment of the flight control system and the attitude reference assembly mounted on top of the payload. A removable access hatch is provided on the topside of the compartment (Ref. 5).

The FMPS is interchangeable with the daylight television mission payload system (TVMPS) both as to form and fit. The FMPS will use the same connections and be electrically interchangeable with the TVMPS. The controls and displays for the MPS are contained in the mission payload operator control and display (C&D) console located in the ground

MISSION PAYLCAD COMPARTMENT ORIGHAL PAGE M OF POOR QUALTEY • ATTITUDE REFERENCE **ASSEMBLY** • FLIGHT CONTROL SYSTEM • FMPS COVER LASER TRANSMITTER • POWER SUPPLY • PROCESSOR **ELECTRONICS PAYLOAD** SUPPORT **ASSEMBLY FURRET ASSEMBLY** • REAR **COVER** • OUTER GIMBAL ● WINDOW **COVER** ● AZ (INNER) GIMBAL # FLIR • RANGE RX

Figure 2.2-1. FLIR Mission Payload Subsystem (FMPS)

FMPS WAJOR ASSEMBLIES

control station (GCS). The C&D for the alternative payload, TVMPS and FMPS, will be integrated into the same replaceable units. This is feasible since the functions and displays for the FLIR sensor (in spite of differences in functional names) are either the same or similar enough to the TV sensor. There are minor differences in the names of controls but the control positions on the control panel are essentially the same except for an additional switch function; black/white or white/black background.

The technical information collected on a generic FLIR MPS as sufficient to allow an engineering comparability analysis to be conducted for this study. In addition, as part of the engineering analysis, a thorough review of available RPV LSAR summaries, dated 13 June 1983, was performed. This review verified that no significant changes had occurred in failure rates and task data from that already developed in DRC's previous system engineering analysis efforts. Therefore, having completed the LSAR review, the consolidation of suitable FLIR reliability and maintainability (R&M) parameters was the only remaining task to complete the RPV CDB for this portion of the study.

#### 2.2.3 RAM Data Development

To conduct an engineering comparability analysis, reliability, availability and maintainability (RAM) data is required. For this iteration, a FLIR reference system was identified in a Navy P-3 aircraft which was supported by reliability and maintainability (R&M) data resident in the Navy's 3-M maintenance data collection program. This R&M information, which served as the basic data necessary for reference system workload determination, was analyzed and

rate data was selected for the analysis. failure Maintainability data was perturbed in the area of corrective preventive maintenance task requirements organizational maintenance level. This assumption was based upon the fact that only organizational maintenance tasks would be required in consonance with those tasks associated data in LSAR summaries. with RPV TVMPS Comparable FLIR task times were developed from FLIR contractor estimates. These estimates are based on experience attained by current manufacturers of FLIR subsystems who have fielded a prototype FMPS and have ongoing foreign military sales programs for RPV-type payload subsystems.

For the engineering evaluation of a FLIR baseline system, DRC contacted commercial vendors of RPV FMPS packages to derive comparable FLIR R&M values. The assumption for the use of this technical data source was the fact that the RPV's FMPS was to be government furnished equipment (GFE) and, therefore, R&M data values would be closer to present RPV FLIR designs than to a new design comprised entirely of advanced technology. Additionally, this contractor had accomplished some preliminary analysis of the technical requirements of their product line in light of the prospective specifications for the y's FLIR MPS.

DRC analysts deemed these technical efforts as credible and subsequently used these R&M projections and level of repair structure as the basis for the maintenance workload determination of the FLIR baseline system. Figure 2.2-1 depicts a generic FLIR baseline design predicated on this contractor's initial engineering effort for an Army RPV FLIR subsystem. DRC's use of contractor developed data does not construe a favoring of one contractor's FLIR MPS design over

any other prospective contractor's design. Rather, it is an attempt to reflect state-of-the-art in assessing technological capability for the Army's RPV FLIR subsystem.

#### 2.3 IDENTIFI SYSTEM ANALYSIS RESULTS

Results of the FLIR system analysis showed that subsequent additions to the RPV CDB had a minimal impact on additional maintenance work'oad requirements for the total system. The FLIR MPS maintenance requirements were minor considering the fact that: (1) no direct support maintenance would be accomplished, (2) organizational level maintenance required only minor servicing tasks for preventive maintenance and only inspection and remove and replace tasks for correct ive maintenance, and (3) the designated **RPV** maintainer (MOS 13TP9) was capable of handling the additional workload associated with the FLIR MPS due to its similarity to TVMPS repair requirements.

#### SECTION 3 - DETERMINE MANPOWER RESOURCE REQUIREMENTS

#### 3.1 STUDY CONSIDERATIONS/ASSUMPTIONS

#### 3.1.1 Task and Failure Rate Data

Analysis of the FLIR/24 hour versus the daylight-TV/12 hour reliability, maintainability and scenario data indicated equipment failure rates and operator/maintainer tasks used to compute workload and manpower requirements were very similar. This permitted use of the existing Interactive Manpower Aggregation and Estimation System (IMAGES) data base, with modifications, to account for any changed requirements.

As noted in the engineering analysis, review of current RPV LSAR's disclosed no significant changes in failure rates for existing equipments and associated human tasks. Failure rates and tasks directly attributed to the FLIR package were therefore added to make the data base truly reflective of the FLIR/24 hour requirements. These task and failure rate additions included:

- o Inspection and service of the FLIR package at the section level;
- o Potential for reconfiguration of on-hand mission payloads and AVs to marry operational units that would satisfy mission requirements;
- o Positional MOS/skill level changes in the RPV Section.

Subsequent to the DRC daylight-TV/12 hour RPV report, "Application of the HARDMAN Methodology to the Army Remotely Piloted Vehicle" dated 8 April 1983, the Army Troop Support and Aviation Material Readiness Command (TSARCOM) published a Final Qualitative and Quantitative Personnel Requirements Information (FQQPRI) document (Ref. 3) on 27 May 1983. This document made four major changes effecting RPV section workload tasks which were incorporated into the new study.

The first two changes resulted in removal of organizational level maintenance workload within the purview of MOS 31V (Tactical Communications System Operator/Mechanic) and 63B (Light Wheeled Vehicle Mechanic) from the RPV section. The unit supporting an RPV section, the Target Acquisition Battery (TAB), was assigned responsibility for accomplishment of these maintenance tasks. Workload associated with these tasks were retained in a separate IMAGES data file and is available for determining the impact of RPV section operations of the supporting unit.

Thirdly, the FQQPRI added a requirement for MOS 52D (Power Generator Equipment Repairer) to the RPV section for operation and maintenance of the electrical power generating systems. Associated with this change is the requirement for a maximum of 90 seconds lost-power time for the ground control station (GCS). Review of the GCS power generating and distribution system equipments revealed a lack of automatic monitoring and switching controls. Therefore, to meet the 90 second power interrupt requirement, it will require both 30 KW generators to be in continuous operation (one online, one in "hot" stand-by) with an operator in constant attendance to shift load in the event the online

generator fails. This operator requirement was added to the section workload tasks.

Finally, the fourth change was reflective of increased staffing requirements brought about by adding the FLIR mission payload capability and expanding the section to accommodate 24 hour operation (see Table 3.1-1). These requirements added a 13T40 position to the section and realigned task responsibilities. Task responsibilities affecting the previous daylight-TV/12 hour scenario were modified to reflect these changes and are shown in Appendix B.

#### 3.1.2 RPV IMAGES Model.

Review of DRC's IMAGES RPV modeling equations developed for the daylight TV/12 hour scenario indicated the equations were still applicable for use with the FLIR/24 hour requirements. Equations necessary to account for multiple mission payloads and their respective maintenance requirements were added.

#### 3.1.3 FLIR/24 Hour Scenario Changes

Addition of the FLIR package added only one new variable to the scenario factors. It is now necessary to show the ratio of specific types of mission payload flights to total RPV flights (e.g., 40% daylight TV and 60% FLIR flights).

Specific scenario changes are shown in Table 3.1-2 while composite scenario values used are listed in Appendix A. It

Table 3.1-1

RPV Section MOS, Skill Levels and Paygrades

MOS	Paygrade	Skill Level/ASI	<u>Title</u>
211B	WO	-	RPV Technician (Section Commander)
13T	E-7	4	RPV Section Chief
13T	E-6	3	RPV Team Leader
13T	E-5	2	Launch and Recovery Team Chief
13Т	E-5	2	Senior Air Vehicle Operator
13T	E-5	2/P9	RPV Mechanic
13T	E-4	1	Senior Mission Payload Operator
13T	E-4	1/P9	RPV Mechanic
13T	E-4	1	Air Vehicle Operator
13T	E-3	1	Mission Payload Operator
13T	E-4/E-3/E-2	1	RPV Crewman
52D	E-4/E2	•	Power Generator Equipment Repairer

# Table 3.1-2 FLIR/24 Hour Scenario Changes

- The section flys an average of 5 missions/day; 60% of the flights are FLIR missions; 40% are Daylight TV.
- The average FLIR/Daylight TV weather degradation factor for the sustained operation conditions is reduced to 20% from 50% (Daylight TV only). This is due to increased capability of FLIR to see through haze, smoke, darkness, and other Daylight TV degrading factors.
- Both 30KW generators will operate the entire time a section is in place with only one under load.
- Due to bad lighting conditions, all work performed outside the Maintenance and Ground Control shelters after dark has an added 10% productivity factor included in manhours required to accomplish these tasks.
- AV loss rates per flight used in the 12 hour scenario apply to the 24 hour scenario. This results in a daily battle loss rate of 0.83 aircraft, and a miscellaneous loss rate of 0.33 for all other causes for five (5) flights per day in the sustained operating scenario.
- The section commander's truck will be used on-site for the equivalent of 3 round trips per day.
- All GCS flight supporting equipment operates the entire time an RPV section is inplace.

is noted that in spite of increased AV usage experienced with the FLIR/24 hour scenario, no significant increase in resupply task frequencies occurred. This is based on DRC's assumption that no inordinate delays occur in the accomplishment of resupply tasks and AV resupply will occur every 48 hours or whenever AV availability approaches 40% (two AVs). Projected total loss rates for the sustained FLIR/24 hour scenario are 1.16 AVs per day or 2.32 in 48 hours. This would alter section AV availability to an average of 53.6% before scheduled AV resupply would normally occur.

#### 3.1.4 Contingency Manning

In the FLIR/24 hour scenario, a need arises to insure sufficient around-the-clock manning is available to support AV launch, recovery and mission flight operations for short notice or no-notice missions. This requires that the positions noted in Table 3.1-3 be continuously manned on a rotating shift basis. Although positions satisfying these operational requirements are available to perform useful work, there will be times when personnel are being used for no other purpose than to be fully ready in the event a mission may be required during the period of their shift. Therefore, this contingency operational manning could lead to some positions not being filled to workload capacity.

Table 3.1-3 RPV Section FLIR/24 Hour Operational Manning Positions

Operator	Position Title	Number Per Shift
Mission (	Commander	1
Mission 1	Payload Operator	ì
Air Vehic	cle Operator	1
Launch/Re	ecovery Team Leader	1
Launch/Re	ecovery Team Member	4
0	AVH/LS Crane Operator	
0	RPV Crewman	
0	RPV Crewman	
O	RS Operator (required due	
	to simultaneous deployment	
	of RS for each launch)	
30KW Gene	erator Operator	1

# 3.2 RPV WORKLOAD DEVELOPMENT

### 3.2.1 RPV Section Workload

DRC's IMAGES model was used to compute workload for the RPV FLIR/24 hour scenario. Scenario and task values (Appendices A and B, respectively) were revised from the 12 hour analysis case to show specific value changes applicable to the FLIR/24 hour scenario. These new sets of operational values were then used to compute the RPV section workloads as shown in Figure 3.2-1 and Table 3.2-1.

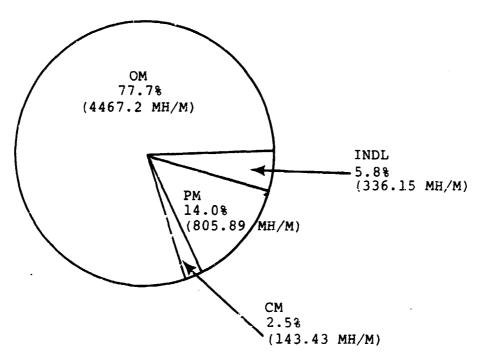
Workload was aggregated by specific MOS skill level and ASI to efficiently load the identified positions shown in the Workload Position sections of Table 3.2-2. It is noted that each position shown is loaded to no more than 90% of its 365 hours/month capacity. This loading accounts for personal productivity associated with tasks that are not bound by fixed time limits (e.g. extracting an AV after netting requires no specific length of time to complete whereas being mission payload operator for a 3 hour flight takes 3 hours and is time bound). Section maintenance workload growth in moving to the 24 hour operating period was significantly reduced by shifting workload associated with the 31V and 63B MOS out of the section and assigning its responsibility to the unit supporting the RPV section. workload and positions associated with these support requirements are shown in Table 3.2-3.

# 3.2.2 RPV Section Operator Requirements

The change from 12 hour to 24 hour operations required further analysis of the operator positions identified in Table 3.1-1. For the 12 hour scenario the operator

Figure 3.2-1 RPV Section Workload Distribution

# REFERENCE - O&O SCENARIO



# REFERENCE - SUSTAINED

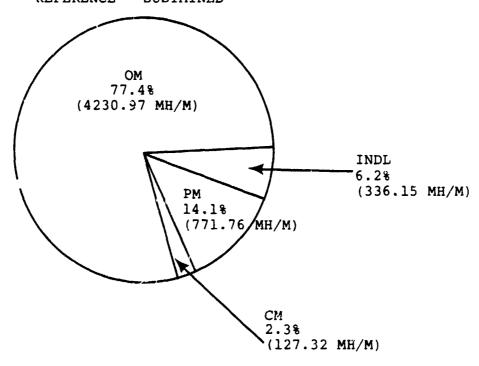
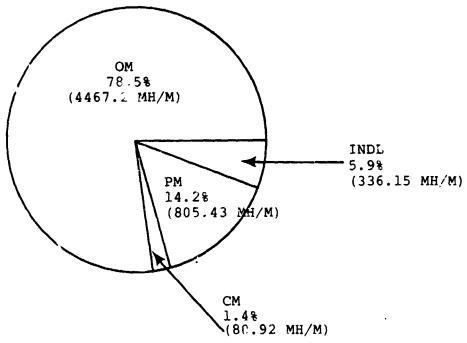


Figure 3.2-1 (Continued)

# BASELINE - O&O SCENARIO



BASELINE - SUSTAINED

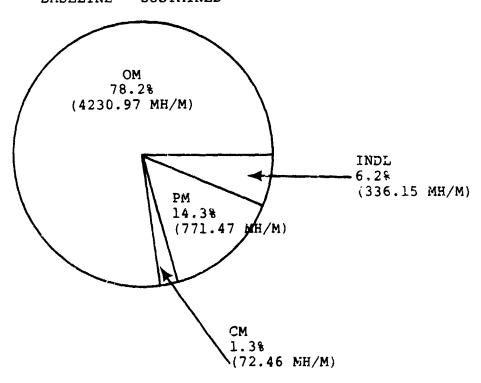


Table 3.2-1

RPV Section Workload Distribution (MH/Month)

MOS/SI/PAY		NORKLOAD CATEGORY	REI O&O	FERENCE SUSTAINED	BAS O&O	ELINE SUSTAINED
211B		CM PM CM INLD	- - - 42.35	42.35	- - - 42.35	- - - 42.35
13740 1	E7	OM PM CM INDL	59.90 - - 64.36	59.90 - - 54.36	59.90 - - 64.36	59.90 - - 64.36
13T30	Eő	OM PM CM INDL	656.52	606.35 - - -	65.52 - - -	60.35
13T20	F5	OM PM CM INDL	34.23 2.73 0.20 4.81	24.86 2.73 17 32	34.23 2.73 0.20 4.62	24.86 2.73 3.17 4.82
13T20F9	<b>E</b> 5	OM PM CM INDL	33.40 39.95 2.16	33.66 26.12 2.16	- 32.52 19.30 2.16	25.24 15.96 2.16
13T10	E4	OM PM CM INDL	538.66 166.24 14.29 2.16	493.38 165.62 13.34 2.16	538.56 166.38 6.10 2.16	493.38 165.83 5.61 2.16
13T10P9	E4	OM PM CM INDL	47.48 136.18 67.36	47.58 123.26 60.69	47.57 136.46 38.83	47.57 123.64 35.55
52D10	E4	OM PM CM INDL	340.57 34.17 13.30	340.57 34.17 12.42	340.57 34.17 13.30	340.57 34.17 12.42

Table 3.2-1 (Continued)

MOS/SI/PAYGRADE	WORKLOAD CATEGORY	REI O&O	FERENCE SUSTAINED	BAS O&O	SELINE SUSTAINED
13T10 E3	OM PM CM INDL	105.86 60.23 1.83 18.79	968.38 48.86 1.41 18.79	1058.86 60.23 0.87 18.79	968.38 48.86 0.73 18.79
13T10 E2	OM PM INDL	152.38 38.30 6.50	145.36 36.36 5.63	152.38 38.30 2.32	145.36 36.36 2.02
52D10 E2	indr Cw bw Ow	349.97 29.24 -	349.97 29.24 - -	349.97 29.24 -	349.97 29.24 -
XXXX E4	OM PM CM INDL	6.36 - - -	6.36 - - -	6.36	6.36 - - -
XXXX E3	OM PM CM INDL	31.82	31.82	31.82	31.82
XXXX E2	OM PM CM INDL	1190.35 305.40 201.51	1156.44 305.40 - 201.51	1156.44 305.40 201.51	1156.44 305.40 - 201.51
TOTAL	OM PM CM INDL	4467.20 805.89 143.43 336.15	771.76 127.32	4467.20 805.43 80.92 336.15	771.47 72.46
GRAND TOTAL		5752.67	5466.20	5689.70	5411.05
MAXIMUM NUMBER OF WORKLOAD DRIVEN : * (90% loaded to for personal p	POSITIONS account	18*	17*	18*	17*

Table 3.2-2. RPV Section Manpower Requirements Summary by Crew Position for 24 Hour - FLIR Operations.

			WO PC	WORKLOAD POSITIONS		THREE		3 SHIFT GCS <sup>1</sup> , 2 SHIFT
CREW POSITION	MOS/SI ASI	PAYGRADE	080	SUSTAINED	FQQPRI	SHIFTS (3 SHIFT)	3 SHIFT GCS <sup>1</sup> (2 OUTSIDE/3 INSIDE)	OUTSIDE, SHARED POSITION (3/2 SHIFT)
Mission Commander	211B0 13T40 13T30	жо Е7 Е6		н п п			1 1 1	1 1
Air Vehicle Operator	13T20 13T10 13T10	ខ 4 4 4						1 1 1
Mission Payload Operator	13T10 13T10 13T10	គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ គ	ннн	ппп	1 (E5) 1 1	1 4 1	1 1 1	<pre>1 + 4 hr. L/R Team 1 + 4 hr. L/R Team 1 + 4 hi. L/R Team</pre>
Generator Operator	52D10 52D10 52D10	E2 E2	1 12 0	$\begin{matrix} 1 \\ 1 \\ 0 \end{matrix}$	1 0 0	1 1 1	1 1 0	1 1 0
Launch/ Recovery Team Leader	13T30 13T20 13T20 P9	9 9 5 3 5 3	ннн	1 1			l l (see L/R Team)	l 1 (see L/R Team)
Launch/ Recovery Team #1	13T10 P9 13T10 13T10 13T10	БВ 3 В 2 В 2		חוסו	וו		1 1 1 1	1 1 1
Launch Recovery Team #2	13T10 13T10 13T10 13T10	E4 E3 E3	0 0 00	0 0	1 (13T10 P9) 0 0 0	) 1 1 1	1 (13T20 P9) 1 1	1 (13T20 P9) *GCS Operators Shared Position 1
Launch Recovery Team #3	13T10 13T10 13T10 13T10	E4 E3 E2	0	0 0 0 0	0000	нннн	0 0 0	0000
TOTAL			18	17	18	27	213	203

# Table 3.2-2 (Continued)

- There is no difference in operator shift position requirements between 040 and sustained scenarios as they both cover 24 hour periods. (T) NOTE:
- Decision not to include a third 52D position assumes the 13T10 is capable of manning the generator operation station part time with a minimum of on-the-job-training (OJT). (3)
- Allows for availability of vehicle drivers to make resupply, site survey and RPV briefing trips offsite. (3)

Table 3.2-3. Displaced RPV Organizational Workload

	Workload	(MMH/MO)	Posit	ions*
MOS	Baseline	Reference	Baseline	Reference
O&O Scenario				
3 1 V	11,07	16.25	1	1
63B	225.63	225.63	1	1
Sustained Scenar	io			
31V	9.88	15.18	1	1
63B	210.30	<b>725.29</b>	1	1

<sup>\*</sup> Workload capacity of each porting unit organizational position is assumed to be the same as for the RPV section.

positions required only one shift; further, those positions requiring intense concentration (GCS positions) could be rotated with less intense duties of the launch/recovery (L/R) team. This operating procedure also permits sufficient positions to make resupply runs and still launch, operate and recover the AV. Permitting section members an uninterrupted 7 hour period for sleep each day was easily accommodated in the 12 hour off cycle even when resupply and relocation might have occurred in this timeframe.

The 24 hour scenario presents a completely different problem than that of the 12 hour. More specific delineation of responsibilities and accounting for rest periods and offsite briefing/resupply requirements is required. In the 24 hour scenario, the five flights proposed for each day can be assigned at any time. To be prepared for this contingency, all operator positions listed in Table 3.2-1 must be manned 24 hours a day. Workload not specifically associated with an operator position can be performed by that individual during the periods when they are in a standby mode. exception to this method of operation would be for workload which causes personnel to leave the site (e.g., resupply runs). In these cases, an individual not in the duty shift must be used. Table 3.2-2, Operator Positions, show three possible shift configurations to man the section for 24 hour operations.

While a detailed human factors analysis of RPV section positions was not within the scope of this study, RPV section operator positions were subjected to a qualitative human factors review for the degree of intense concentration required and the duration this attention must be applied. It was concluded that the Mission Commander (MC), Mission

Payload Operator (MPO) and Air Vehicle Operator (AVO) positions required intense concentration on cathode ray tube (CRT) displays for five hours out of every 8 hour shift For these types of operational conditions, the Navy, as an example, restricts the operator shift time to two-4 hour periods a day (a three shift rotation). Applying this concept to the entire RPV section results in 27 operator positions per section. This number of operators would be more than sufficient to accomplish all workload including off-site trips but represents very inefficient utilization of available workload capacity. Although GCS shifts were optimized this operator with configuration, an average section position is loaded to only 60% of its capacity.

All other operator positions not in the GCS were similarly analyzed and evaluated as requiring low to moderate levels of concentration for short periods of time with exception of the 30KW generator operator. This position required low levels of concentration for extended periods. Fatigue factors were also qualitatively evaluated for non-GCS operators. It was concluded that there is no reasonably expected workload that will over fatigue a rested, healthy operator in a 12 hour shift routine. This then gave rise to the possibility of a split shift situation for RPV section operators such as shown in Table 3.2-2. This manning scheme results in 21 operators being required and is much more simple three shift efficient than the condition. Additionally, this contingency manning results in an average section position being loaded to 77% of capacity.

Continued analysis of RPV section operator requirements indicated that part of the operators in the GCS could also

be used as L/R team members when not on duty in the GCS. For this reason, it is suggested that the 4 hours that each of three GCS operators has available for useful work after standing shift in the GCS be combined to satisfy one operator position in the L/R team. This reduces total operator requirement to 20 (Table 3.2-1) and still provides sufficient personnel not in the duty shift, but still available for duty, to make necessary off site trips.

A 20 man RPV section is therefore considered the optimum manpower blend to satisfy workload and operator driven requirements. This brings the average RPV section position to 81% of workload capacity. Army RPV manpower requirements resulting from these analyses are shown in Tables 3.2-4 and 3.2-5.

### 3.2.3 Direct Support (DS) Level Maintenance Workload

DS level workload was analyzed in a similar manner to that used for the daylight-TV/12 hour scenario. The only notable change is in the requirements for MOS 63W (Wheeled Vehicle Repairer). This change has been brought about by significantly increasing the number of launch, recovery and air vehicle handler operations. Increasing planned flights and increased launches due to reduction of weather cancellations resulted in a 267% rise in activity over the previous study. No appreciable FLIR mission payload subsystem (FMPS) workload was added at DS level because the fault isolation and corrective maintenance is to be accomplished at the GS and depot levels.

Table 3.2-4
Manpower Requirements Reference and Baseline Systems
Sustained Concept\*

		æ	RPV SECTION	z	121	RPV PLATOON	z		ARMY TOTAL		
MOS AS1	ASI PAYGRADE	WORKLOAD 3 SHIFT	3 SHIFT	3/2 SHIFT SHARED	WORKLOAD	3 SHIFT	3/2 SHIFT SHARED	WORKLOAD	3 SHIFT	3/2 SHIFT SHARED	
211B0	OM	7	7	1	4	4	4	26	56	99	
13T40	E7	1	7	ч	4	4	4	99	99	99	
13T30	E6	7	7	7	<b>60</b>	80	ω	112	112	112	
13T20	ES	7	7	7	<b>6</b> 0	80	ω	112	112	112	
13110	H 4	m	'n	м	12	20	12	168	280	168	
13T10	Е3	m	60	ស	12	32	20	168	448	280	
13r10	E2	1	٣	8	4	12	εο	99	168	112	
13T20P9	E5	1	1	ч	4	4	4	26	26	. 95	
13T10P9	Э <b>4</b>	1	1	1	4	4	4	26	26	. 56	
52010	E 4	1	Т	ı	4	4	4	99	26	26	
52D10	E2	1 (1)	7	1 (1)	₹	<b>∞</b>	4	99	112	56	
		17	27	20	89	108	80	952	1512	1120	

\*RPV Platoon Headquarters Requirements are not included in this table.

Note: (1) Assumes 13T10 is capable of manning the generator operator station with minimum on-the-job training (OJT).

Table 3.2-5

Manpower Requirements Reference and Baseline Systems

O&O Concept\*

		<b>E</b>	RPV SECTION	z		RPV PLATOON	2	7	ARMY TOTAL	
MOS ASI	ASI PAYGRADE	WORKLOAD 3 SHIFT	3 SHIFT	3/2 SHIFT SHARED	WORKLOAD	3 SHIFT	3/2 SHIFT SHARED	WORKLOAD	3 SHIFT	3/2 SHIFT SHARED
211B0	OM.	1	1	7	4	4	4	99	99	56
13T40	E7	1	-	7	₹	4	4	56	56	99
13T30	<b>E6</b>	7	7	7	œ	<b>&amp;</b>	€	112	112	112
13T20	85	7	7	7	80	σ.	60	168	112	112
13T10	E4	m	S	м	12	20	12	168	280	168
13T10	Е3	4	89	ĸ	16	32	20	224	448	280
13110	E2	7	æ	7	₹	12	æ	26	168	112
13r20P9	ខ្ម	7	7	7	<b></b>	₹	4	26	56	26
13T10P9	<b>♣</b>	-	-	1	4	4	4	99	56	56
52D10	М 4	1	1	1	4	ঝ	4	99	26	26
52D10	E2	1 (1)	7	1(1)	4	œ	4	56	112	2 <b>9</b>
		18	27	20	72	108	80	1008	1512	1120

40

\*RPV Platoon Headquarters Requirements are not included in this table.

Note: (1) Assumes 13T10 is capable of manning the generator operator station with minimum on-the-job-training (OJT).

DS workload and manpower requirements are shown in Tables 3.2-6 and 3.2-7.

### 3.3 MANPOWER ANALYSIS RESULTS

### 3.3.1 FLIR RPV Section

From this analysis, it can be seen that for the 24 hour scenario it is the operator shift requirements rather than workload which is the controlling factor for manpower requirements. Making maximum use of all manpower assets, including maintainers to fill operator requirements, the RPV section will need 20 positions to function properly. These personnel, when in a stand-by mode while on shift duty, would be expected to accomplish other useful section workload such as air vehicle preventive and corrective equipment maintenance. Because there are now more positions than required by absolute workload, the inclusion of additional flights and/or section displacements can be considered without impacting manpower requirements.

Each additional flight adds 15.8 manhours of workload to the section total and each displacement cycle adds 46.8 manhours. This would mean, for example, the FLIR scenario could include up to two displacement cycles per day without adding any workload positions in excess of those driven by operator requirements. This is as a result of contingency manning providing additional workload capacity. Furthermore, two moves per day would not impact upon the operational requirement to conduct five flights per day.

Table 3.2-6
Direct Support Maintenance Manpower Reference System 24 Hour - FLIR Operations

MOS	PAYGRADE	MONTHIAY O&O	MANHOURS SUSTAINED	RPV O&O	PLATOON SUSTAINED	ARI O&O	MY TOTAL SUSTAINED
26B	E4	10.98	10.45	1	1	14	14
26L	E5*	56.68	45.36	1	1	14	14
26 <b>T</b>	E4	82.29	66.16	1	1	14	14
31E	E4	133.81	116.77	1	1	14	14
31J	E4	60.73	60.73	1.	1	14	14
31 <b>s</b>	E4	26.38	26.38	1	1	14	14
34Y	E5*	46.78	39.94	1	1	14	14
35E	E5*	10.76	7.57	1	1	14	14
35H	E5*	35.90	35.90	1	1	14	14
36H	E4	14.59	14.59	1	1	14	14
41B	E4	19.41	19.41	1	1	14	14
41C	E4	0.46	0.46	1	1	14	14
43M	E4	1.39	1.39	1	1	14	14
44B	E5*	20.93	19.03	1	1	14	14
45B	E4	1.38	1.38	1	1	14	14
45G	E4	105.83	74.91	1	1	14	14
52C	E5*	53.93	53.21	1	1	14	14
52D	E4	91.02	80.66	1	1	14	14
63G	E5*	189.22	156.93	1	1	14	14
63J	E4	1.34	0.95	1	1	14	14
63W	E3	416.00	416.00	2	2	28	28
63W	E5*	180.60	101.23	1	1	14	14
TOTAL		1560.41	1349.41	23	23	322	322

<sup>\*</sup>Includes workload from a lower skill level within the same MOS.

Table 3.2-7

Direct Support Maintenance Manpower Baseline System
24 Hour - FLIR Operations

		MONTHI	Y MANHOURS	RPV	PLATOON	ARM	Y TOTAL
MOS	PAYGRADE	0&0	SUSTAINED	080	SUSTAINED	0:30	SUSTAINED
26B	E4	.90	0.72	1	1	14	14
26L	E5	.20	0.17	1	1	14	14
31E	<b>E4</b>	81.19	76.23	1	1	14	14
31J	E4	12.82	12.82	1	1	14	14
31S	E4	26.38	26.38	1	1	14	14
34Y	E5*	7.54	6.39	1	1	14	14
35E	E5	1.30	0.96	1	1	14	14
35H	E5*	35.90	35.90	1	1	14	14
36H	E4	14.59	14.59	1	1	14	14
41B	E4	19.41	19.41	1	1	14	14
41C	<b>E4</b>	0.46	0.46	1	1	14	14
43M	<b>E4</b>	8.32	8.32	1	1	14	14
44B	E5*	22.22	19.97	1	1	14	14
45B	E4	1.38	1.38	1	1	14	14
52C	E5*	65.69	64.97	1	1	14	14
52D	E4*	75.42	69.66	1	1	14	14
63G	E5*	72.20	62.62	1	1	14	14
63J	E4	0.96	0.68	1	1	14	14
63W	E3	208.00	208.00	1	1	14	14
63W*	<b>E</b> 5	105.42	64.32	1	1	14	14
TOTAL		760.30	693.95	20	20	280	280

<sup>\*</sup>Includes workload from a lower skill level within the same MOS.

A review of Table 3.3-1 shows the preponderance of section workload is associated with GCS operators. The second ranking workload high driver (generator operator) could be eliminated by adding an appropriate switchboard or switching capability in the power distribution design. These additions would permit parallel operation of the two 3(KW generators, automatic disconnect of a failing generator, and alarm presentation in the GCS to notify operators of a generator failure.

Not shown as a high driver, but contributing two positions to the 20 man RPV section, is the imposed requirement to deploy the recovery system for each launch. If this requirement were removed and the generator operator replaced by a switchboard capability, the RPV section could potentially be reduced to 16 positions (remove one 52D10 and three 13T10s). This would coincide closely with the expected number of workload-driven positions for that situation.

The shifting of MOS 31V and 63B tasks to the supporting unit has reduced section workload by the equivalent of one position. However, it would impact by adding workload to the supporting unit organization by adding workload and possibly drive additional position requirements there. This depends upon a 31V MOS being present at the supporting unit and having the capacity to absorb the added workload. The added 63B workload will justify adding a new position to the supporting units organizational maintenance allowance.

# 3.3.2 FLIR RPV Direct Support Maintainers

As was the case for the 12 hour scenario, the 24 hour scenario normally drives DS positions with workload that

Table 3.3-1 Workload High Drivers (MH/Month)

Sustained	AVOPS Control	Generator	Site Displacement	Resupply	Pers Supervision*	Non-AV Briefs
	1254.24	Operator 678.72	569.98	125.50	80.07	15.15
Baseline 0&0	AVOPS Control	Generator Operator 678.72	Site Displacement 569.98	Resupply 125.50	Pers Supervision* 1 80.07	Non-AV Briefs
ce	AVOPS Control	Generator	Site Displacement	Resupply	Pers Supervision*	Non-AV Briefs
Sustained	1254.24	Operator 678.72	569.98	125.50	80.07	15.15
Reference	AVOPS Control	Generator	Site Displacement	Resupply	Pers Supervision*	Non-AV Briefs
040	1363.32	Operator 678.72	569.98	125.50	80.07	15.15
Ranking	1	2	ю		2	E
Workload Category	<b>W</b> O			JONI 45		

NOTE: \*Included only 90/E7 personnel administration/counciling workload.

Table 3.3-1 (Continued)
Workload High Drivers (MH/Month)

Sustained	Wheeled*	Air **	GCS ***	GCS ***	Air	Wheeled*
	Vehicles 331.68	Vehicle 116.39	97.91	25.72	Vehicle 24.78	Vehicles 14.4;
Baseline	Wheeled *	A₁: **	GCS ***	GCS ***	Air	Wheeled *
O&O	Vehicles 331.68	Vehicle 183.01	97.91	29.96	Vehicle 26.88	Vehicles 15.62
Sustained	Wheeled*	Air **	GCS ***	Air	GCS ***	Wheeled *
	Vehicles 331.68	Vehicle 116.39	97.91	Vehicle 55.20	41.52	Vehicles 18.05
Reference	Wheeled *	Air **	GCS ***	Air	GCS ***	Wheeled *
0&0	Vehicles 331.68	Vehicle 183.01	97.91	Vehicle 59.49	49.97	Vehicles 19.80
Ranking	1	2	æ	1	2	m
Category	М			<b>∑</b> O 46		

46

\*Wheeled vehicles PM/CM does not include maintenance for carried RPV subsystems/equipments. NOTE:

\*\*Approximately 75% of this PM is associated with AV prelaunch preparation and is normally performed outside the maintenance shelter.

\*\*\*Includes associated Ground Support Equipments.

does not completely fill its capacity. In these cases, if the required MOS exists in the proper DS maintenance organization/unit, it would be worthwhile to investigate existing assigned workload to determine if it could absorb RPV-driven workload without adding new positions. The notable exception to this case is the 63W, where enough workload at different skill levels exists to warrant adding up to three DS positions. Workload for the 63W increased because of vehicle usage associated with the significant increase (2.56 times) in numbers of AV launches and recoveries. This impacted on the maintenance requirements for launch/recovery and air vehicle handling vehicles.

For the 24 hour scenario, one additional site displacement increases DS workload by about 0.4 hours (1.6 hours for four sections) for the baseline system and 0.9 hours (3.6 per platoon) for the reference system; most of this workload is associated with the wheeled vehicle maintainers. Further, each AV launch/recovery cycle results in adding about the same number of hours to baseline/reference system DS workload, respectively; 0.5 and 1.0 hours per section supported. Significant increases in DS workload will result from increasing the number of section displacement cycles to two per day or number of launches to six per day.

### SECTION 4 - DETERMINE TRAINING RESOURCE REQUIREMENTS

### 4.1 STUDY CONSIDERATIONS

This section describes the results of the RPV Training Resource Requirements Analysis (TRRA) and outlines the general procedures that were employed. This analysis is an extension of the initial Remotely Piloted Vehicle TRRA. A more detailed discussion of the procedures employed may be found in this initial report and in the Army Research Institute's (ARI) Technical Report on the application of the HARDMAN methodology to the Division Support Weapon System. The overall purpose and scope of the RPV analysis are discussed in Section 1 of this report. These objectives were further refined into the following TRRA objectives:

- O Update the baseline training pipeline which will support section manning and operation by:
  - a) Updating the existing training pipeline and course analysis to incorporate FQQPRI skill level changes.
  - b) Updating the existing maintenance MOS assignments and courses to reflect FQQPRI MOS changes.
  - c) Updating the existing operation and maintenance courses to include the training requirements for the Forward Looking Infrared (FLIR) mission payload subsystem (FMPS).

- d) Updating the existing operator courses to include newly-received training information that is more comparable to the RPV system.
- e) Updating the training resource requirements analysis to reflect changes in the student loads created by the 24 hour/FLIR operational scenario.
- o Identify the differences in training resource requirements between the existing 12 hour daylight operational scenario and the 24 hour/FLIR operational scenario by:
  - a) Identifying courses impacted.
  - b) Identifying changes in course content and length.
  - c) Identifying changes in instructor requirements.

All of the training assumptions made in the initial TRRA remained the same, except for one which was modified to incorporate changes in the FQQPRI that reflect system maintenance responsibility for the Warrant Officer.

o The RPV Warrant Officer will have responsibility for the supervision of the tactical employment of the RPV system and will also be a qualified maintenance technician.

### 4.2 TRAINING RESOURCE REQUIREMENTS ANALYSIS (TRRA)

All of the major steps in a general Training Resource Requirements Analysis (TRRA) were conducted for the update of the RPV study. Training data that had been requested for the previous study and not received, was subsequently received. The analysis and inclusion of this new data was accomplished. The content and quality of this new data has improved the estimation of the training requirements for the RPV operators. Many of the changes found in the tables and figures that follow are due to these changes in the updating of the available data.

Table 4.2-1 shows the RPV MOS's selected for the updated reference and baseline systems. One new MOS was added due to a change in the FQQPRI. This new MOS is a Weapons Support Radar Repairer (26B) at skill levels 1 and 2 and Combat Area Surveillance Radar Repairer (26C) at skill level 3. MOS 31V (Tactical Communications Systems Operator/Mechanic) and MOS 63B (Light Wheel Vehicle/Power Generation Mechanic) were deleted because they perform organizational maintenance on RPV equipment outside of the RPV section. The assignments of these MOSs to their respective equipment are found in Appendix C.

Once the MOS had been determined, the existing resident courses of instruction associated with the MOS were identified (Ref. 6). Table 4.2-2 summarizes the RPV technical courses of instruction. The entry level course for MOS 26B (104-26B19) was the only new course added. The courses required by MOSS 31V and 63B were deleted.

Table 4.2-1
Summary of RPV MOS and ASI

MOS	CMF	Skill Level	Title (with abbreviation)
13T	13	1-4	Remotely Piloted Vehicle Crewman (RPV Crewman)
13TP9	13	1-2	Remotely Piloted Vehicle Mechanic (RPV Mech)
26B	29	1-2	Weapons Support Radar Repairer (Weapons Spt Rdr Rep)
26C	29	3	Combat Area Surveillance Radar Repairer (Cbt Area Svl Rdr Rep)
26L	29	1-3	Tactical Microwave System Repairer (Tac Mwave Sys Rep)
2 <b>6T</b>	84	1-3	Radio/Television Systems Specialist (Rdo/TV Sys Sp)
31E	29	1-3	Field Radio Repairer (*)
31J	29	• 1-3	Teletypewriter Repairer (Teletypewriter Rep)
31 <b>S</b>	29	1-3	Field General COMSEC Repairer (Field Gen COMSEC Rep)
34Y	74	1-3	Field Artillery Computer Repairer (FA Computer Rep)
35E	29	1-3	Special Electronics Devices Repairer (Sp Elec Devices Rep)
35H	29	1-3	Calibration Specialist (*)
36Н	29	1-3	Dial/Manual Central Office Regairer (Dial/Man Cen Ofc Rep)
41B	81	1-2	Topographic Instrument Repair Specialist (Topo Inst Rep Sp)
41C	63	1-3	Fire Control Instrument Repairer (FC Instrument Rep)
4 3M	76	1-3	Fabric Repair Specialist (Fabric Repair Sp)

Table 4.2-1
Summary of RPV MOS and ASI (continued)

MOS	CMF	Skill <u>Level</u>	Title (with abbreviation)
44B	63	1-2	Metal Worker (*)
44E	63	3	Machinist (*)
45B	63	1-2	Small Arms Repairer (*)
45G	63	1-3	Fire Control Systems Repairer (FC Systems Rep)
45K	63	3	Tank Turret Repairer (*)
52C	63	1-3	Utilities Equipment Repairer (Utilities Equip Rep)
52D	63	1-3	Power Generation Equipment Repairer (Pwr Gen Equip Rep)
63G	63	1-2	Fuel and Electrical Systems Repairer (Fuel & Elec Sys Rep)
63H	63	3	Track Vehicle Repairer (Track Veh Rep)
63J	63	1-3	Quartermaster and Chemical Equipment Regirer (QM & Chem Equip Rep)
63W	63	1-2	Wheel Vehicle Repairer (Wveh Rep)
82D	81	3	Topographic Surveyor (*)
211BO	-	-	Remotely Piloted Vehicle Technician (RPV Tech)

<sup>\*</sup>Indicates no abbreviation

Table 4.2-2
Summary of RPV Technical Courses of Instruction

MOS	Skill Level 1	Skill Level 2	Skill Level 3
13T	XXX-13T10 XXX-13TP9	None	XXX-13T30
26B	104-26B10	None	None
26L	101-26L10	None	None
26 <b>T</b>	G3ABR30435	None	None
31E	101-31E10	None	None
31J	113-31J10	None	None
31S	160-31S10	None	None
3 <b>4</b> Y	041-34Y10	None	None
35E	198-35E10	198-35E20	None
35H	G3ABR3240-003	G3AZR32470-000	198-35H30
36H	622-36H10	None	None
41B	670-41B10	None	None
41C	670-41C10	None	None
43M	760-43M10	None	None
44B	704-44Bl0	None	702-44E30
45B	641-45B10	None	643-45K30
45G	113-45G10	None	None
52C	662-52C10	662-52C20	None
52D	662-52D10	662-52D20	None
63G	610-63G10	None	611-63H30
63J	690-63J10	None	690-63J30
63W	610-63W10	None	611-63H30

211B0 Warrant Officer Course: XX-211B

A revision of the proposed RPV-specific courses is shown in This proposed training course pipeline Figure 4.2-1. represents a possible plan for providing training and is based on the present career progression plans for the RPV section personnel. This training configuration was followed RPV operator estimating the and organizational maintenance training requirements. Added to this pipeline at paygrade E6 is a new course (Field Artillery Cannon NCO Advanced Course) to provide training for the RPV Section Chief and Platoon Sergeant. The addition of this new course is again due to changes in the FQQPRI.

At this point, the existing reference courses were reviewed and updated. First, the FQQPRI and FLIR MOS differences were identified. Next, the new training materials received for the study were reviewed and new comparable training was selected where appropriate. Some training in the Basic Technical Course (XXX-13T30) was taken from the new Field Artillery Cannon Fire Support Specialist Basic Noncommissioned Office Course (BNCOC) program of instruction (POI), and some training and course data in the RPV Warrant Officer Course (XX-211B) was taken from the new Target Acquisition Radar Technician Course (4C-211A) Program of Instruction (POI). Once the reference training courses were configured, the existing baseline training courses were modified to reflect the new FQQPRI MOS assignments and new training materials received. As shown in Table 4.2-3, a total of nine courses were developed or modified to reflect the reference equipment, then six of these courses were modified to reflect differences between the reference and baseline systems. Table 4.2-4 shows the affects of these differences on course length in man-days. Table 4.2-5 highlights the course topic and training time differences between the two

Figure 4.2-1. Proposed Training Course Pipeline

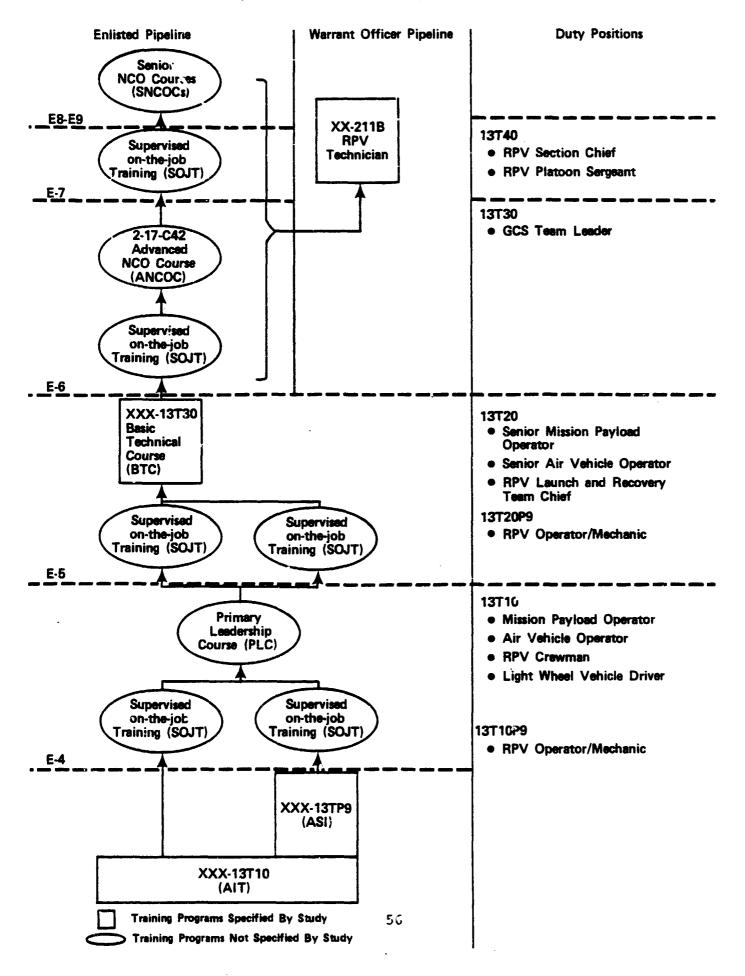


Table 4.2-3

New and Modified Courses by System

MOS	Course Number	Course Title	Reference	Baseline
13T	XXX-13T10 XXX-13TP9 XXX-13T30	RPV Crewman RPV Mech RPV BTC	1 2 3	10 11 3
26B	104-26B10	Weapons Spt Rdr Rep	4	4
26L	101-26L10	Tac Mwave Sys Rep	<b>5</b>	12
26T	G3ABR30435	Radio/TV Sys Rep	NC	
31E	101-31E10	Field Radio Repairer	6	13
31 <i>J</i>	113-31J10	Teletypewriter Rep	NC	NC
31S	160-31s10	Field Gen COMSEC Rep	NC	NC
34Y	041-34Y10	FA Computer Rep	7	NC
35E	198-35E10	Sp Elec Devices Rep	8	14
35н -	G3ABR3240-003	Calibration Specialist	e NC	NC
36H	622-36H10	Dial/Man Cen Ofc Rep	NC	NC -
41B	670-41B10	Topo Inst Rep Sp	NC	NC
41C	670-41C10	FC Instrument Rep	NC	NC
43M	760-43M10	Fabric Repair Sp	NC	NC
44B	704-44B10	Metal Worker	NC	NC
45B	641-45B10	Small Arms Repairer	NC	NC
45G	113-45G10	FC Systems Rep	NC	
52C	662-52C10	Utilities Equip Rep	NC	nc
52D	662-52D10	Pwr Gen Equip Rep	NC	NC
63€	610-63G10	Fuel and Elec Sys Rep	NC	NC
63J	690-63J10	QM & Chem Equip Rep	NC	NC
63W	610-63W10	Wveh Rep	NC	NC
211BO	XX-211B	RPV Tech	9	15

NC No change from existing course

<sup>--</sup> No course required for system

Table 4.2-4
RPV Course Impacts

MOS	Course	Reference	<u>Baseline</u>
13T	XXX-13T10 XXX-13TP9 XXX-13T30	New 55.8 M.D. New 63.1 M.C. New 21.1 M.D.	New 50.0 M.D. New 42.1 M.D. New 21.1 M.D.
26B	104-26B10	Added 1.5 M.D.	Added 1.5 M.D.
26L	101-26L10	Added 17.0 M.D.	Added 4.7 M.D.
26T	G3ABR20435	NC	
31E	101-31E10	Added 5.8 M.D.	Added 3.1 M.D.
31J	113-31J10	NC	NC
31S	160-31S10	NC	NC
34Y	041-34Y10	Added 17.4 M.D.	NC
35E	198-35E10 198-35E20	Added 18.5 M.D. NC	Added 3.6 M.D. NC
35H	G3ABR3240-003 G3AZR32470-000 198-35H30	NC NC NC	NC NC NC
36н	622-36H10	NC	NC
41B	670-41B10	NC	NC
41C	670-41C10	NC	NC
4 3 M	760-43M10	NC	NC
44B	704-44B10 702-44E30	NC NC	NC NC
45B	641-45B10 643-45K30	NC NC	NC NC
45G	113-45G10	NC	
52C	662-52C10 662-52C20	NC NC	NC NC
52D	662-52D10 662-52D20	NC NC	NC NC
63G	610-63G10 611-63H30	NC NC	NC NC
63J	690-63J10 690-63J30	NC NC	NC NC
6 3 W	610-63W10 611-63H30	NC NC	NC NC
211BO	XX-211B	New 91.8 M.D.	New 74.0 M.D.

NC No change from existing course M.D.

M.D. Man-days

<sup>--</sup> No course required for system

Table 4.2-5 Operator Course Topics and Training Times

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Previous Baseline New New Reference New Baseline Hours Change Note Annex Hours FLIR/24 HRA Hours FLIR/24 HRA	4.3 - A. 4.3 4.3	56.0 1 B. 76.6 76.0	55.4 .1 C. 55.3 55.3	41.5 4 D. 47.1 -	2.0 1 F. 8.2 8.2	9.2 - G. 9.2 9.2	73.8 1 H. 81.4 81.4	115.0 l,2 I. 119.0 Added 3.0 119.00 Added 3.0
revious Baseline ours Change Note	e.		4.	5.				
Topic	System Introduction, Tecinical Manual	Launch Vehicle, Recovery Vehicle, Handling Vehicle and System Emplace- ment Operations	Communications/ COMSEC Procedures	Plotting/Charting/ Map Reading Procedures	Navigation Display Panel Operation	Ground Data Terminal Control and Display Operations	Air Vehicle Command and Display Console Operations	Mission Payload Command and Display Console Operations (Includes
Previous Annex	ď	ů	ů	С 59	<u>.</u>	Ē.	ຜ່	π

Table 4.2-5 (Continued)

Course: XXX-13T10

New Baseline urs FLIR/24 HRA						Added 3.0
New Hours	28.9	1	1	ı	17.3	359.6
New Reference Hours FLIR/24 HRA						Added 3.0 399.6
Hours	28.9	i	1	ı	17.3	446.7
New	J.				<u>.</u>	
Previous Baseline Hours Change Note	1	3	3	(1)	: <b>1</b>	
Previou Hours	10.4	6.5	10.5	5.1	12.0	407.7
Topic	Organizational and Crew Maintenance	Weather (MET)	Survey	Digital Message Device Operation	Processor Start-Up and Data Entry	TOTALS
Previous	ï	J.	ж.	г.	ž	60

Change due to updating or ginal analysis. Notes:

Change due to addition of FLIR and 24 hour operational scenario.

Change due to reassignment in FQOPRI of topic area to higher skill level.

Change due to the planned automation of flight control.

Table 4.2-5 (Continued)

			-Course: XXX	XXX-13T30-	1		]		•
Previous	Topic	Prev. Hours	us Baseline Change Note	New	New	Reference FLIR/24 HRA	New Hours	Baseline FLIR/24 HR∆	
÷	Battalion Training Management System (BTMS) and Required Common Subjects	21.9	4	<b>.</b>	40.0		40.0		
В.	Weather (MET)	14.0	2	В.	29.0	Added 15.0	29.0	Added 15.0	
·.	Navigation	13.1	Н	ပ်	13.0		13.0		
D.	Inteliigence	10.9		D.	16.0		16.0		
<u>г</u>	Field Artillery and RPV Missions/Tactics	24.4	4	ព	36.0		36.0		
ĘЧ ,	Fire Support Duties	85.3	е		ı		ı		
	D jital Message Device Operation	1	æ	• Îz	5.1		5.1		
G	Target ID/Calls for Fire (Fire Support Tactics)	32.0	4		10.0		10.0		
H	Survey	10.9	ĸ		1		J		
ï	Convoy and Route Planning	2.5	m		ı		1		
J.	FA Communications Systems	1.7	4	н.	4.0		4.0		
×	IM-93/IM-174/PD	1.5	4		ı		1		
	Diagnostic and End of Course Exam	1	4	ı.	16.0		16.0		
	TOTALS	218.2			169.1	Added 15.0	169.1	Added 15.0	

# Table 4.2-5 (Continued)

Change due to updating original analysis. Notes:

- Change due to addition of FLIR and 24 hour operational scenario. 3. . 4
- Change due to reassignment in FQQPRI of topic area to higher skill level.
- Change due to use of MOS 13F30 (Field Artillery Cannon Fire Support Specialist Basic Noncommissioned Officer Course) POI for training estimation.

Table 4.2-5 (Continued)

---Course: XX-211B---

Pre	Previous Annex		Previous Hours C	Previous Baseline Hours Change Note	New	New Reference Hours FLIR/24 HRA	New Baseline Hours FLIR/24 HRA
	Α.	Leadership	22.1	i	Α.	22.1	22.1
	B.	Supply	28.6	1	B.	28.6	28.6
	ં	Maintenance Management	36.2	Ħ	<b>်</b>	32.0	32.0
	ъ.	Emergency Destruction	6.	ì	D.	6.	6.
	ស	Air Ground Navigation Review	26.9	1	<u>ы</u>	26.9	26.9
	<del>ري</del> ا •	Mission Planning	71.0	-	<u>г</u>	74.5	74.5
63	G	Target Identification and Calls for Fire	44.6	ı	ö	44.4	44.4
	H.	Field Artillery Communications	6.8	<b>.</b>	н.	9.3	9.3
	Ι.	NBC Operations	8.5	æ		•	1
		Survey	ı	2	ï	4.2	4.2
		Convoy Route Planning and Emplacement Planning	ı	7	ŗ.	15.8	15.8
		System Organizational Maintenance	1	2,4		475.5	332.9
		TOTALS	245	9.		734.2	591.6

Change due to updating original analysis. -Notes:

Change due to reassignment in FQQPRI of topic area to higher skill level. 2.

Change due to use of MOS 211A (Target Acquisition Radar Technician) POI for training estimation. 3.

Change due to new assignment of responsibility for system maintenance.

studies and between the reference and baseline systems in the new study. Brief notes are provided on the table to identify the sources of differences.

As shown in Table 4.2-6, significant differences in skill level and grade still exist in the new XXX-13T10 course. However, significant improvements were achieved in the XXX-13T30 course from the change in the FQQPRI increasing the RPV Section Chief to paygrade E7. Much of the necessary training that in the previous study had been shifted down to paygrade E6 (the former RPV Section Chief grade) from the Field Artillery Cannon NCO Advanced Course (0-B-C42) will now be received by the RPV Section Chief in this course. Still, a substantial portion of the other two baseline operator courses was derived from existing courses which are at a higher grade level. As pointed out in the previous these high skill requirements and low grade authorizations may mean that system performance requirements will not be achieved. While substantial improvements have now been made at the section chief level, further study and consideration should be given to resolving the differences and reassessing the proposed grade structure at the lower grades.

Table 4.2-7 shows the impacts of the various design configurations on maintenance training. changes occurred in either of the organizational maintenance training courses (XXX-13TP9), because the service and remove/replace tasks required for the FLIR mission payload system were judged to be similar to the tasks performed on the TV mission payload system assemblies. Direct support maintenance training for the navigation display unit was shifted from the 041-34Y10 course to the 104-26B10 course, while direct support

Table 4.2-6
Reference to Baseline Skill/Grade Differences

Course Topic/ Equipment	Reference Training Source with Grade	Baseline Course Assignment	RPV Grade
AV Recovery AN/PVS-5 Night Vision Goggles	Officer/WO Rotary Wing Aviator Course 2C-15A/2C-100B-B (Officer/WO)	XXX-13T10	El-E4
Plotting and Charting Aircraft Routes		0	0
Navigation Display Panel Operation	TACFIRE Operations Specialist 13C (BTC) (E6)	0	E4
Ground Data Terminal Control and Display Operations			
RPV Aerodynamics	OV-1 Instructor Pilot Course 2B-F5 (Officer/WO)	0	0
AV Command Display Console Operation	Officer/WO Rotary Wing Aviator Course 2C-15A/2C-100B-B (Officer/WO)	0	0
Target Identifi- cation	Image Interpreter PTC 242-96D20 (E5) Officer/WO Rotary Wing Aviator Course	0	0
Aerial Adjustment of Artillery	2C-15A/2C-100B-B (Officer/WO)	o .	0
Target Ranging Laser Designa- tion	Field Artillery Officer Basic 2-6-C20-13E (Officer)	0	0

o same as above

Table 4.2-6 (Continued)

Course Topic/ Equipment	Reference Training Source with Grade	Baseline Course Assignment	RPV Grade
Flight Planning/ Weather	Officer/WO Rotary Wing Aviator Course 2C-15A/2C-100B-B	XXX-13T30	E6
Flight Planning/ Navigation	(Officer/WO)	0	0
Digital Message Device Operation	Field Artillery Officer Basic 2-6-C2D-13E (Officer)	0	0
Leadership	Field Artillery Officer Basic	XX-211B	Warrant Officer
Training Manage- ment (Unit)	2-6-C20-13E (Officer)	0	0
Logistics Management Supply/ Maintenance		0	O
Navigation		0	0
Mission Planning		0	0
Target Identifi- cation and Calls for Fire		0	0
Communications		0	0
NBC Operations		0	0

# o same as above

Table 4.2-7
Maintenance Course Topics and Training Times

	Course: XXX-13TP9	Additiona	1 Hours
LCN	Equipment Name	Reference	Baseline
OAAM,OAAMAB	Propulsion System, Engine Module	6.0	<u>Dabelline</u>
OAAH,OAAX	Airspeed and Altitude (A&A) Sensors	4.0	
OAAJ	Attitude Reference Assembly	11.9	
OAAL,OASA, OAEA	Flight Control Electronic Package, Control Actuators	25.0	
OAALAB	Central Processing Unit (CPU) Module Assembly	30.0	
OAAWAF	Airborne Data Terminal (ADT)	35.7	
OEAAB, OEAAD	Television Camera, Main Optics Assembly	6.0	
OEAAC, OEAAE	Laser System	3.0	
OEAAF-OEBAA	Mission Payload System Assemblies	<u>13.0</u>	
	AIR VEHICLE SUBTOTAL	133.7	
OAS	Handling Crane	2.0	
OAL, OAT	AV Recovery Harness, AV Container	9	
	AIR VEHICLE HANDLER SUBTOTAL	2.9	
ODAA3	Radiac Meters	2.0	
ODAA3AE	Power Monitor	3.0	
ODAC2	Video Reconstruction Unit	5.0	
ODAC3	Master Interface Unit (MIU)	6.7	
ODADA,ODAEA ODAFA	Video Monitor	5.0	
ODADG	Ground Data Terminal Control Display	2.0	
ODADH	AV Control & Display Assembly	4.0	
ODAEH	Mission Payload Control & Display Assembly	4.0	
ODAFH	Mission Commander's Control & Display Assembly	4.5	
ODAFK	Video Recorder Assembly	2.0	
ODAGB	Teleprinter Assembly AN/UGC-74	2.0	
ODAJ	Navigation Display Unit	4.0	
ODALAAA	Computer/Signal Processor Rack Code Assembly	3.4	

	Table 4.2-7 (Continued)		
	Course: XXX-13TP9	Additional	Hours
LCN	Equipment Name	Reference	Baseline
ODALBAA	Main Computer	33.6	·
ODALD	Interface Unit	6.7	
OD6	Training Interface Unit, Imagery Simulator	28.2	
OD7	Portable Data Entry Device	1.0	
	GROUND CONTROL STATION SUBTOTAL	117.1	
СВВ	Initializer Assembly	16.1	
OBC	Launcher Assembly	32.0	
OBCAAAF	Launcher Control Panel	2.0	
OBD	Launcher Command Module	1.0	
	LAUNCHER SUBSYSTEM SUBTOTAL	51.1	
OGQ	AV Fault Isolator	15.0	
OGR	Nitrogen Purge Set	4.2	
XWL6,XWL7	Multimeters	1.7	
	MAINTENANCE SHELTER SUBTOTAL	20.9	
OCA	Recovery Assembly	7.0	
OCB	Recovery Guidance Assembly	<u> 5.0</u>	
	RECOVERY SUBSYSTEM SUBTOTAL	12.0	
MRGT	Antenna	7.0	
MRGT1	Remote Ground Terminal Electronics	38.0	
	REMOTE GROUND TERMINAL SUBTOTAL	45.0	
General Subjec	t Areas:		
Initialization	ction, Components Familiarization, , System Programs, Review, Preventive lanuals, System Troubleshooting, Etc.	_92.8	
·	TOTAL ACADEMIC TIMES	475.5	332.91
•			

<sup>1</sup>The reference system time was reduced by 30% in the baseline system in order to reflect planned built-in test and other diagnostic capabilities.

Table 4.2-7 (Continued)

LCN	Equipment Name	Additiona Reference	
	Course: 104-26B16		
ODAJ	Navigation Display Unit	12.0	12.0
	Course: 101-26L10		
ODAC3	Master Interface Unit	14.3	
OBB	Initializer Assembly	37.8	37.8
MRGT	RGT Antenna	21.0	
MRGT1	Remote Ground Terminal Electronics	63.0	
	TOTALS	136.1	37.8
ODAB8,ODAB9	Communications Mode Selector Control	24.5	24.5
ODADE, ODAEE,	Communications Panel Assembly	22 0	
ODAFE	TOTALS	46.5	24.5
OAALAB	Central Processing Unit Module Assembly	51.0	
ODADG	Ground Data Terminal Control Display	3.0	
ODADH	AV Control & Display Assembly	8.0	
ODAEH	Mission Payload Control & Display Assembly	8.0	
ODAFH	Mission Commander's Control & Display Assembly	10.2	
ODALBAA	Main Computer	47.2	
ODALD	Interface Unit	<u>13.8</u>	
	TOTALS	139.2	0.0
OAAJ	Attitude Reference Assembly	64.0	
	Recovery Guidance Assembly		29.0
OCB	Recovery Guidance Assembly		20.0
OCB OEAAF-OEBAA	Mission Payload System Assemblies	84.0	

maintenance training for the recovery guidance assembly in the baseline system was moved from the 610-63W10 course to the 198-35E10 course. Both of these changes were made due to changes in the FQQPRI.

The total course length for the reference 13TP9 course of 63.1 man-days (12.6 weeks) is the same as in the previous study and represents a substantial amount of organizational maintenance training. The course length for the baseline 13TP9 course (42.1 man-days) was based solely on engineering and training judgment. Most systems fielded in the Army at this time do not contain automated test equipment (ATE) or built-in test (BIT) equipment. The result was that comparability analysis could not be used to assess this RPV Based on the collective knowledge and design parameter. experience of the DRC engineering and training analysts, it was estimated that 30% of the troubleshooting training contained in the reference course could be eliminated it some form of reliable, automatic fault isolation capability was installed in the contractor However, it must be noted that this furnished equipment. projection is based on the assumption that the test capability will be dependable and will achieve the 95% fault A small number of developmental and isolation planned. recently fielded Army systems with BIT are known by DRC analysts to have not achieved their desired rate of fault isolation. Should this occur with RPV, alternate troubleshooting training as found in the reference training course would be required. In either case, sufficient training will exist to justify the requirement for an RPV-specific organizational maintenance MOS.

The direct support (DS) maintenance requirements identified for the reference system in Table 4.2-7 and summarized in Table 4.2-4, represents DS maintenance that was identified for comparably fielded equipment chosen for estimation. The total of all new projected DS maintenance training for the reference system amounts to 60.2 man-days (12.0 weeks). This does not include the RPV maintenance requirements that were assigned to existing DS maintainers who were deemed to require no additional training due to the existence of previously attained skills and knowledges. However, the baseline system requires only 12.9 man-days (2.6 weeks) of additional DS maintenance training. significant difference is due to the small amount of maintenance being assigned to the direct support echelon of maintenance in the logistics support analysis (LSA).

The shifting of DS maintenance workload to the general support (GS) and depot maintenance levels has two implications. First, a much higher number of line replaceable units (LRU's) and other maintenance repair spares will have to be maintained in the inventory, as the repair process will probably take longer. Secondly, very little training savings will be achieved as virtually all DS and GS maintainers attend the same courses. Preliminary studies underway within the Army to combine the DS and GS categories of maintenance into one, would also negate any savings achieved by having maintenance performed at the GS level.

The difference of 47.3 man-days of DS maintenance training from the reference to the baseline system, is a hidden "cost" with the baseline system. Personnel will obviously have to be trained at either the GS or depot level to repair these subsystems. The creation of a DS/GS maintenance MOS

may be required, but any such decision, as with a possible organizational maintenance MOS, involves a complicated set of personnel and training factors that would need to be studied.

The success of the present RPV training program, illustrated in Figure 4.2-1 and as mentioned in the initial study, will depend to a large degree on the supervised onthe-job training (SOJT) program. The availability of the RPV equipment, training interface unit, and training time, the required proficiency of the unit, the cross training of maintainers to operators, and the skill development of operators will have to be carefully junior system coordinated within a section. This is further complicated by the complex nature of team performance during the conduct of a flight mission. A well-defined structure of formal training, MOS proficiency certification, and supervised unit training will be required. As the XXX-13T10 course is now configured, the majority of the training will be on ground control station (GCS) operation. The graduate of this course is not likely to perform in this capacity until he is a senior E4 or a junior E5, 2 to 3 years after assignment to a unit. The training provided on GCS operation will have to be repeated when the soldier moves into the GCS, unless the SOJT program insures retention of these skills and know-An alternative approach might be to cor entrate ledges. XXX-13T10 training on launcher subsystem operations, recovery subsystem operations, air vehicle handling operations, and vehicle driving. This would necessitate the development of a Primary Technical Course (PTC) at paygrade E5 that would be devoted to GCS operation.

#### 4.3 IDENTIFY RPV TRAINING ANALYSIS RESULTS

Two parameters were chosen to depict the training resource requirements for RPV:

- o Training man-days the length of time needed to train an individual in a course.
- o Instructors the number of instructors required to conduct a course of instruction (COI).

The selection of these parameters takes into onsideration (1) the training data available for analysis, and (2) the level and kinds of meaningful training resource estimation needed by the program office to make decisions at this stage in the acquisition process. As the RPV system i further defined, subsequent iterations of the methodology allow for more detailed and varied analyses of training resource requirements

## 4.3.1 FLIR RPV Training Man-days

The number of man-days required for training was obtained from the POI for those courses that did not change and from course modification worksheets for those courses that did. Table 4.3.1-1 is a summary of the annual training man-day requirements for RPV. The reference 3/2 shift manning configuration will have the largest total requirement for training time, while the baseline sustained scenario will have the least.

Table 4.3.1-1
Annual Training Man-Days

		Refer	ence	Daseli	ne	
MOS	Course	Sustained	3/2 Shift	Sustained	3/2 Shift	FOOPRI RPV Section
13T	XXX-13T10 XXX-13TP9 XXX-13T30	27,392 8,998 722	46,727 8,998 722	24,545 6,003 722	41,870 6,003 722	30,320 6,791 722
26B	104-26B10	1,828	1,828	1,828	1,828	
26L	101-26L10	3,526	3,526	3,306	3,306	
26T	G3ABR30435	821	821	•	-	
31E	101-31E10	2,633	2,633	2,577	2,577	
31J	113-31J10	1,375	1,375	1,375	1,375	
31 <b>S</b>	160-31510	1,463	1,463	1,463	1,463	
34Y	041-34Y10	4,210	4,210	3,570	3,570	
35E	128-35E10	3,385	3,385	2,920	2,920	
35H	G3ABR3240-0	03 5,191	5,191	5,191	5,191	
36H	622-36H10	3,37	3,374	3,374	3,374	
41B	670-41B10	533	533	533	533	
41C	670-41C10	1,797	1,797	1,797	1,797	
43M	760-43M10	314	314	314	314	
44B	704-44B10	1,421	1,421	1,421	1,421	
45B	641-45B10	33€	336	336	336	
45G	113-45G10	2,3€2	2,362	_	-	
52C	662-52Cl0	2,532	2,532	2,532	2,532	
52D	662-52D10	6,683	6,683	6,683	6,683	4,104
63G	610-63G10	3,278	3,278	3,278	3,278	
63J	690-63Jl0	482	482	482	482	
63W	-610-63W10	2,932	2,932	2,295	2,295	
	TOTALS	87,588	106,923	76,545	93,870	

# 4.3.2 FLIR RPV Instructor Quantities

Estimation of the number of instructors associated with the system-specific RPV courses was determined by applying the new instructor determination and training course data provided by the Management Engineering Branch, TRADOC. Table 4.3.2-1 is a listing by system and MOS of the annual instructor requirement for RPV. The overall range of instructor requirements varied from 95.9 for the reference so tained scenario to 112.0 for the reference 3/2 shift scenario. Overall, the baseline sustained scenario was less intensive in the use of training resources than the other scenarios.

Table 4.3.2-1
Annual Instructor Requirements

		Refer	rence	Basel	ine	
MOS	Course	Sustained	3/2 Shift	Sustained	3/2 Shift	FQQPRI RPV Section
13T	XXX-13T10 XXX-13TP9 XXX-13T30	21.5 15.8 .6	36.6 15.8 .6	20.3 11.1 .6	34.6 11.1 .6	25.1 12.5 .6
26B	104-26B10	5.2	5.2	5.2	5.2	
26L	101-26L10	3.6	3.6	3.4	3.4	
26T	G3~7R30435	.8	.8	_	-	
31E	101-31E10	1.8	1.8	1.7	1.7	
31J	113-31J10	1.1	1.1	1.1	1.1	
31 <b>s</b>	160-31S10	1.6	1.6	1.6	1.6	
34Y	041-34Y10	8.5	8.5	7.6	7.6	
35E	198-35E10	3.6	3.6	2.8	2.8	
35H	G3ABR3240-00	3 2.8	2.8	2.8	2.8	
36H	622-36H10	2.7	2.7	2.7	2.7	
41B	670-41B10	.6	.6	.6	. 6	
41C	670-41C10	2.0	2.0	2.0	2.0	
43M	760-43M10	. 4	. 4	. 4	. 4	
44B	704-44B10	1.0	1.0	1.0	1.0	
45B	641-45B10	. 9	. 9	.9	. 9	
45G	113-45G10	3.4	3.4	-	_	
52C	662-52C10	3.9	3.9	3.9	3.9	
52D	662-52D10	6.5	7.5	6.5	7.5	4.8
63G	-610-63G10	4.0	4.0	4.0	4.0	
63J	690-63J10	.6	.6	.6	.6	
63W	610-63W10	3.0	3.0	2.3	2.3	
	TOTALS	95.9	112.0	83.1	98.4	

#### SECTION 5 - DETERMINE PERSONNEL REQUIREMENTS

#### 5.1 STUDY CONSIDERATIONS

The purpose of the Personnel Requirements Analysis (PRA) is to estimate the number of personnel needed to sustain any one set of system specific manpower requirements, typically those of a single Military Occupational Specialty (MOS). A PRA's major output is the number of personnel which must be trained per year to support manpower requirements; it's secondary output is a personnel structure.

It is important to note the difference between manpower and personnel requirements. A manpower requirement is a statement of the necessary number of people, described in MOS and paygrade, needed to directly perform a specific set of mission-oriented tasks for a particular weapon system. A manpower requirement is calculated based on the workload A personnel requirement is an required for the task. estimate of the number of people carried within the MOS and paygrade to offset various losses from the manpower requirement over a specified period of time. standard time period, one year, it is assumed that there are no changes to a manpower requirement ("steady-state"), hence the personnel requirements are due solely to the structure of the personnel system.

# 5.2 APPLICATION OF THE IMPACT MODEL TO THE FLIR/24 HOUR SCENARIO

The Interactive Manpower-Personnel Assessment and Correlation Technology (IMPACT) Model was developed by DRC

as a tool to determine personnel requirements given (1) manpower requirements, (2) promotion rates; (3) attrition rates and (4) Trainees, Transients, Holdees and Students (TTHS) percentage.

The concept which underlies the IMPACT model is the conservation of people. This means that the quantities of personnel which leave a particular paygrade must be replaced by personnel entering that paygrade. The IMPACT model determines the quantities of personnel needed in the specified personnel structure support manpower to requirements and to sustain itself so that the personnel structure can account for incurred losses. The IMPACT model's objective is to calculate the minimum amount of personnel needed at each level in the personnel structure. It is constrained so that each paygrade must support losses from the next higher paygrade, since replacement for those losses must be promoted from the paygrade below. The process will iterate several times before the optimal structure is established.

The example in Table 5.2-1 shows the impact on personnel requirements when two different sets of manpower requirements are generated for the same MOS. The upper set illustrates the 12 hour scenario used in the initial RPV study and the lower set reflects the FLIR/24 hour scenario. With the incorporation of the FLIR/24 hour scenario, the total system personnel requirements increased by 41.7% for the baseline system utilizing sustained workload, and 142% increases between the 3/2 shift with shared workload and the Baseline O&O scenario. These increases reflect all parameters of the FLIR/24 hour scenario which generated more manpower positions and therefore a higher demand on the

Table 5.2-1 12 HOUR SCENARIO vs. FLIR/24 HOUR SCENARIO

Rec: uits Per Year = 390.7

MOS = 13T

OVERHEAD LOSSES PER YEAR	390.7	0.0	26.3	105.6	20.7	21.0	15.0			OVERHEAD LOSSES PER YEAR	837.4	600.2	0.0	273.9	108.1	47.5	19.6
MANPOWER LOSSES PER YEAR	.0	280.1	206.1	74.2	55.8	17.1	4.4			MANPOWER LOSSES PER YEAR	0.	0.	498.1	111.3	55.8	34.2	21.9
PERSONNEL TO BE TRAINED PER YEAR	390.7	280.1	232.4	1.79.7	76.5	38.1	19.4			PERSUNNEL TO BE TRAINED PER YEAR	837.4	600.2	498.2	385.2	163.9	81.6	41.5
TTHS ADJUSTED MANPOWER	0.	132.3	175.7	117.4	115.4	57.5	14.0			TTHS ADJUSTED MANPOWER	0.	0	424.7	176.1	115.4	115.0	70.0
UNADJUSTED MANPOWER	.0	126.0	168.0	112.0	112.0	56.0	14.0		837.4	UNADJUSTED	0.	0.	406.0	168.0	112.0	112.0	70.0
PERSONNEL REQUIREMENTS	213.6	132.3	198.2	284.4	158.1	128.3	61.9		Recruits Per Year = 8	PERSONNEL REQUIREMENTS	457.8	283.5	424.7	609.5	338.7	274.9	132.6
PAYGRADE	E-1	E-2	E-3	<b>₽</b> -3	E-5	B-6	E-7	79	MOS = 13T	PAYGRADE	E-1	E-2	E-3	E-4	R-5	E-6	E-7

personnel system. Other specifics of the IMPACT model are contained in Section 6 of DRC's initial RPV study (Ref. 1).

#### 5.3 MOS/PAYGRADE DEVELOPMENT

Steady-state personnel requirements of the personnel structure are the secondary output parameter of the IMPACT model.

Figure 5.3-1 illustrates the logic upon which the PRA is based, by showing two MOS's (A and B) at two paygrade levels (El and E2). The Personnel Requirements Analysis determines the size and structure of the personnel pipelines in steady state condition by estimating the losses that occur to a Two main causes for MOS/paygrade losses are promotion and attrition. The definition of the promotion rate is the rate at which individuals advance from one paygrade to another. The attrition rate is the rate at which individuals leave a particular MOS/paygrade. types of attrition exist in the Army: (1) MOS attrition (horizontal attrition) and (2) Army attrition. Trainees, transients, holdees or students (TTHS) contribute to total force numbers, but are actually non-operational personnel and are classified as overhead. Individuals that comprise the TTHS category, while not a direct loss to the Army or paygrade since they will most likely become operational, are a substantial MOS/paygrade loss to the operational force and must be compensated for.

## 5.4 PAYGRADE DISTRIBUTION

As mentioned in Section 5.3, steady-state personnel requirements of the personnel structure are the secondary

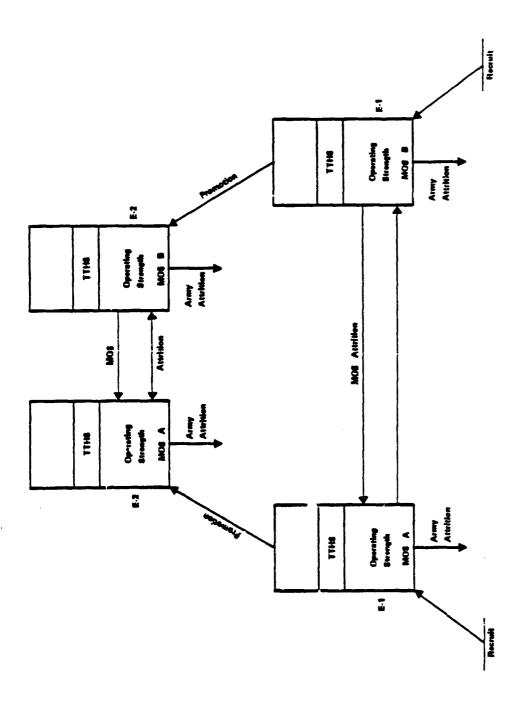


Figure 5.3-1. The Personnel Flow Diagram

output parameter of the IMPACT model. This parameter is used as a relative measure of the personnel requirements of one system as compared to those of another system. Replacement for losses primarily occur by promoting from the Therefore, if manpower requirements begin lower paygrade. at an E4 level, personnel are needed in lower paygrades to be promoted as manpower losses occur. These personnel requirements, over and above manpower requirements, are considered to be overhead supporting a particular weapon system, although they may potentially be used by another we apon system. A measure of the quantity and quality of the personnel structure provides an indication efficiently specific manpower requirements sustain For example, a structure of requirements which themselves. decreases as the paygrade spread increases (i.e., pyramidal structure) is more self-sustaining than the opposite situation. The example in Table 5.4-1 shows the impact on the personnel structure and personnel to be trained for two equal sets of manpower requirements with different grade The upper set illustrates that when the distributions. manpower requirements (column 3) for the E2 and E3 levels are aggregated at the E3 level, a larger demand personnel exists. Thus, as manpower demands call for higher skill levels (paygrades), the structure becomes less self supporting.

#### 5.4.1 FLIR RPV Recruit Requirements

The IMPAC<sup>\*</sup> del is currently a system-specific personnel model which is driven by steady-state manpower requirements. Because of this, it is assumed that manpower requirements

Table 5.4-1. Comparative Personnel Structure Impacts

	RECRUITS PER YEAR =		Company of Commen	THE CHILD THE PROPERTY.		
REQUI	REQUIREMENTS	MANPOWER	TTHS ADJUSTED MANPOWER	PERSONNEL TO BE TRAINED PER YEAR	MANPOWER LOSSES PER YEAR	OVERHEAD LOSSES PER YEA
45	457.8	0.	0.	837.4	0.	837.4
28	283.5	0.	0.	600.2	0.	600.2
42	424.7	406.0	424.7	498.2	498.1	0.0
9	609.5	168.0	176.1	385.2	111.3	273.9
33	338.7	112.0	115.4	163.9	55.8	108.1
27	274.9	112.0	115.0	81.6	34.2	47.5
13	132.6	70.0	70.0	41.5	21.9	19.6
RECRUTES	RECRUTUS PER YEAR =	= 629.5				
34	344.2	0.	0.	629.5	0.	629.5
21	213.2	203.0	213.1	451.2	451.2	0.0
3]	319.3	203.0	212.3	374.5	249.1	125.4
4	458.2	168.0	176.1	289.6	111.3	178.3
25	254.7	112.0	115.4	123.3	55.8	67.4
24	206.6	112.0	115.0	61.4	34.2	27.2
0,	49.7	70.0	70.0	31.2	21.9	9.3

are already filled, and therefore, the personnel requirements represent the quantities and qualities of personnel which it takes to sustain these already filled manpower requirements. Table 5.4-2 shows the annual recruiting requirements for all the MOSs used in the RPV study. These requirements reflect the minimum number of recruits that need to be brought into the personnel pipeline in order to sustain RPV manpower requirements. With the FLIR/24 hour scenario, recruiting requirements increased over the requirements that supported the 12 hour scenario.

Table 5.4-3 shows the recruiting requirements for the fractional MOS concept, which is based on determining personnel requirements solely on workload as opposed to the "whole body". These personnel requirements are shown for DS maintenance elements only since this is where "shared" support will occur with other units. The fractional MOS consideration results in a lower demand on the personnel system.

#### 5.5 IDENTIFY PERSONNEL ANALYSIS RESULTS

The RPV 13T MOS personnel structure indicates a larger demand at the E4 and E3 levels than is available from the inherent 13T E2 and E1 levels. This was in spite of accomplishing much of the non-skill level specific workload at the E2 level; e.g., vehicle drivers. There are a number of potential solutions to this "hump" in the structure, including (1) reinforcing the 13T MOS at the E4 level with personnel cross trained from another MOS, (2) cross training with other systems so that a greater F1 and E2 pool would be available (i.e., create a secondary MOS), or (3) shift

Table 5.4-2. Recruiting Requirements

	Refer	cence	Baseli	ne	
MOS	Sustained	3/2 Shift	Sustained	3/2 Shift	FQQPRI RPV Section
13T	490.9	837.4	490.9	837.4	606.4
13TP9	142.6	142.6	142.6	142.6	161.3
,26B	15.3	15.3	15.3	15.3	
26L	17.9	17.9	17.9	17.9	
26T	10.8	10.8	-	-	
31E	20.6	20.6	20.6	20.6	
31J	12.5	12.5	12.5	12.5	
31S	22.5	22.5	22.5	22.5	
34Y	36.8	36.8	36.8	36.8	
35E	31.2	31.2	31.2	31.2	
35H	29.0	29.0	29.0	29.0	
36H	17.3	17.3	.17.3	17.3	
418	21.3	21.3	21.3	21.3	
41C	20.9	20.9	20.9	20.9	
43M	9.5	9.5	9.5	9.5	
44B	20.9	20.9	20.9	20.9	
45B	8.2	8.2	8.2	8.2	
45G	20.9	20.9	-	-	
52C	42.2	42.2	42.2	42.2	
52D	142.2	142.2	142.2	142.2	88.6
63G	44.9	44.9	44.9	44.9	
63J	11.2	11.2	11.2	11.2	
63W	54.3	54.3	42.5	42.5	•

Table 5.4-3. Annual Recruiting Requirements

Fractional MOS Consideration at
the Direct Support (DS) Level

	Refer	rence	Base	line
MOS	Sustained	3/2 Shift	Sustained	3/2 Shift
26B	0.8	0.8	0.1	0.1
26L	3.8	4.8	0.1	0.1
26T	3.4	4.3	-	-
31E	11.6	13.3	7.5	8.1
31J	3.7	3.7	0.8	0.8
31 <b>S</b>	2.9	2.9	2.9	2.9
34Y	7.1	8.1	1.0	1.3
35E	1.1	1.5	0.2	0.2
35H	5.0	5.0	5.0	5.0
36H	1.2	1.2	1.2	1.2
41B	2.0	2.0	2.0	2.0
41C	0.1	0.1	0.1	0.1
43M	0.1	0.1	0.4	0.4
44B	1.9	2.1	1.9	2.2
45B	0.1	0.1	0.1	0.1
45G	7.5	10.6	-	-
52C	10.8	10.8	13.2	13.2
52D	8.5	9.6	7.4	8.1
63G	34.0	40.7	13.4	15.7
63J	0.1	0.1	0.1	0.1
63W	34.7	34.7	27.2	27.2

workload through the system engineering analysis to incorporate a greater El and E2 requirement.

Personnel requirements for the FQQPRI RPV section were calculated using the IMPACT model. Comparing the result against the operator requirements for the baseline system 3/2 shift, this analysis resulted in a 696 requirement increase in personnel for the baseline system 3/2 shift.

#### 5.6 CALCULATE PERSONNEL REQUIREMENTS

Results of the IMPACT model for each of the Military Occupational Specialties (MOSs) considered in the RPV application are contained in Appendix D. Tables 5.6-1 through 5.6-4 are summary charts of these results, depicting personnel requirements by MOS including the DS fractional considerations by paygrades (with and without headquarters requirements) and includes the FQQPRI requirements as well.

Table 5.6-1 Personnel Requirements by MOS (Includes Platoon Headquarters Requirements)

	Referen	nce	Basel	ine	
MOS	Sustained	3/2 Shift	<u>Sustained</u>	3/2 Shift	FOOPRI RFV Section
131	1478	2522	1478	2522	1826
13T*	1391	2435	1391	2435	1739
13TP9	360	360	360	350	407
26B	39	39	39	39	
26L	59	59	59	5 9	
26 <b>T</b>	31	31	-	-	
31E	44	44	44	ьą	
31J	34	34	34	٤٠	
31s	51	51	51	51	
34Y	97	97	97	97	
35E	90	90	90	90	
35Н	82	82	82	82	•
36H	43	43	43	43	
41B	42	42	42	42	
41C	44	4.4	44	44	
43M	2.7	27	27	27	
44B	69	69	69	69	
45B	27	27	27	27	
45G	47	47	-	-	
52C	125	125	125	125	
52D	293	293	293	293	182
63G	111	111	111	13.1	
63J	31	31	31	31	
6 3W	147	147	113	115	

<sup>\*</sup>Does not include Platoon Headquarters 13T requirements.

Table 5.6-2 Total Personnel Incorporating Fractional MOS Consideration for Direct Support (DS) Level

	Refere	Reference		Bas-line	
MOS	<u>Sustained</u>	080	Sustained	080	
263	2.0	2.0	0.4	0.4	
26L	13.0	16.0	0.5	0.5	
26T	10.0	12.0	_	-	
31E	25.0	28.0	16.0	17.0	
31 <i>3</i>	10.0	10.0	2.0	2.0	
31.5	7.0	7.0	7.0	10.0	
34 <u>%</u>	19.0	22.0	3.0	4.0	
303	3.0	5.0	1.0	1.0	
35H	14.0	14.0	14.0	14.0	
36H	3.0	3.0	3.0	3.0	
41B	4.0	4.0	4.0	4.0	
41C	0.4	0.4	0.4	0.4	
43M	0.1	0.1	1.0	1.0	
44B	6.0	7.0	6.0	7.0	
45B	0.1	0.1	0.1	0.1	
45G	17.0	24.0	-	-	
52C	32.0	32.0	39.0	39.0	
52D	18.0	20.0	15.0	17.0	
63G	84.0	101.0	33.3	38.8	
63J	0.3	0.3	0.3	0.3	
63W	147.0	147.0	73.0	73.0	

Table 5.6-3 Personnel Requirements by Paygrade (Includes Platoon Headquarters Requirements)

Reference		Base	line		
<u>Grade</u>	Sustained	3/2 Shift	Sustained	3/2 Shift	FOOPRI RPV Section
E-1	676.8	866.2	652.7	842.1	466.4
E-2	467.1	584.4	446.2	563.5	294.2
<b>E-</b> 3	644.6	820.3	621.4	797.1	432.4
E-4	964.5	1,216.7	911.6	1,163.8	616.8
E-5	376.6	516.7	372.7	512.8	310.5
E-6	161.1	274.9	161.1	274.9	199.0
E-7	77.1	132.6	77.7	132.6	96.0
E-8	-	-	-	-	-
E-9	-	-	-	-	-
TOTAL	3,368.4	4,411.8	3,243.4	4,286.8	2,415.3

Table 5.6-4 Personnel Requirements by Paygrade (Excludes Platoon Headquarters Requirements)

	Refer	ence	Basel:	<u>ine</u>	
<u>Grade</u>	Sustained	3/2 Shift	Sustained	3/2 Shift	FQQPRI RPV Section
1	534.7	724.1	510.6	700.0	450.6
2,	379.0	496.4	358.1	475.5	284.4
3	512.8	688.5	489.6	665.3	417.8
4	775.3	1,027.5	722.4	974.6	595.8
5	271.4	411.6	267.5	407.7	298.8
6	151.7	189.6	151.7	189.6	189.6
7	73.2	91.5	73.2	91.5	91.5
8	-	-	-	-	-
9	-	~	-	-	-
TOTAL	2,698.1	3,629.2	2,573.1	3,504.2	2,328.5

#### SECTION 6 - CONDUCT IMPACT ANALYSIS

#### 6.1 OVERVIEW

Impact Analysis determines the demand that an emerging system's personnel and training requirements will place upon the projected supply of personnel and training resources. This supply/demand assessment identifies a system's "high drivers", i.e., those factors related to design, personnel or training policy, maintenance plan or scenario, which would cause consumption of a disproportionate share of the available resources. Having determined these high resource drivers, they often become the focus for tradeoff analysis to identify alternative approaches to lessen their system impacts.

Impact Analysis for this iteration was conducted by taking advantage of a reasonable, simplifying assumption: RPV will, in essence, represent a complete addition to the Army's force structure (and hence manpower, personnel and training requirements). In other words, no Army system presently deployed will be replaced by RPV. The rationale of this assumption stems from the RPV's Organizational and Operational Concept, which indicates that the Army presently lacks the capability which RPV provides, thus establishing the RPV system requirements. The utility of this major assumption is elaborated upon in the following sections, which describe training and personnel impacts, respectively.

#### 6.2 TRAINING IMPACTS

For a determination of training impacts, the assumption that the RPV will represent a complete force structure addition implies that existing training resources will be, and will remain, completely committed to Army training presently being conducted. Thus, RPV the training resource requirements, or demands, determined in Section 4 are completely "unfunded", and consequently the impacts of these demands are the demands themselves. It remains only to rank-order the training resource requirements (man-days and instructors) in descending order to determine their degree The results of this ranking are displayed in of impact. Tables 6.2-1 and 6.2-2.

# 6.3 PERSONNEL IMPACTS

## 6.3.1 Process

A comparison of the personnel demands of a new system to available personnel resources can indicate three conditions: (1) a surplus of resources relative to demand, (2) a shortage of resources, or (3) projected resources are adequate to meet demand. In Impact Analysis, the first condition is called a surplus, the second a shortfall, and the third condition is referred to as neutral.

Two types of personnel data, authorizations and availability, were used to make supply/demand comparison. Authorizations are those manpower positions, or spaces, for which the Army has received (or must request) funding authority from the Congress. Thus authorizations constitute

Table 6.2-1
Training Impacts: Man-Days

Reference

Baseline

Rank Order	Susta MOS Ma	ined n-Days		Shift an-Days		ained an-Days		Shift an-Days
Order	MOS Ma	II-Days	<u> 1105 11</u>	an bays	<u> </u>	an bays	<u>1105</u> H	an-bays
1	13T 2	7,392	13T	46,727	13T	24,545	13T	41,870
2	13TP9	8,998	13TP9	8,998	13TP9	6,003	52D	6,683
3	52D	5,645	52D	6,683	52D	5,645	13TP9	6,003
4	35H	5,191	35H	5,191	35H	5,191	35H	5,191
5	34Y	4,210	3 <b>4</b> Y	4,210	3 <b>4</b> Y	3,570	34Y	3,570
6	26L	3,526	26L	3,526	36H	3,374	36H	3,374
7	35E	3,385	35E	3,385	26L	3,306	26L	3,306
8	36H	3,374	36H	3,374	63G	3,278	63G	3,278
9	63B	3,278	63G	3,278	35E	2,920	35E	2,920
10	63W	2,932	63W	2,932	31E	2,577	31E	2,577
11	31E	2,633	31E	2,633	52C	2,532	52C	2,532
12	52C	2,532	52C	2,532	63W	2,295	-6'3W	2,295
13	45G	2,362	45G	2,362	26B	1,828	26B	1,828
14	26B	1,828	26B	1,828	41C	1,797	41C	1,797
15	41C	1,797	41C	1,797	31S	1,463	315	1,463
16	3 <b>1S</b>	1,463	31s	1,463	44B	1,421	44B	1,421
17	44B	1,421	44B	1,421	31J	1,375	31J	1,375
18	31J	1,375	31J	1,375	13T30	722	13T30	722
19	26T	821	26T	821	41B	533	41B	533
20	13T30	722	13T30	722	63J	482	63J	482
21	41B	533	4]B	533	45B	336	45B	336
22	63J	482	63J	482	43M	314	4 3M	314
23	45B	336	45B	336	-	-	_	-
24	43M	314	43M	314	_	-	-	-

Table 6.2-2
Training Impacts: Instructors

Baseline Reference Sustained 3/2 Shift Sustained 3/2 Shift Instructors Order MOS Instructors MOS Instructors MOS Instructors MOS 36.6 13T 20.3 13T 13T 21.5 13T 34.6 1 15.8 13TP9 15.8 13TP9 11.1 13TP9 11.1 2 13TP9 7.6 3 34Y 8.5 34Y 8.5 34Y 7.6 34Y 7.5 6.5 52D 7.5 52D 6.5 52D 4 52D 5 5.2 26B 5.2 26B 5.2 26B 5.2 26B 4.0 63G 4.0 4.0 4.0 6 63G 63G 63G 7 52C 3.9 52C 3.9 52C 3.9 52C 3.9 8 26L 3.6 26L 3.6 26L 3.4 26L 3.4 9 35E 3.6 35E 3.6 35E 2.8 35E 2.8 45G 3.4 45G 3.4 35H 2.8 2.8 10 35H 3.0 63W 3.0 2.7 2.7 11 63W 36H 36H 12 2.8 35H 2.8 2.3 35H 63W 2.3 63W 2.7 36H 2.7 41C 2.0 41C 2.0 13 36H 14 41C 2.0 41C 2.0 31E 1.7 31E 1.7 1.8 1.8 31S 1.6 31S 1.6 15 31E 31E 1.6 31J 1.1 31J 1.1 16 31S 1.6 31S 1.1 44B 1.0 44B 1.0 17 31J 1.1 31J 1.0 45B .9 45B .9 18 44B 1.0 44B 19 45B .9 45B . 9 13T30 13T30 . 6 . 6 .8 26T . 8 41B . 6 41B . 6 20 26T .6 13T30 63J 63J . 6 21 13T30 . 6 . 6 22 41B .6 41B . 6 43M . 4 43M . 4

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43M

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63J

43M

a statement of the Army's demand for manpower. ability, on the other hand, is a statement of the personnel system's ability to fill the authorized positions with individuals. In any current year, availability is a statement of personnel inventory on-hand. In a future year, it is an estimate of future supply. It must be noted that authorizations do not reflect the force structure required to satisfy the various missions with which the Army has been tasked. In peacetime, the Army chooses not to man (i.e., authorize) 100% of its units at 100% of their force structure requirement, in order to divert resources to other priority objectives. Consequently, authorizations are usually lower than requirements; stated another way, the manpower demand reflected by requirements is almost always higher than that reflected by authorizations. It is not possible to make an analysis of how an emerging system's manpower requirements impact on the total force structure requirements without knowing how force structure requirements are allocated to the various systems and MOS's. This information was not available for this RPV study.

It was, however, possible to determine the impact of RPV for a supply/demand comparison based on authorizations. RPV will represent a complete increase to present projections of both authorizations and availability, since it is also assumed that no systems will be replaced by RPV. 1 Therefore

The new enlisted MOS required by RPV, 13TXX with ASIP9, RPV Crewmember and Mechanic, respectively, were assumed to impact upon, and therefore could be represented by, the existing MOS 15D. Their true availability ratios are zero, since the skills do not presently exist in the inventory. However, the impacts presented here represent the more realistic case, where RPV will draw its manpower from an existing pool such as the 15D MOS.

100% of the RPV specific manpower (i.e., force structure) requirement will be added to present authorizations. An availability ratio (AR) may now be calculated using the equation:

where:

AR < 1 = Shortfall AR > 1 = Surplus AR = 1 = Neutral

Availability and authorization data, by MOS and paygrade, for fiscal year (FY) 1983 were provided from the Army's Personnel Policy Project Model (P<sup>3</sup>M). This data was accepted as the "best estimate" on which to base near-term decisions regarding RPV. Further, the data were inflated to allow for the effect of the Trainees, Transients, Holdees and Students (TTHS) account. These figures had to be backed-out using the TTHS percentages from the Chief of Personnel Operations (COPO) 45 report. Thus the final equation was:

Adjusted availability and authorizations for the MOS's considered by the RPV study are displayed in Table 6.3-1. RPV manpower requirements are displayed in Table 6.3-2. Table 6.3-3 displays the Availability Ratio results. example of how to interpret the given AR values, the 13T MOS in Table 6.3-3 indicates that the potential source of the 13T MOS has a projected availability for FY-84 of 87%. 0.69 in column 4 indicates that when the RPV demands for MOS 13T are placed on the personnel system, a 31% shortfall exists. The 0.21 in parenthesis for column 3 indicates that the AR demand in column 4 shows a load of 21% with respect to the column 2 FY84 AR projection. The following section describes the P<sup>3</sup>M model and how availability authorization were defined. For detailed information regarding the P<sup>3</sup>M model and how specific availability and authorization considerations are defined, see DRC's initial RPV report, Volumes I and II, previously referenced.

#### 6.4 MAINTENANCE IMPACTS

The addition of the FLIR payload package to the RPV system introduced some requirements for additional operator and maintenance task—at the section level. The impact of this payload package upon the total workload requirements previously determined for the RPV section was minimal. This information is detailed in Sections 2 and 3.

However, because of the specific requirements for detailed and sophisticated maintenance tasks for the FLIR payload, consideration was given to the impact of the maintenance level at which these specific tasks were to be performed. While having little or no effect on the RPV section

Table 6.3-1. Adjusted Availability/Authorizations FY 1984 Total MOS/Paygrade

MOS	Availabilit	<u>Authorizations</u>
13T	2,517.07	2,839.58
26B	152.22	185.77
26L	763.04	926.62
26 <b>T</b>	235.12	261.95
31 <b>E</b>	1,605.29	1,634.74
31 <b>J</b>	1,713.18	1,891.23
31 <b>s</b>	747.19	631.69
34Y	585.14	455.62
35E	521.37	529.06
35H	1,330.93	1,285.33
36H	1,339.13	1,586.42
41B	49.22	42.98
41C	514.32	546.12
43M	458.84	516.17
44B	1,540.48	1,436.45
45B	467.07	515.26
45G	356.30	320.74
52C	1,851.32	1,805.10
52D	3,143.56	3,314.69
63G	821.35	877.70
63J	1,006.13	1,312.64
6 3W	3,386.56	4,126.45

Table 6.3-2. RPV Manpower Requirements

	Reference		Basel	line	
MOS	Sustained	3/2 Shift	Sustained	3/2 Shift	RPV FQQPRI Section
13T	700	840	702	840	756
13TP9	112	112	112	112	168
26B	14	14	14	14	
26L	14	14	14	14	
26T	14	14	-	-	
31E	14	14	14	14	
31J	14	14	14	14	
31S	14	14	14	14	
34Y	14	14	14	14	
35E	14	14	14	14	
35H	14	14	14	14	
36H	14	14	14	14	
41B	14	14	14	14	
41C	14	14	14	14	
43M	14	14	14	14	
44B	14	14	14	14	
45B	14	14	14	14	
45G	14	14	-	-	
52C	14	14	14	14	
52D	126	126	126	14	56
63G	14	14	14	14	
63J	14	14	14	14	
63W	42	42	28	28	

Table 6.3-3. Availability Ratio Results

	Current FY 84	Reference	Baseline
	Projection	Sustained 3/2 Shif	
13T	0.87	(.21) .59 (.24) .6	6 (.21) .69 (.24) .66
26B	0.82	(.07) .76 (.07) .7	6 (.07) .76 (.07) .76
26L	0.82	(.01) .81 (. () .8	1 (.01) .81 (.01) .81
26T	0.90	(.06) .85 (.06) .89	5 (.00) .90 (.00) .90
31E	0.98	(.01) .97 (.01) .9	7 (.01) .97 (.01) .97
31J	0.91	(.01) .90 (.01) .90	0 (.01) .90 (.01) .90
31 <b>s</b>	1.18	(.02) 1.16 (.02) 1.16	6 (.02) 1.16 (.02) 1.16
34Y	1.28	(.02) 1.25 (.02) 1.29	5 (.02) 1.25 (.02) 1.25
35E	.99	(.02) .97 (.02) .97	7 (.02) .97 (.02) .97
35H	1.04	(.02) 1.02 (.02) 1.02	2 (.02) 1.02 (.02) 1.02
36H	0.84	(.00) .84 (.00) .84	(.00) .84 (.00) .84
41B	1.15	(.25) .86 (.25) .86	(.25) .86 (.25) .86
41C	0.94	(.02) .92 (.02) .92	2 (.02) .92 (.02) .92
43M	0.89	(.03) .86 (.03) .86	(.03) .86 (.03) .86
44B	07	(.01) 1.06 (.01) 1.06	(.01) 1.06 (.01) 1.06
45B	0.91	(.03) .88 (.03) .88	(.03) .88 (.03) .88
45G	7.11	(.06) 1.06 (.06) 1.06	(.00) 1.11 (.00) 1.11
52C	1.03	(.01) 1.02 (.01) 1.02	(.01) 1.02 (.01) 1.02
52D	0.95	(.04) .91 (.04) .91	(.04) .91 (.04) .91
63G	0.94	(.02) .92 (.02) .92	(.02) .92 (.02) .92
63J	0.77	(.01) .76 (.01) .76	(.01) .76 (.01) .76
63W	0.82	(.01) .81 (.01) .81	(.00) .82 (.00) .82

workload, the level at which repair of the FLIR package would be accomplished does have an effect on the overall system supportability and thus ultimately effecting total system readiness and availability. Therefore, the prime maintenance impact associated with this study effort was the level at which maintenance/repair functions for the FLIR payload package are performed.

#### SECTION 7 - TRADEOFF ANALYSIS

#### 7.1 IDENTIFY TRADEOFF ALTERNATIVES

As an integral step within the HARDMAN methodology, tradeoff analyses which assess design, personnel, training or logistics alternatives are normally conducted. These tradeoffs help to formulate solutions to excessive resource consumers and potential problems are identified during system impact analysis.

As the analysis of the RPV section operating with alternative mission payloads in a 24 hour per day scenario proceeded, numerous tradeoff candidates were considered. Of these, three likely tradeoff candidates within the scope of this study were recommended to the program office. These candidates included tradeoffs concerning operational scenario and support considerations.

Regarding the operational scenario, a tradeoff of the number of moves conducted by the RPV section within a 24 hour period and its impact on system human resource requirements was proposed. Concerning support considerations, two tradeoff alternatives were identified. The first involved an examination of the maintenance tasks associated with the FLIR mission payload subsystem (FMPS) and the level at which these maintenance tasks were performed. This alternative included consideration of maintenance actions at the crew/organizational, direct support (DS), general support (GS) and depot levels of maintenance.

The second support consideration involved an examination of the requirement for a minimum delay time associated with unavoidable stoppage/breakdown of the 30KW generators that power the ground control station. Present specifications call for a 90 second maximum period of time within which one generator can stop and the other one be brought online. This requirement has direct impact upon the personnel who must operate and service the generator, specifically the Power Generation Equipment Repairers, MOS 52D. A tradeoff examination of the impact of this 90 second requirement upon the manpower requirements of the RPV section (as effects MOS 52D or other similarly trained personnel) was proposed.

After reviewing the three proposed tradeoff alternatives, the RPV Program Office decided that an examination of the maintenance tasks related to the FMPS should be conducted.

Emphasis of the tradeoff would be an examination of the direct support, general support and depot maintenance tasks associated with the FMPS. The results of this tradeoff are detailed in the following sections.

# 7.2 TRADEOFF OF SELECTED ALTERNATIVE

# 7.2.1 Scope of Analysis

In the design of modern weapon systems, adequate attention must be given to determine a weapon system's optimum level of repair (LOR) structure. The earlier in the acquisition process that LOR considerations are examined and planning commences, the greater the probability that the approved LOR decision for a given design will be optimal with respect to

repair sources required. The final LOR structure identifies the repair location as well as the extent of maintenance tasks to be performed and resources necessary to support the repair process.

Consideration of all logistic and operational factors and alternatives must precede the LOR decision. Thus, such a decision can be made an integral part of the system design process to ensure optimum logistic support at minimal cost. Ultimately, a specific design of a system or subsystem must be used to conduct a competent, in-depth repair-level analysis. However, the RPV FLIR mission payload subsystem (FMPS) procurement has not as yet reached the contractual stage of engineering development whereby a design has been selected.

In considering likely FLIR designs, potential commercial FLIR vendors provided design related information to DRC during the timeframe of this study. Additionally, FLIR systems which are presently in DoD inventories were examined with respect to the present level of repair considerations. Therefore, armed with information/data regarding both present and proposed FLIR systems, this examination of the support concepts that may be associated with a FLIR LOR analysis serves as a "first cut" at identifying and determining those factors that can influence the FLIR LOR decision.

It should be noted that other than a DoD data item description requirement (number DI-S-6169), titled Optimum Repair Level Analysis (ORLA) Report, there is no specific instructions for conducting an Army ORLA. For this reason, the Military Standard Level of Repair, MIL-STD-1390B (Navy), was used as a guideline for this analysis (Ref. 8).

# 7.2.2 Approach to Problem

The LOR considerations were initially approached from principally a non-economic LOR analysis since cost data were not readily available. Also, non-economic considerations sometime preempt the LOR choices available and should therefore precede an economic analysis. However, for this study pertinent economic analysis cost factors are also considered and a full qualitative and a limited quantitative assessment of their influence is made. This economic assessment is limited in the sense that the cost values are only representative of those that may be encountered rather than actual. Since this a comparative analysis, the results will be valid indicators of the respective cost of repair.

Table 7.2-1 summarizes the results of this first step in the LOR analysis of the FMPS. Specifically, the left hand column of Table 7.2-1 lists the factors that are of concern when reviewing LOR analysis considerations. The two columns labeled "Impact Potential" provide a judgemental determination of whether there is an influence on those factors by the F'S when the LOR is changed.

Given that one or more of the line replaceable units (LRUs) of the FMPS has its designated LOR changed from the depot to the general support (GS) level or vice-versa, or from the GS to the direct support (DS) level or vice-versa; the "what if" question(s) posed in making the judgments were: (1) wi'l the factors listed be impacted and (2) why and to what degree are these economic and non-economic factors influenced? Non-economic feasibility and relative cost were two principal criteria used when considering the degree of impact.

Table 7.2-1 LOR Analysis Considerations for FLIR MPS

-	Impact Po Depot ← GS Level	Potential Depot ↔ DS Level	Considerations of Importance
Non-Economic Factors, "Preemptive"			
Safety	Yes	Yes	Laser Safety Conditions
Manning	Yes	Yes	Workload shift may cause additional positions even though no significant manhours required
Human Factors			
(1) Special Skills	Yes	Yes	Special Test Equipment; sophisticated and new sensors
(2) Human Engineering	ON.	No	
. 0		•	
(3) Life Support Engineering	ON	O.	
Technical Feasibility of Repair			
(1) Specialized Repair Facilities	Yes	Yes	Possible clean room conditions; need for special test equipment
(2) Training Requirements	Yes	Yes	See Special Skills
(3) Manpower Availability	Yes	, ves	Special Training or prerequisites may inhibit availability

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Considerations of Importance	End item is less than 60 lbs.	End item specification requires a low volume.	Use of special containers is necessary regardless of LOR.	•	DS and GS level will require special test and/or support equipment (potential high cost item)	Line Replaceable Units location will influence pipeline spares cost (high cost item)	See Special Skills.	Smailer components to transport as LOR shifts toward field, special containers may be necessary, however.	Containers and spares require suitable storage space.	Requires special bench repair capability, particularly if a clean room is needed.	
ntial Depot⇔ DS Level	o X	Ø.	Yes, but		Yes	Yes	Yes	Yes	Yes	Yes	- {
Impact Potential Depot ← GS Dep	NO	ON.	Yes, but		Yes	Yes	Yes	Yes	Yes	Yes	
Special Transportation Factors	(1) Weight	(2) Volume	(3) Susceptibility to Transportation Damage	Economic Analysis Factors, "Cost"	Support Equipment (SE)	Spares Inventory	Training	Transportation	Inventory Storage Space	Repair & SE Space	

Table 7.2-1 (Continued)

Considerations of Importance	Not labor intensive therefore not a high manhour cost but could cause need for a position (See Manning).	Not a high cost item in relation to spares and SE.
tential Depot ↔ DS Level	Yes	Yes
Impact Potential Depot ↔ GS Depot Level Level	Yes	Yes

Documentation

Labor

A "yes" answer indicates an impact of some nature when the LOR is changed. A "no" answer indicates no apparent impact. The cause or consideration that resulted in a particular impact finding, plus any comments regarding the degree of influence, are provided in the right hand column labeled "considerations of importance."

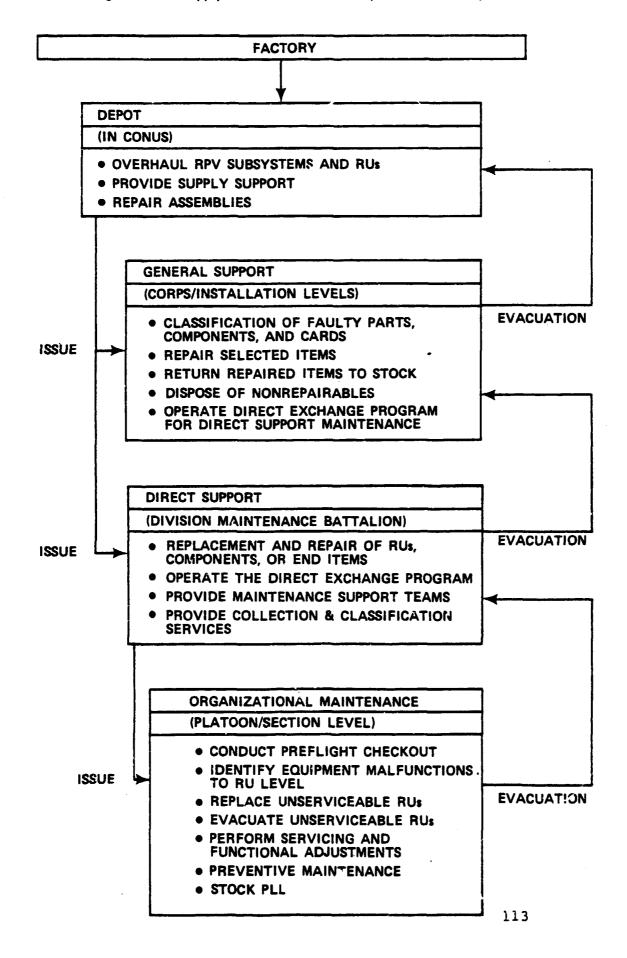
#### 7.2.3 Technical Considerations/Assumptions

The FMPS is to be a modular replacement for the present TV equipped MPS (TVMPS). Therefore, the present RPV system maintenance concept was the frame of reference and the original TVMPS maintenance requirements served as an example of potential LOR capability when examining FMPS maintenance requirements. Figure 7.2-1 depicts the RPV system supply and maintenance concept as delineated by Lockheed Missile and Space Company's Integrated Logistic Support Plan (ILSP) (Ref. 7).

The following assumptions regarding test and repair and the logistic process requirements prevail in this analysis:

- o The FMPS will conform to the same four-level maintenance concept as the RPV system; namely, organizational, direct support (DS), general support (GS), and depot.
- o Depot level maintenance is fully capable of any type of repair regardless of lower level repair assignments.

Figure 7.2-1. Supply and Maintenance Concept for the RPV System



- o Logistic support for equipment and material will be through normal Army supply and maintenance channels.
- o No discards of assemblies or components take place below depot level.

The following list contains the general assumptions regarding cost elements and/or principal cost factors that are inherent in the DRC life cycle cost model which is titled the reliability, maintainability, and cost model (RMCM). Only the assumptions effecting this analysis are included.

- o The model considers a uniform level of air vehicles at each operating site. (one GS maintenance element per site supporting one RPV platoon of four sections).
- o The spares level and pipeline quantities are computed to support the peak level of system activity, peak flying hours, rather than any incremental buildup.
- The model explicitly computes only those logistics support costs associated with the system, line replaceable (LRU) subsystem, and unit indenture levels. Components below the LRU level (i.e., a shop replaceable unit (SRU)), are only implicitly considered by their relationship to a repair of a given LRU. For example, average costs of SRU spares are computed based on the failure rates of their respective LRUs.

- There are three levels of repair exclusive of C condemnation: (1) on-equipment repair at the organizational level, (2) shop repair at the DS or GS level on-site, and (3) repair at the depot. From the on-site GS facility, only two levels can repair at the GS or ship to the be exercised: The decision to ship failed LRUs to the depot is made at the GS level upon receipt and inspection of the equipment, and this probability is obtained from the R&M model. Items designated for depot repair provide the source of the LRUs and SRUs for condemnation (throw away). A one percent and five percent condemnation rate were selected for the LRUs and SRUs, respectively.
- sites are assumed to be identical in the model with respect to maintenance manpower levels, consumables, and facilities.
- o The recurring depot repair cost factors are predicated on average values of one centralized depot repair location.
- o Sites are assumed to be identical with respect to environmental effects on equipment failure rates and logistics support.
- Inventories of spare LRUs are located at each of the sites consistent with the demand rate for LRUs at the sites and the variable depot-to-site resupply time-interval selected for use in the model. In addition, inventories are also located at the depot consistent with the appropriate LRU

demand rates, resupply times, site repair-cycle time, and depot repair-cycle time selected for use in the model.

- o Transportation costs may vary for the sites, but a representative average for overseas and CONUS sites is employed in the model for the LRU depot repairs.
- o Forward supply points are not considere the model. However, the transportation cost impot repairables for overseas sites is computed in terms of the increased packing and shipping cost, and the proportion of forces overseas.
- o The relationship established for determining the required quantities of shop support equipment (SE) assumes a manhour/machine hour equivalence. This SE demand time supposes that a given piece of SE is occupied during the elapsed time period equivalent to the mean time to perform a shop bench check task event. The downtime for repair of the SE test station is also accounted for when computing SE utilization.
- o Maintenance personnel perform the direct maintenance manhours (DMMH) needed to meet the depot maintenance requirements of the deployed unit(s). The indirect maintenance labor attributable to supervisors, administrative, and supply personnel are accounted for through the indirect labor cost terms in the model.

- o Training costs are computed according to the following concept: (1) initial training and training equipment costs are not considered, (2) recurring training costs for organizational and DS/GS personnel are based on average turnover rates for each MOS and (3) cost of recurring training for the cadre personnel other than depot are absorbed in their yearly salaries over the lifetime of the system. The recurring costs of training depot personnel are assumed to be in the overhead of depot level LRU repair.
- o All costs input to the model are in constant-year, 1982 dollars.
- The reliability parameter values in the data bases are based on mean operating/flying hours between maintenance actions (MFHBMA). The maintenance actions inherent in the MFHBMA variable include those brought about by the FMPS being removed and shipped to the shop for repair and the remove-and-replace LRU actions. The remove actions are representative of the mean time between failure (MTBF) rate for the LRUs that are to be repaired.
- o Maintenance costs are computed to include the costs of labor for both corrective (unscheduled) and preventive (scheduled) maintenance at the site level. Maintenance labor costs at the depot are contained in the average cost-per-depot-repair of an LRU.
- o Some of the major cost values used, and associated assumptions are:

- FMPS Production Cost/Srbsystem = \$125,000 (Ref.
   The three lower level major assemblies were prorated to add up to the FMPS cost as follows:
  - (a) Optical Turret Assembly = \$46,800
  - (b) Inner Gimbal Assembly = \$57,200
  - (c) Payload Support Assembly = \$20,800
- 2. Unit cost of the next lower level replaceable assemblies were estimated. The average cost of the SRUs used in the repair process were calculated on the basis of how many of these SRUs are contained in the subassembly. This average SRU cost was multiplied by a factor of 1.5. This factor incorporates the consideration that the total costs of all subassembly parts (SRUs) when produced separately are greater than the cost of the subassembly itself.
- 3. Unit cost of each test station (support equipment (SE)) for the GS level is \$130,000 including the \$30,000 interface hardware to utilize existing test stations. One SE is required per GS site.
- 4. Unit cost of depot level SE is \$200,000 per "test station". Two SE are required for the one depot site. However, four SE are required at the depot when the GS level is not performing maintenance to handle the additional load.

- 5. Depot repair cycle time is 34 days.
- 6. Base repair cycle time is 5 days.
- 7. Expected back order for spares is 0.1.
- 8. Number of GS sites is 14.
- 9. Number of AVs supported by a GS site is 20.
- 10. Half of the total force is deployed overseas.
- 11. Planned inventory usage period (Life Cycle) is 10
   years.

#### 7.2.4 FMPS Work Breakdown Structure

Section 2 describes the system engineering analysis portion of this study which resulted in the choice of a representative FMPS. Figure 2.2-1 pictorially displays the major assemblies of the FMPS. The equipment was identified to the level of indenture necessary to establic the reliability and maintainability characteristics suitable for obtaining workload. This was adequate for the organization and DS level maintenance study since the FMPS is replaced as a unit at the organization level and the DS level merely operates a direct exchange program for the FMPS. The faulty complete FMPS is then sent to the GS level for fault isolation and repair or disposition (e.g., return to depot).

However, to perform the LOR analysis, the equipment had to be identified to a lower level of indenture. The

nomenclature of the work breakdown structure (WBS) of the FMPS design resulting from this analysis is listed in Table 7.2-2 along with the nomenclature of its replaceable units (RUs). An FMPS WBS block diagram is depicted in Figure 7.2-2 with the respective WBS number shown above each block. These are the replaceable assemblies (i.e., RUs). Included in Figure 7.2-2 is the suggested level of repair based on the non-economic analysis that served as the LOR reference system. This reference system represents a maintenance philosophy that is comparable to the daylight TVMPS. As noted in the Figure 7.2-2 key, a notation in the upper left hand corner of an assembly is the remove and replace level and in the lower right hand corner, the repair The notation for the four possible levels of repair actions are:

0 = Organization

DS = Direct Support

GS = General Support

D = Depot

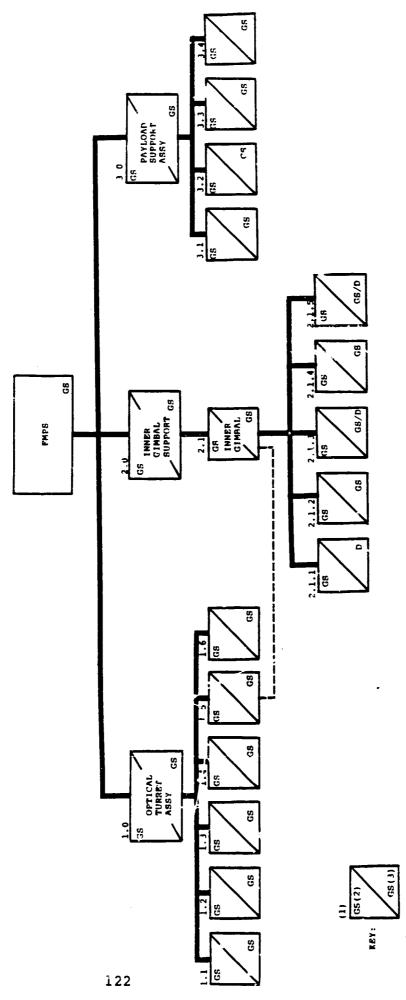
# 7.2.5 Non-economic Analysis

It will be noted that all the RU's are considered repairable at the GS level with the exception of the following units which are recommended as being depot repairable:

WBS	NOMENCLATURE	REPAIR LEVEL
1.1	Laser Transmitter	GS/D
1.6	Window Assembly	D
2.1.1	FLIR Receiver	D
2.1.3	Laser kange Receiver	GS/D
2.1.5	Gyro System	GS/D

Table 7.2-2 Work Breakdown Structure Nomenclature

ID CODE	NOMENCIATURE
1.0	Optical Turret Assembly
1.1	Laser Transmitter
1.2	Payload Processor Electronics
1.3	Turret Assembly
1.4	Outer Gimbal Drive System
1.5	Windscreen Assembly Outer Gimbal
1.6	Window Assembly
_	
2.0	Inner Gimbal/Support
2.1	Inner Gimbal
2.1.1	FLIR Receiver
2.1.2	Inner Gimbal Drive System
2.1.3	Laser Range Receiver
2.1.4	Miscellaneous Motor/Drive Electronics
2.1.5	Gyro System (Stabilization Electronics)
2.0	Daviland Current Agreeble
3.0	Payload Support Assembly
3.1	Access Cover
3.2	System Power Supply
3.3	Slipring Assembly
3.4	Azimuth Drive System



(i) Identification Code of Assembly (See Table 7.2-2 for nomenclature) (2) Level of Maintenance for Remove and Replace (3) Level of Maintenance for Repair (Repair may be remove and replace subassemblies)

The laser transmitter, the laser ranger and the gyroscope system are shown as having a possibility of repair at the GS level. The principal restriction against GS level repair will be the availability of a suitable testing capability. The Army's AN/USM-410 Electronic Quality Assurance Test Equipment (EQUATE) will be required to allow sufficient test capability. However, the mission payload system, both TV and PLIR, are not compatible with the AN/USM-410 core (Ref. 9). For example, considerable electro-optic (E-O) augmentation is required because the present AN/USM-410 core system has no provision for mounting, stimulating or measuring the output of E-O sensor units.

The FLIR payload and the composite type of optics required for a window assembly are not compatible with the USM-410 core test capability and a clean-room atmosphere is recommended for their handling and repair. Since these optical units contain multiple lenses they must be handled with care when removed from the FMPS to avoid exceeding specified "G" limitations. Also, these units require an optical test table with special fixtures for functional testing. The sensor elements of the FLIR, as well as the optics, can be easily damaged and contaminated by an inadequate clean-room atmosphere. For these reasons, repair at intermediate levels of maintenance (DS or GS) seems highly unlikely.

DS-level repair was eliminated as a viable alternative for the foregoing reasons as well as for the costs associated with the requirement for three times the amount of test equipment without a compensating reduction in spares. This completed the non-economics portion of the analysis.

An economic analysis was then accomplished despite the limited availability of cost data. The rationale for the

validity of the results is based upon the fact that the economic analysis involves comparability analysis of costs between the selected LOR alternatives. Therefore, as long as the costs are reasonable in respect to each other for a given alternative, use of those same costs for a second alternative will provide a valid comparison.

#### 7.2.6 Economic Analysis

A DRC developed life cycle cost (LCC) model entitled the reliability, maintainability, and cost model (RMCM) was used to compare LOR alternatives (Ref. 10). The RMCM is an interactive accounting type model that accommodates all LCC parameters while providing maximum visibility into the operational and support (O&S) costs. The RMCM equations used were tailored to those LCC elements which are influenced by LOR considerations. Cost values not specific to LOR considerations were ignored. Therefore, there was no intent to obtain "bottom line" LCC values, but rather, to obtain O&S costs that could be compared to provide additional information for the "OR analyses.

The following elements were computed using constant 1982 dollar values:

#### CODE LCC COST ELEMENT

# Non-recurring costs:

CPTI	Cost of	Initial Maintenance Personnel Training
CSPI	Cost of	Spares Investment
CDRI	Cost of	Initial Depot Support Equipment
CSEI	Cost of	Base Level Support Equipment Investment
CJGI	Cost of	Initial Maintenance Manuals

# CIMI Cost of Initial Inventory Management

#### Recurring Costs:

CIM

```
COM Cost of On-Equipment Maintenance (crew/organization)
CSM Cost of Intermediate Shop Maintenance (DS/GS)
CPT Cost of Maintenance Personnel Training
CSP Cost of Replacement Spares
CDR Cost of Depot Maintenance
CSE Cost of Maintaining Support Equipment
CJG Cost of Supporting Maintenance Manuals
```

The LOR alternatives chosen to make the economic analyses were:

Cost of Inventory Management

- (1) The reference system as described in the previous section. This is principally GS level repair of RU's except for the FLIR, lasers, gyros, and optics which are repaired at the depct.
- (2) Depot level maintenance for the three major assemblies, with only unit test and removal of these assemblies from the FMPS at GS level.
- (3) GS level test and repair permissable for all assemblies. It should be noted that this may not be a viable alternative, as previously discussed, but provides a lower limit of cost associated with pipeline sparing. The cost of test equipment procurement will, however, increase.

The results of the LCC model runs for the three alternatives are shown in Table 7.2-3. The procurement cost is provided

Table 7.2-3 LCC Comparison of LOR Alternatives

LOR Alternative (\$000)

Cost Element	#1 GS/Depot Mix	#2 Depot	#3 GS
• Non-recurring (Initial) Costs:			
Maintenance Personnel Training	0	0	0
Spares Investment	5,896	13,885	3,215
Depot Support Equipment	440	880	440
Site Level Support Equipment	1,820	105	2,100
Maintenance Manuals	263	30	263
Inventory Management	42	9	42
• Total Non-recurring Costs (NRC)	8,461	14,909	6,060
• NRC % of LCC (including procure-ment)	7.8%	10.1%	10.1%
• Recurring (O&S) Costs:			
On-Equipment Maintenance	11,070	11,070	11,070
GS Level Shop Maintenance	1,142	627	1,880
Maintenance Personnel Training	293	274	320
Replacement Spares	4,538	4,538	4,538
Depot Maintenance	47,299	81,059	39
Maintain Support Equipment	560	28	560
Support Maintenance Manuals	99	11	99
Inventory Management	207	44	207
• Total Recurring Cost (RC)	65,208	97,651	18,713
• RC % of LCC (including procure- ment)	60%	66.2%	31.3%
• Total RC and NRC	73,669	112,560	24,773
• Procurement	34,944	34,944	34,944
• Total Computed LCC	108,613	147,504	59,717

in Table 7.2-3 to serve as a comparative value to the LOR involved cost elements. The estimated procurement costs of \$34,944,000 is based on a system cost of \$124,800 with a total force of 280 FMPS units. Integration, installation and delivery costs are not considered.

The GS/Depot repair alternative mix, although not the least costly, is the recommended alternative since it is also the most feasible with respect to non-economic parameters. The Depot repair alternative is the most costly due to cost of sparing major assemblies. The GS repair alternative although the probable least cost (the cost of modifying the SE may be substantially higher than estimated) is offset by the non-economic considerations. The facilities cost associated with providing a clean room capability would, also, have to be estimated. The cost differential to allow these considerations is theoretically \$50,000,000 for this limited tradeoff study.

#### SECTION 8 - COMPARATIVE ANALYSIS AND RESULTS

This section contains a discussion of the results of this particular study and how they compare with findings of the initial RPV study. Based upon the results of this study recommendations for further actions are contained at the end of this section.

# 8.1 MAJOR DIFFERENCES BETWEEN THE 12 HOUR SCENARIO AND THE 24 HOUR SCENARIO

The initial MPT analysis of the Army RPV involved examination of the human resources supportability requirements for the RPV section operating in a 12 hour daylight scenario. Thus, tactical flight operations were confined to that 12 hour period. Additionally, only a single AV payload package (the TVMPS) was considered.

This study involved expanding the scenario to include around the clock operations, 24 hours—a—day. Additionally, an alternative or second mission—payload system was added for the AV. This was the FLIR subsystem. Therefore, not only did the operations envelope have to be expanded to consider impacts upon manpower requirements of this longer flying day but the operator and maintainer tasks associated with the additional FLIR equipment also had to be added.

Finally, during the period from completion of the first analysis until beginning the second analysis, additional information and documentation regarding the RPV system was received from the Program Office. This information included:

- O The Final Qualitative and Quantitative Personnel Requirements Information (FQQPRI). This information added and deleted certain MOSs from the RPV section as well as the direct support maintenance elements used for the first RPV study.
- o Basis of Issue Plan Feeder Data (BOIPFD). This information provided cost data on major RPV subsystems and was used extensively during the tradeoff analysis conducted during this study.
- Logistics Support Analysis Record (LSAR) summaries from Lockheed Missile and Space Company. These summaries were significantly more complete than the LSAR's used during the initial study. While only 30% of the contractor's LSA was completed by workload for the first study, approximately 70% of the LSA was completed for this study. However, Lockheed's LSAR summaries reflected only daytime operation and did not include any FLIR/nighttime operator and maintainer tasks.
- o Scenario data necessary to completely define the RPV sections operation during a 24 hour period. In places where this data was not complete, DRC analysts coordinated with RPV Program Office personnal to define parameters necessary to complete this study.
- o Course material and programs of instruction previously requested but not available for use during the initial study. Receipt of this material allowed an update of proposed training

requirements and more accurately reflected training information used in the reference system.

Based upon those major data sources listed towe, along with other study information, the RPV Consolidated Data Base (CDE) was updated and configured for the 24 hour scenario alternative payload analysis. It should be noted that expanding the initial analysis from a 12 hour scenario to a 24 hour scenario does not involve simply multiplying results of the first study by a factor of two. While this may seem obvious, more importantly is the fact that some major changes in the grade and MOS structure of the RPV section occurred, as well as the equipment change resulting from adding the FLIR. Additionally, the 26B MOS Weapons Support Radar Remairer was added at the direct support maintenance level. Thus, these factors were all considered as part of this follow on study.

#### 8.2 COMPARATIVE MANPOWER PERSONNEL AND TRAINING

Comparisons of results between the two studies will concentrate on the areas of manpower, personnel and training requirements. While each study contained impact and tradeoff analyses, these assessments were peculiar to the specific study and as such, offer no real basis for comparison.

#### 8.2.1 Manpower Requirements

Shown in Tables 8.2-1 through 8.2-4 are the manpower requirements of the baseline and reference systems for the RPV section under the 12 hour scenario. These results are

TABLE 8.2-1 (12 Hour Scenaric)
MANPOWER REQUIREMENTS, BASELINE SYSTEM
0&0 CONCEPT\*

MOS	ASI	PAYGRADE	RPV SECTION	RPV PLATOON	ARMY TOTAL
<b>21</b> 1B		WO	1	4	5จ์
13T30		E6	1	4	56
13T20		E5	2	8	112
13110		<b>E4</b>	2	8	112
13T10		E3	3	12	168
13T10		E2	2	8	112
13T20	P9	E5	1	4	56
13T10	P9	E4	1	4	56
63B10	•	E4	1	4	56_
				•	
TOTAL			14	56	784

<sup>\*</sup> RPV Platoon Headquarters Requirements are not included in this table.

TABLE 8.2-2 (12 Hour Scenario)
MANPOWER REQUIREMENTS, BASELINE SYSTEM
SUSTAINED CONCEPT \*

MOS	ASI	PAYGRADE	RPV SECTION	RPV PLATOON	ARMY TOTAL
211B		WO	1	4	56
13T30		E6	1	4	56
13T20		E5	2	8	112
13T10		E4	2	8	112
13T10		E3	3	12	168
13T10		E2	1	4	56
13T20	P9	<b>E</b> 5	1	4	56
13T10	P9	E4	1	4	56
63B		<b>E4</b>	_1_	4	6
TOTAL			13	52	728*

<sup>\*</sup> RPV Platoon Headquarters Requirements are not included in this table.

TABLE 8.2-3 (12 Hour Scenario)

MANPOWER REQUIREMENTS, REFERENCE SYSTEM

O&O CONCEPT \*

MOS	ASI	PAYGRADE	RPV SECTION	RPV PLATOON	ARMY TOTAL
211B		WO	1	4	56
13T30		E6	1	4	56
13T20		E5	2	8	112
13T10		E4	2	8	112
13T10		E3	3	12	168
13T10		E2	2	8	112
13T10	P <b>9</b>	E5	1	4	56
13T10	P9	E4	1	· 4	56
31V10		E 4	1	4	<b>5</b> 6 .
63B10		E4	_1	4	56
JATOT			15	60	840

<sup>\*</sup> RP: Platoon Headquarters Requirements are not included in this table.

TABLE 8.2-4 ('2 Hour Scenario)

MANPOWER REQUIREME: 3, REFERENCE SYSTEM

SUSTAINED CONCEPT \*

MOS	ASI	PAYGRADE	RPV SECTION	RPV PLATOON	ARMY TOTAL
211B		WO	1	4	56
13T30		E6	1	4	56
13T20		<b>E</b> 5	2	8	112
13T10		E4	2	8	112
13T10		E3	3 .	12	168
13T10		E2	1	4	56
13T20	P9	E5	1	4	56
13T10	P <b>9</b>	E4	1	4	56
31V10		E4	1	Ÿ	5€
63B10		E4	1	4	56
TOTAL			14	56	784

<sup>\*</sup> RPV Platoon Headquarters Requirements are not included in this table.

driven exclusively by operator and maintainer workload requirements. Therefore, equipments for each configuration expressly defined the operator and maintainer tasks, and thus the workload each section position had to accomplish.

The manpower requirements for the 24 hour scenario are shown in Table 8.2-5. These requirements, unlike those of the 12 hour scenario, are driven by contingency manning considerations. Contingency manning dictates that all positions of the RPV section be manned on an around-the-clock basis. Therefore, strict workload considerations no longer are the main factor in determining section positions.

Finally, the section workload distribution is shown for the two scenarios in Figure 8.2-1 through 8.2-4. Figures 8.2-1 and 8.2-2 apply to the 12 hour scenar > while Figures 8.2-3 and 8.2-4 apply to the 24 hour scena . It can be seen that there are two main difference in these studies. Operational Manning (OM) for the 12 hor scenario consumed about 65% of the sections total workload. OM workload for the 24 hour scenario totaled approximately 78%. This large increase is directly related to the increase in flight operations and its associated supporting activities. Additionally, Preventive Maintenance (PM) and Corrective Maintenance (CM) workload decreases from 17% and 4%, respectively, for the 12 hour scenario to 14% and 2%, respectively, for the 24 hour scenario. This decrease is attributable to the fact that the 63B Wheeled Vehicle Mechanic has been moved from the section level to the organizational supporting unit. Thus, the workload associated with this position also shifts to the organizational support unit.

RPV Section Manpower Requirements Summary by Crew Position for 24 Hour - FLIR Operations Table 8.2-5

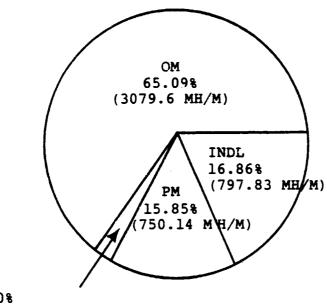
		-	*	WORKLOAD			OPERATOR POSITIONS	
CREW POSITION	MOS/SI ASI	PAYGRADE	PC 080	POSITIONS SUSTAINED	FQQPR1	three Shifts	3 SHIFT GCS 2 SHIFT OUTSIDE	3 SHIFT GCS 2 SHIFT OUTSIDE SHARED POSITION
Mission	21180	0%	٠,	1	1	1.		1
Commander	13T40 13T30	67 86					<b>-</b> -	
Air Vehicle	13T20	ES	7		1	1	1	1
Operator	13T10	М 0		-4 <i>-</i> -			<b></b> -	-4 -
	01161	a	-	1	Ţ	<b>,</b>	T	-
Mission	13110	E4	-	1	1 (ES)	7	1	L/R
Payload Operator	13T10 13T10	ខេង ខេង					<b>.</b>	1 + 4 hr. L/R Team 1 + 4 hr. L/R Team
Generator	52010	E4	1	1	1	1	1	
Operator	52D10 52D10	E2 E2	02	1 <sub>2</sub> 1		- -	. 0	0
Launch/	13T30	E6	-	1	7	]	1	1
Recovery Team Leader	13T20 13T20 P9	23 23			<b>-</b> -		l (see L/R Team)	l (see L/R Team)
Launch/	13T10 P9	F.4	-	1	1	1	1	
Recovery Team #1	13T10 13T10	E E		1 0				1 1
	13r10	E2	~	1	1	1	1	1
Launch	13T10	E4	0	0		1	1	
Recovery Team #2	13710	E 33		0	(13T10 P9)	-	(13T20 P9) 1	(13T20 F9) *GCS Operators
	13410	£.	C	c	c	-	_	Shared Position
	13710	E2	0	0	0	1	1	1
Launch	13710	E4.	0	0	0	1	0	0
Recovery	13T10 13T10	ലെല	00	00	c o		c o	0 0
	13T10	E2	0	0	0	1	0	0
TOTAL			18	17	, 18	27	. 213	203

# Table 8.2.5 (Continued)

- There is no difference in operator shift position requirements between 040 and sustained scenarios as they both cover 24 hour periods. (1) NOTE:
- Decision not to include a third 52D position assumes the 13T10 is capable of manning the generator operation station part time with a minimum of on-the-job-training (OJT). (3)
- Allows for availability of vehicle drivers to make resupply, site survey and RPV briefing trips offsite. (3)

Figure 8.2-1 RPV Section Workload Distribution (12 Hour Scenario)

BASELINE - O&O SCENARIO



CM / 2.20% (103.88 MH/M)

BASELINE - SUSTAINED

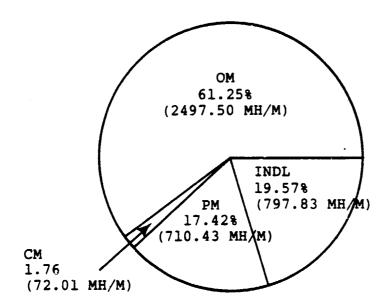
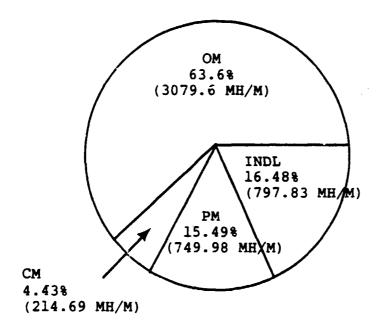


Figure 8.2-2 RPV Section Workload Distribution (12 Hour Scenario)

REFERENCE - O&O SCENARIO



REFERENCE - SUSTAINED SCENARIO

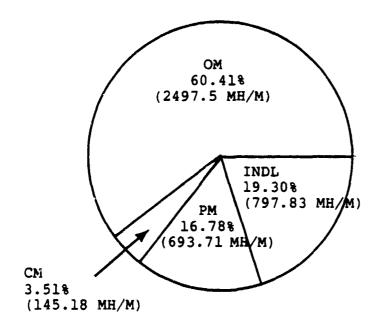
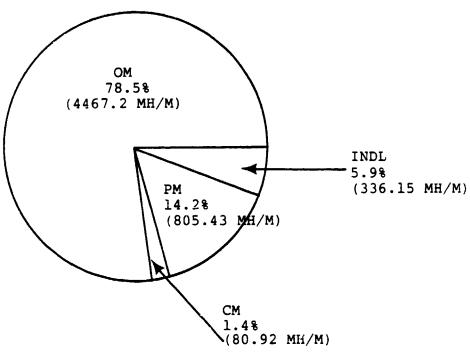


Figure 8.2-3 RFV Section Workload Distribution (24 Hour Scenario)

BASELINE - O&O SCENARIO



BASELINE - SUSTAINED

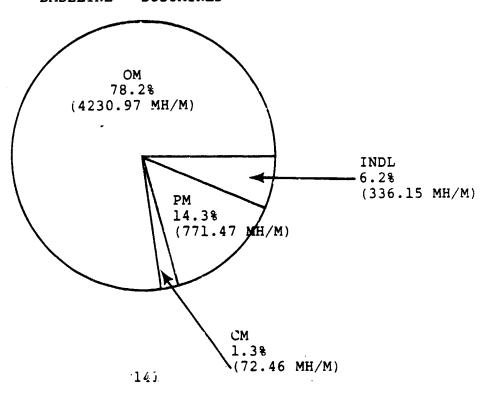
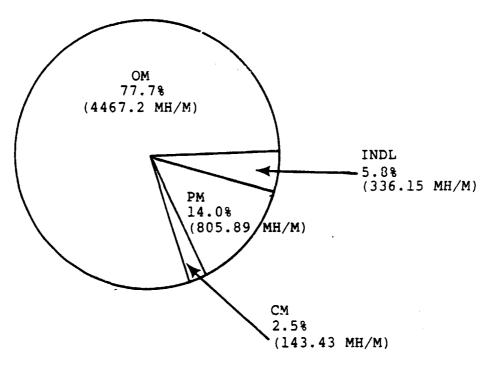
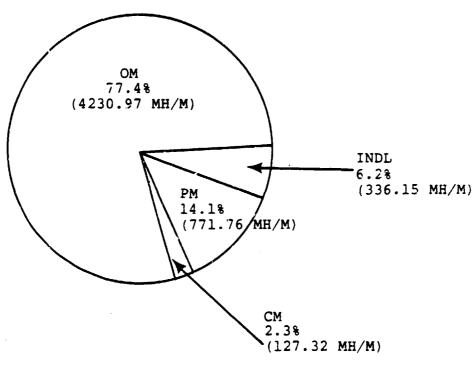


Figure 8.2-4
RPV Section Workload Distribution
(24 Hour Scenario)

REFERENCE - O&O SCENARIO



REFERENCE - SUSTAINED



#### 8.2.2 Personnel Requirements

A comparison of the personnel requirements of the RPV system including the platoon headquarters personnel, is shown in Tables 8.2-6 and 8.2-7 for the 12 hour and 24 hour scenarios, respectively. As can be seen, a large increase (145%) in personnel requirements for the 24 hour scenario This is primarily due to two main factors. First, the contingency manning requirement of the 24 hour scenario dictates that a greater number of positions will be found at the section level. However, another significant reason as to why personnel requirements increase so dramatically lies in the fact that an E7, 13T40, was added to each RPV section by the FQQPRI. Thus many personnel are required in the pipeline to "grow" this E7. However, the addition of the E7 is very beneficial since it greatly reduces much of the skill overload considerations which were present during the first study. (Skill overload involves lower skill level personnel being required to perform higher level skills.)

## 8.2.3 Training Requirements

The impact of the 24 hour scenario on training will result in the addition of only three hours of training to the entry level operator course (XXX-13T10) and no addition of training to the organization and direct support echelon maintenance courses. This is the result of adding only the FLIR equipment itself to the previous RPV system configuration. Therefore, the effect of changing from a 12 hour to a 24 hour scenario is minimal with respect to training.

Table 8.2-6 Personnel Requirements by MOS (12 Hour Scenario) (Includes Platoon Headquarters Requirements)

	Refe	erence	Base	line
MOS	Sustained	0&0	Sustained	0&0
13T	1,043	1,177	1,043	1,177
13T*	989	991	989	991
13T P9	350	360	360	360
26L	59	59	59	59
26T	31	31	-	_
31E	44	44	44	44
31J	34	34	34	34
31S	51	51	51	51
31V	176	176	-	_
34Y	97	97	97	97
35E	90	90	90	90
35H	82	82	82	82
36H	42	42	42	42
41B	42	42	42	42
41C	44	44	44	44
43M	27	27	27	27
44B	ō9	69	69	69
45B	27	27	27	27
45G	47	47	-	-
52C	12.	125	125	125
52D	46	46	46	46
63B	139	139	139	139
63G	111	111	49	49
63J	31	31	31	31
63W	115	115	115	115

<sup>\*</sup> Does not include Platoon Headquarters 13T requirements.

Table 8.2-7. Personnel Requirements by MOS (24 Hour Scenario) (Includes Platoon Headquarters Requirements)

	Referen	nce	Baseline		
MOS	Sustained	3/2 Shift	Sustained	3/2 Shift	FQQPRI RPV Section
13T	1478	2522	1478	2522	1826
13T*	1391	2435	1391	2435	1739
13TP9	360	360	360	360	40,
268	39	. 39	39	39	
26L	59	59	59	59	
26 <b>T</b>	31	31	-	•	
31 <b>E</b>	44	44	44	44	
31J	34	34	34	34	
315	51	51	51	51	
34Y	97	97	97	97	
35E	90	90	90	90	
35H	82	82	82 .	82	
36H	43	43	43	43	
41B	42	42	42	42	
41C	44	44	44	44	•
43M	27	27	27	27	
44B	69	69	69	69	
45B	27	27	27	27 -	
45G	47	47	-	-	
52C	125	125	125	125	
52D	247	293	247	293	182
63G	111	111	111	111	
63J	31	31	31	31	
6 3 W	147	147	115	115	

<sup>\*</sup>Does not include Platoon Headquarters 13T requirements.

Changes resulting from the FQOPRI updating, however, are quite significant. The RPV Warrant Officer (211B) will require the addition of 475.5 hours of maintenance training in the reference system and 332.9 additional hours in the baseline system. This will accommodate his non-required maintenance instruction. Use of built-in-test (BIT) equipment provides the larger difference in training course length.

The FQQPRI also requires the addition of one new direct support MOS, Weapons Support Radar Repaire: (26B). Training of maintenance tas's to support new FLIR equipment will require an additional 1.5 mandays of training for this MOS.

#### 8.3 RESULTS

The thrust of this study concentrated on the human resource requirements of the RPV section. Important considerations involved an operational scenario which covered an entire 24 hour period, as well as the additional equipment necessary to support around-the-clock operations. This additional equipment consisted of the FMPS.

Table 8.3-1 presents the results of the study with respect to the reference and baseline systems analyzed for the RPV. Some of the more specific results are contained in the following paragraphs, and were discussed in greater detail in the appropriate section of this report.

## Mission

o The equipment which defines the baseline RPV section is adequate to perform those target

Table 8.3-1. RPV System Summary

# MANPOWER

Level	Tempo	Requirements			
		Section	Platoon	Army	
Crew	Workload Driven				
	• 0&0	18	72	1008	
	• Sustained	17	68	952	
	Contingency Manning				
	• 3 Shift	27	108	1512	
	• 2 Outside/ 3 Inside	21	44	616	
	• 3/2 Shift	20	40	560	
	FQQPRI	18	72	1008	
Direct	Baseline	-	20	280	
Support	Reference	_	23	322	

# PERSONNEL

	Reference	System	Baseline	System
	Sustained	3/2 Shift	Sustained	3/2 Shift
Number of MOS	23	23	21	21
Personnel Requirement*	3,325	4,361	3,216	4,305
Annual Recruit Rate	1,243	1,590	1,200	1,546
TRAINING				
Annual Training Man-Days	86,550	106,923	75,507	93,870
Annual Instructo Requirements	r 95.9	112.0	83.1	98.4

<sup>\*</sup>Includes Platoon Headquarters Personnel

acquisition missions assigned to the RPV section operating in a 24 hour-a-day configuration.

## System Analys's

o FQQPRI changes of moving corrective maintenance (CM) requirements to an organizational support unit transfer significant maintenance workload to that supporting unit.

## Manpower

- o Optimal manning for the 24 hour-a-day scenario is three shifts in the GCS and two shifts outside the GCS with outside workload shared between GCS and outside personnel (3/2 shifts). This contingency manning alternative requires 20 positions.
- o Manpower requirements of the RPV system operating around the clock are driven more by contingency manning requirements than by workload considerations.

### Personnel

o The 13T10 MOS availability for the RPV system projects a 31% personnel shortfall at IOC (based on FY 1984 estimates).

## Training

o The requirement exists for both a system specific organizational maintenance MOS (rather than ASI P9) and a direct support maintenance MOS. This is based on the amount of training required by the P9

and the criticality of built-in-test (BIT) to perform to design specifications.

o The FQQPRI addition of the 13T40 at the section level greatly reduces the RPV skill overload which previously existed.

## Impact

o RPV manpower requirements at IOC include MOS's already projected using Fiscal 1984 estimates to be in short supply. Among the most critical of these are:

MOS	<u>Shortfall</u>
13Т	31%
26B	24%
63J	24%
26L	19 %
63W	19 %

## Tradeoffs

The tradeoff selected was an examination of the maintenance tasks associated with a the FLIR mission payload subsystem (FMPS) at the direct support (DS), general support (GS), and depot maintenance levels. The tradeoffs, thus, became a level of repair (LOR) analysis for the FMPS. Both a non-economic and an economic LOR analysis were conducted. Results indicate that a GS/Depot repair mix is the recommended alternative although not necessarily the least cost.

#### 8.4 CONCLUSIONS AND RECOMMENDATIONS

The RPV section, while operating in a 24 hour-a-day scenario and utilizing both TVMPS and FMPS payload packages, is optimally manned if operated with 3 shifts in the GCS and 2 shifts outside the GCS with outside workload shared. This manning configuration requires a total of 20 personnel at the section level, bringing each section position to 81% of workload capacity. Hence, the configuration best satisfies all workload and contingency manning requirements.

Based upon the study's results and above conclusion, a number of recommendations are made. First, a manpower, personnel and training and requirements assessment of an RPV section deployed in the central launch configuration (ground control station and remote ground terminal forward and support elements such as Launcher Subsystem, Subsystem, and associated handling and maintenance equipment in the rear area) should be conducted. The initial DRC study identified the possibility that workload associated with maintenance actions at the section level could be incorporated, or shifted, into existing direct support positions, or better performed in a rear area. This present identified all operator and maintainer associated with a 24 hour-a-day operation utilizing FMPS and The proposed investigation could also include a sensitivity analysis regarding the level at which operational and maintenance workload associated with this central launch concept is performed. This level of repair analysis should include depot level maintenance considerations.

Second, a detailed Training Resource Requirements Analysis (TRRA) should be performed to evaluate the training required by the 13TXX MOS and 13TXXP9 MOS. Having already identified the tasks and equipment secessary for the RPV MOS 13TXX personnel to perform their duties, a detailed TRRA would provide the interface between the task requirements of operators and maintainers and proposed simulators and training devices. A detailed TRRA, by developing the necessary courses of instruction for the RPV operators and maintainers, would greatly assist in finalizing the RPV Army Training Plan.

Third, an assessment of the operation of the RPV section, deployed in a nuclear, biological and chemical (NBC) environment should be conducted. Such an analysis would verify time to perform designated operator and maintainer tasks as well as determine the effectiveness of operating under NBC conditions. Additionally, as an integral part of the assessment, a human factors analysis of the ground control station should be performed. Operating within this controlled environment for extended periods of time would be key to the overall NBC evaluation.

#### BIBLIOGRAPHY/REFERENCES

Upwards of 280 documents have been compiled in the library portion of DRC's consolidated data base concerning remotely piloted vehicle (RPV) technology. Most of these documents were listed in the bibliography for the previous RPV study. In the interest of brevity, the only documents listed below are those that provided significant information for this study and are major references, i.e., those sources contributing directly to this front-end analysis technology.

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## GLOSSARY OF DEFINITIONS/ACRONYMS

## DEFINITIONS

Reference System: The reference system is a notional design configured to approximate a proposed major system or subsystem. The reference system meets mission/programmatic requirements specified for the proposed system in its Justification for Major System New Start (JMSMS) and/or Operational Requirement. The reference system is a composite of hardware and software components selected from current DoD/NATO inventories. Wherever possible, selected equipment should be mature so as to have reliability maintainability, operating hour, and manhour data available for analysis.

Baseline System: Like the reference system, the baseline system is a notional design configured to approximate a proposed major system or subsystems. The baseline system also meets mission/programmatic requirements specified for the proposed system in its JMSNS and/or Operational Requirement and is described in terms of its constituent hardware/software components. However, the baseline system can also include modified, improved, or new design features reflecting technological advances available before the proposed system's IOC. Thus, unlike the reference system, the baseline system can incorporate subsystems for which only laboratory or test data are available.

## ACRONYMS

AFM Air Force Manual

AFREG Air Force Regulation

AIT Advanced Individual Training

AR Army Regulation

AR Availability Ratio

ASI Additional Skill Indicator

ASARC Army System Acquisition Review Council

AV Air Vehicle

AVIM Aviation Intermediate Maintenance

AVUM Aviation Unit Maintenance

BIT Built-in-test

BOIP Basis of Issue Plan

BOIPFD Basis of Issue Plan Feeder Data

BTC Basic Training Course

CDB Consolidated Data Base

CFE Contractor Furnished Equipment

CM Corrective Maintenance

COI Course of Instruction

COPO Chief of Personnel Operations

COTR Contract Office Technical Representative

MDC Defense Manpower Data Center

DoD Department of Defense

DRC Dynamics Research Corporation

DS Direct Support

DT/OT Development Test/Operational Test

ECMF Enlisted Career Management Field

EMF Enlisted Master File

FEAT Front End Analysis Technology

FLIR Forward Looking Infrared

FM Failure Mode

FMECA Forward Modes Effects Criticality

Analysis

FMPS FLIR Mission Payload Subsystem

FQQPRI Final Qualitative and Quantitative

Personnel Requirements Information

FY Fiscal Year

GCS Ground Control Station

GFE Government Furnished Equipment

HQ Headquarters

ILSP Integrated Logistic Support Plan

IMAGES Interactive Manpower Aggregation

Estimation System

IM PACT Interactive Manpower-Personnel

Assessment and Correlation Technology

INDL Indirect Labor

IOC Initial Operational Capability

JMSNS Justification for Major System New Start

JPL Jet Propulsion Laboratory

KW Kilowatt

LCN Logistic Control Number

LOR Level of Repair

LS Launcher Subsystem

LSA Logistic Support Analysis

LSAR Logistic Support Analysis Record

MAA Mission Area Analysis

MAC Maintenance Allocation Chart

MACRIT Manpower Authorization Criteria

MEP Mission Event Profile

MH Manhour

MILPERCEN U.S. Army Military Personnel Center

MOS Military Occupational Specialty

MPT Manpower, Personnel and Training

MRA Manpower Requirements Analysis

MRC Maintenance Requirements Card

MTTR Mean Time to Repair

MS Maintenance Shelter

NAMSO Navy Maintenance Support Office

NATO North Atlantic Treaty Organization

NCOES Non Commissioned Officer Education

System

NETP New Equipment Training Plan

O&O Organizational and Operational

OICTP Outline of Individual and Collective

Training Plan

OM Operational Manning

OP-AUDIT Operational Audit

OPNAVINST Chief of Naval Operations Instruction

OT Operational Test

PERSACS Personnel Structure and Composition

System

PM Preventive Maintenance

PMCS Preventive Maintenance Checks and

Services

PM Project Manager

POI Program of Instruction

PRA Personnel Requirements Analysis

P3M Personnel Policy Project Model

QQPRI Qualitative and Quantitative Personnel

Requirements Information

RAM Reliability, Availability, and

Maintainability

R&M Reliability and Maintainability

RGT Remote Ground Terminal

ROC Required Operational Capability

RPV Remotely Piloted Vehicle

RS Recovery System

SDC Sample Data Collection

SOJT Supervised On-the-Job Training

TAB Target Acquisition Battery

TM Technical Manual

TRADOC U.S. Army Training and Doctrine Command

TRRA Training Resource Requirements Analysis

TTHS	Trainees, Transients, Holdeen and Students
TVMPS	Television Mission Payload Subsystem
WQEC	Weapon Quality Engineering Center
WSAP	Weapon System Acquisition Process
3-M	Maintenance and Material Management

# GENERAL SCENARIO - MULTIPLE PAYLOAD SYSTEMS O&O CONCEPT - 24 EOUR PER DAY OPERATION

- 1. Move site once a day.
- 2. Section selects new site 10% of the time.
- 3. RPV section has responsibility for own resupply functions.
- Average distance moved between sites is 10 miles (15KM).
- 5. Average highway sperd 25 MPH due to weather, road conditions, and time of day/night.
- 6. Five AV flights per day (three are FLIR, two are daylight TV) in a 24 hour period; 365 days/year; flight time 3.0 hours.
  - a. 1 MPS change per week to marry proper MPS with operational AV.
- 7. AV Operating Hours

1825 flights/year at 3 hours	5475.0 hr/yr
1825 flights/wear at .17 hour power up on rail time	310.5 hr/yr
TOTAL	5785.5 hr/yr

- 8. Average on-site distance traveled between emplacements 200 meters at 5 MPH.
- 9. Section commanders truck used for adultional tasks of:
  - a. Transportation of section site selection team.
  - b. On-site administrative runs of 0.8 km round-trip distance on an average of three times per day.
  - c. Every other day used for resupply runs of 20 km round trip.
  - d. Daily briefing runs of 20 km round trip.
- 10. Cargo vehicle makes one resupply run every other day of 50 km round trip.
- 11. Launcher and recovery systems are deployed for each launch then both return to shelter. Round trip distance is 0.4 km.
- 12. Recovery system redeployed for recovery for each returning flight.
- 13. AV handler (AVH) system operates in support of each launch, then proceeds to recovery site to support possible recovery at launch. AVH also supports each recovery and all AV handling not related to AV flights.

## 14. Ground Control Station operating hours/year

- a. Environmental support equipment for the GCS-8522.7 hr/yr total assuming heating and cooling systems operate 4261.4 hr each (1/2 the time).
- b. Off-site voice radio system (to HQ) 8522.7 hr/yr (includes maintenance time).

NOTE: a and b are based on a 8,760 hr/yr less 237.3 hours associated with site moves.

- c. All other GCS equipment 8577.5 hr (365 days of operations) per year; 24 hour operating window per day less emplacement/ displacement time modified for 30 minute set up/secure time.
- d. RGT operating time 8577.5 hr/yr. Same rationale as for GCS equipment noted in sub-paragraph c above.

## 15. Generator Operations

- a. 1.5KW RGT generators operating hours same as for RGT; 8577.5 hr/yr. NOTE: Both generators are required during operating periods due to critical nature of RGT.
- b. 30KW generator operating time 8577.5 hr/yr per generator. This assumes each generator operates all the time due to 90 second power recovery time for the GCS equipment.

- 16. Mission planning time, exclusive of data recording and entry time, totaled 48 minutes per flight for a 30 waypoint mission. This total is based on 20 minutes analysis time plus a 70% learning curve for waypoint development with initial waypoint construction taking 3 minutes.
- 17. The RPV site is completely set up (100% site improvement) all of the time.
- 18. RPV administrative report workload consists of supervision, evaluation, and minimum reporting to satisfy necessary data inputs for higher echelons.
- 19. A direct support maintenance element supports four RPV sections.

## GENERAL SCENARIO - MULTIPLE PAYLOAD SYSTEMS SUSTAINED TEMPO - 24 HOUR PER DAY OPERATION

- 1. Five flights per day (three are FLIR, two are daylight TV Ops). Each AV flight is scheduled for three hours in the air. Total daily operations window is 24 hours.
- Weather/battle area conditions preclude 20% of the flights from being launched.
- 3. Battle AV losses are 0.83 per day. Miscellaneous AV losses are 0.33 per day. These values reflect a straight line increase from the 12 hour scenario.
- 4. Losses result in a 15% increase in launches.
- 5. The recovery system deploys for an average of 90% of the launches and 100% of the AV returns.
- 6. All other scenario values are the same as for the O&O operating conditions.

## GENERAL SCENARIO - MULTIPLE PAYLOAD SYSTEMS REDUCED TEMPO - 24 HOUR PER DAY OPERATION

- 1. Average of 2.5 flights per day (1.5 are FLIR and 1.0 are daylight TV).
- 2. Daily battle loss = 0.42 AV's.
- 3. Daily miscellaneous loss = 0.17 AV's.
- 4. No increase in AV launches due to losses.
- 5. Recovery system deploys 70% of the time for launches.
- 6. AV flight hours = 912.5 hrs/yr. Total operational hours = 2892.6.
- 7. Site displacement occurs 5 times per week.
- 8. Daily operational power-up time is 23.6 hours; reduced from 24 hours due to displacement time.
- 9. Remaining values are the same as for sustained operations. With the exception of the number of flights, these values correspond to the 12 hour scenario factors.

# GENERAL SCENARIO - MULTIPLE PAYLOAD SYSTEMS SURGE TEMPO - 24 HOUR PER DAY OPERATION

- 1. Average of 6.5 flights per day (a maximum number of flights if there are to be two displacement cycles per day). (3.9 are FLIR, and 2.6 are daylight TV).
- 2. Flight frequency increase due to losses will be 30%.
- 3. Recovery system deploys for 80% of the launches.
- 4. AV flight hrs = 2375.5 hrs/yr. Total op hours = 7520.8.
- 5. Site displacement occurs twice a day.
- 6. Daily battle loss = 1.67 AV's.
- 7. Daily miscellaneous loss = 0.67 AV's.
- 8. Daily operating power-up time is 22.7 hours; reduced from 24 hours due to displacement time.
- 9. Remaining values are the same as for sustained operations. With the exception of number of flights, these values correspond to the 12 hour scenario factors.

# APPENDIX B MANPOWER REQUIREMENTS ANALYSIS

## B.1 IMAGES MODEL DATA FILE CODES

This appendix reflects the codes used in the computerized workload and manpower files. The interrelationship between fields as well as the field lengths dictated these codes.

Table B.1-1 illustrates the input records of the Interactive Manpower Aggregation Estimation System (IMAGES) workload files. One line constitutes one record. The codes used in each column of Table B.1-1, which contains a data element, are described as follows:

Description	Column	
	-	
Activity	(1)	
Workload Category	(2)	
Task	(3)	
Subtask	(4)	
MOS	(5)	
Grade/Skill Level	(6)	
Logistic Control Number	(7)	

### B.2 RPV MANPOWER TASK TAXONOMY

Table B.1-1 is a listing of the baseline FLIR system manpower task taxonomy for an RPV section.

Once the RPV generic function/task networks were established, tasks were assigned to humans, machines, and software. Those tasks assigned to humans were then organized into baseline and reference system manpower task taxonomies for the RPV section. A qualitative task-by-task analysis was performed on the taxonomies to assign the lowest paygrade and skill level within an MOS capable of performing the task. AR 611-201 and Soldiers Manuals were key references in making this determination.

Table B.1-1. IMAGES Model Data File Codes and RPV Manpower Task Taxonomy

(1)	(2)	(3)	(4)	(5) (	(6) (7)
** RPV SE	BASELINE MMH **	* FLIR *** REL	SORT ** 02 AUG 1983	***	MMHLD302 ***
C MAIN		INSP		3T10	E4 XODAAR
C MAIN	PM GCS	svc	AIR BAFFLE 1	3T10	E4 XODAA9AH
C MAIN	PM GCS	TEST	CHECK GCS 1	3T10	E4 XOD
C MAIN	PM GCS	TEST	GCS DOOR 1	3T10	E4 XODAAR
C MAIN	PM LS	SVC	LAUNCH SYS DY 1	3T10	E4 OB
C MAIN	PM MS	SVC	PERS CBR X20 X		E21.7.6.2
C MAIN		SVC		3T10	E2K1.3.2.2.3.1
C MAIN		svc		3T10	E4 6C
C MAIN		INSP		2D10	E4 GGS
C MAIN		SVC		2D:0	E2K1.3.4.3.1.1.2
C MAIN		SVC		2D10	E2D1.6.3, 2.1
C MAIN		TEST		2010	E4K1.3.4.3.1.1.2
C MAIN		TEST		2D10	E2D1.6.3.2.1
C MAIN		TEST RPR		3710 3710	E4D1.6.3.2.1 E3XODAABAX
C MAIN		RPR		3T10	E2GPVX
C MAIN		RPR		3T10	E2GCS
C MAIN		RPR		3T10	E2GCV
C MAIN		RPR	•	3T10	EZGHV
C MAIN		RPR		3T10	E2GMV
C MAIN		RPR	-	3T10	E2GLV
C MAIN		RPR		3T10	EZGRV
DISP	OM	LOAD		2010	E2K3.2 7
DISP	OM	LOAD	30KW GEN 2 5	2D10	E2D3.2.7.1
DISP	OM	LOAD	30KW GEN 2 X	XXXX	E2DS, 217.1
DISP	GM	LOAD		3T10	E2K3. 2. 5
DISP	OM	LGAD		XXXX	E2D3. 2. 5. 1
DISP	OM	LOAD		3T10	E3K3. 2. 1
DISP	OM	LOAD		XXXX	E2K3. 2. 3
DISP	OM	LGAD		2010	E2D3. 2. 2
DISP	OM OM	LOAD		XXXX	E2D3. 2. 2
DISP	OM	LOAD		XXXX 3T10	E2K3. 2. 1 E3K3. 2. 4
DISP DISP	OM OM	LGAD LGAD		XXXX	E2K3. 2. 6
DISP	OM	POLICE		XXXX	E2D3. 1. 2. 8. 1. 1
DISP	OM	RENDEZVOUS		XXXX	E2K3. 3. 1
DISP	OM .	RENDEZVOUS		3T40	E7K3. 3. 2
DISP	OM	RENDEZVOUS	FORM CONVOY X7 X		E2K3. 3. 4
DISP	OM	RENDEZVOUS		XXXX	E2K3.3.2
DISP	OM	REPLACE	TARP BOW AVHX2 X	XXXX	E2K3.2.5
DISP	OM	REPLACE	TARP BOW CV X2 X	XXXX	E2D3.2.5.1
DISP	<del>o</del> m	REPLACE	TARP BOW LS X2 X		E2K3. 2. 3. 1
DISP	OM	REPLACE	TARP BOW RS X2 X		E2K3. 2. 4. 1
DISP	OM	REPLACE	TARP BOW SC X2 X		E2D3.2.6.1
DISP	GM 	REPLACE		XXXX	E2K3. 2. 1. 1
DISP	OM	SECURE		12D10	E2D3, 1, 2, 6, 3
DISP	GM GM	SECURE	AVH FOR MOV X2 1		E2K3.1.2.5
DISP	OM	SECURE		XXXX XXXX	E2D3.1.1.1 E2D3.1.1.1
DISP	om om	SECURE		XXXX	E203.1.1.1
DISP	OM	SECURE		XXXX	E203.1.1.1
DISP	OM ON	SECURE		XXXX	E2D3. 1. 1. 1
DISP	GM .	SECURE		XXXX	E2D3.1.1.1
DISP	OM .	SECURE		XXXX	E2D3.1.1.1
DISP	OM	SECURE		XXXX	E2D3.1.1.1
DISP	OM	SECURE		XXXX	E203.1.2.7.2
DISP	OM	SECURE	F6C X3 1	3710	E2K3, 1, 2, 7, 3

Table B.1-1 (Continued)

DISP	OM	SECURE	GCS ANTENNA X2 13T10	E2K3.1.2.1.2
DISP	OM	SECURE	GCS EQUIP 13T10	E4K3.1.2.1.1.1
DISP	OM	SECURE	GCS FOR MOV X3 13T10	E3K3.1.2.1.2
DISP	OM .	SL CURE	GND SITE IMPX2 XXXXX	E2K3.1.2.6.4.1
DISP	OM	SECURE	GND SYS IMP X2 XXXXX	E2D3.1.2.6.4
DISP	OM	SECURE	LS FOR MOVE X2 13T10	E3K3.1.2.2
DISP	OM	SECURE	MCPE XXXXX	E4D3.1.1.3
DISP	OM	SECURE	MCPE X3 XXXXX	E203.1.1.3
DISP	OM	SECURE	MS FOR MOVE X2 13T10PS	
DISP	OM	SECURE	PWR CABLES X2 XXXXX	E2D3.1.2.7.1.1
DISP	OM	SECURE	PWR CABLES X2 XXXXX	E2K3.1.2.7.1.1
DISP	OM	SECURE	RGT FOR MOVE 13T10	E4K3.1.2.1
DISP	OM	SECURE	RGT FOR MOVE XXXXX	E2K3.1.2.1
DISP	<b>GM</b>	SECURE	RS FOR MOVE X2 13T10	E3K3.1.2.3
DISP	OM	SECURE	RS GUIDE CABLE XXXXX	E2K3.1.2.7.3
DISP	OM	SECURE	SITE GUARD DEF XXXXX	XXD3. 1. 1. 5. 1
DISP	OM	SECURE	SITE SENSORS XXXXX	XXD3.1.1.4.5.2
DISP	OM	UNSET	SOKW & MATE XS XXXXX	E2K3. 2. 9
DISP	OM	UNSET	GCS X2 XXXXX	E2K3. 2. 8
DISP	OM	UNSET	MS TRUCK X2 XXXXX	E2D3. 2. 5. 1
DISP	OM .	UNSET	RGT AND MATEXS XXXXX	E2K3, 2, 6
DISP	OTS	SECURE	BERTHING FACLTYXXXXX	XXD3.1.1.4
DISP	OTS	SECURE	CBR DECOM XXXXX	XXD3.1.1.4
DISP	OTS	SECURE	MESS FAC XXXXX	XXD3.1.1.4
DISP	OTS	SECURE	OFFSITE COMM WRXXXXX	XXD3.1.1.4
DISP	OTS	SECURE	REST FAC XXXXX	XXD3, 1, 1, 4
DISP	OTS	SECURE	SANI FAC XXXXX	XXD3.1.1.4
DISP	OTS	SECURE	SHOWER FAC XXXXX	XXD3.1.1.4
EMP	INDL IMP	ADMIN	DRAFT CORRES 211B	W61.7.4.1.1
EMP	INDL IMP	ADMIN	GIVE MOS EXAMS 13T20	E51.7.3.4.4
EMP	INDL IMP	ADM I N	MAINT MAPS FILE13720	E51.7.4.1
EMP	INDL IMP	ADMIN	MAINT RECORDS 13T10	E41.7.4.2
EMP	INDL IMP	ADMIN	NON AV BRIEF 13T40	E71.7.4.1.1
EMP	INDL IMP	ADMIN	PERS COUNSEL13T40	E71.7.3.2
EMP	INDL IMP	ADMIN	PERS COUNSEL 2113	W01.7.3.2
EMP	INDL IMP	ADM I N	PERS EVALS 13T40	E71.7.3.1
EMP	INDL IMP	ADMIN	PERS EVALS 211B	W01.7.3.1
EMP	INDL IMP	ADMIN	PERS SUPERVISE 13T40	E71.7.3.2
EMP	INDL IMP	ADMIN	PERS SUPERVISE 211B	W61.7.3.2
EMP	INDL IMP	MAINT SUPPLY		9E51.7.2.3
EMP	INDL IMP	MAINT SUPPLY	SCDR RESUPPLY XXXXX	E2P1.7.2.1.1
EMP	INDL IMP	MAINT SUPPLY	STOW SUPPLYS XXXXX	E21.7.2.2
EMP	INDL IMP	MAINT SUPPLY	WORK PARTY X2 XXXXX	E2H1.6.9.4
EMP	INDL IMP	OPERATE	RESUPPLY CV 13T10	E3H1.7.2.1.2
EMP	INDL IMP	OPERATE	SC ONSITE XXXXX	E2E1.7.2.1.2
			<del>-</del>	
EMP	INDL IMP	PROV SANI	DIG FILL LATRN XXXXX	E2K1.6.9.3
EMP	INDL IMP	PROV SANI	DIG FILL TRASH XXXXX	E2K1.6.9.2
EMP	INDL IMP	SECURITY	CONVOY GUARDX4 XXXXX	E2K1.6.9.6
EMP	INDL IMP	SECURITY	INTERNAL X2 XXXXX	E21.6.9.1
EMP	INDL IMP	SECURITY	RESUPPLY CV XXXXX	E2H1.6.9.5
EMP	INDL IMP	SECURITY	SC RESUPPLY XXXXX	E2P1.7.2.1.1
EMP	OM CONVOY	COMMUNICATE	OPERATE RADIO 13T10	E2K1.2.3.2.1
EMP	OM CONVOY	DETERMINE	CONVOY ROUTES 13T30	E6K1.1.4
EMP	OM CC"VOY	NAVIGATE	CONVOY 13T30	E6K1.2.2
EMP	OM CONVOY	OPERATE	CONVOY TRUCKX7 XXXXX	E2K1.2.1
EMP	OM IMP	COMMUNICATE	ADDED COMM REQ 13T10	E31.6.7.4
EMP	OM IMP	COMMUNICATE	CHG CRYPTO DAY 13T10	E21.3.3.2.1.2
EMP	OM IMP	CONNECT	GEN CABLE X2XXXXX	E2D1.6.3.2.3
EMP	OM IMP	CONNECT	MS PWR CABLESX2XXXXX	E2D1.6.2.2
EMP	OM IMP	CONNECT	OFFSITE PWR 52010	E41.6.9
EMP	OM IMP	CONNECT	PHONE SYST XXXXX	E2D1.6.7.1.2.2
EMP	OM IMP	INSTALL	GND GEN 2 XXXXX	E2D1.6.3.2
EMP	OM IMP	INSTALL	GND MS X2 XXXXX	E201.6.2.2
EMP	OM IMP	INSTALL	MCPE 13T10	E4D1 5 6
w- "	<del></del>			

Table B.1-1 (Continued)

EMB	<b>414</b> 1 140		MADE VA VVVVV	<b>5001</b> 6 6 1
EMP	OM IMP	INSTALL	MCPE X4 XXXXX	E2D1.6.6.1
EMP	OM IMP	LAY	GCS PWR CABLX2 XXXXX	E2D1 . 6 . 3 . 1
EMP	OM IMP	LAY	MS PWR CABLEX2 XXXXX	E2D1.6.2.2
	OM IMP	LAY	MS PWR CABLEX2 XXXXX	E2D1.6.3.1
EM/2				
EMP	OM IMF	LAY	PHONE WIRE XXXXX	E2D1.6.7.1.2.1
EMP	OM IMP	LAY	PHONE WIRE XXXXX	E2D1.6.7.1
EMP	OM IMP	OFFLOAD	CV X2 XXXXX	E2D1.6.8.2.4
	•			
EMP	OM IMP	OFFLOAD	MS TRUCK X2 XXXXX	E2D1 . 6 . 2 . 1
EMP	OM IMP	OPERATE	30 KW GEN 52D10	E21.6.3.9
EMP	OM IMP	OPERATE	30 KW GEN 52D10	E41.6.3.9
EMP	OM IMP	OPERATE	REFUEL GENS XXXXX	E21.6.8.1
EMP	OM IMP	PGS!TION	CV TRUCK ASST XXXXX	E2K1.3.1.3.5.1
EMP	OM IMP	POSITION	MS TRUCK ASST XXXXX	E2K+, 3, 1, 3, 7, 1
			TARP BOW CV X2 XXXXX	
EMP		REMOVE		E2D1.6.8.2 1
EMP	OM IMP	REP.OYE	TARP BOW SC X2 XXXXX	E2D1.6.8.2.2
EMP	OM IMP	SETUP	CAMFLG AVH X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG CV X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG GCS X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG GEN X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG LS X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG MS X5 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG RGT X7 XXXXX	E2D1.6.1
EMP	OM IMP	SETUP	CAMFLG RS X5 XXXXX	E3D1.6.1
EMP	OM IMP	SETUP		P9E4D1.6.2.3.1
EMP	OM LAU	CONTROL	PRELAU OPS AVO 13T1C	E4A1.5.4.2
EMP	OM LAU	CONTROL	PRELAU OPS MC 13T3C	E6A1.5.4.2
EMP	OM LAU	CONTROL	PRELAU OPS MPG 13T10	E3A1.5.4.2
				-
EMP	OM LAU	LAUNCH	XXXXX	XXA1 F.6
EMP	OM LAU	PREFLIGHT	ATTACH WNGS X2 13T10	E3A J.1.1.2.3
EMP	OM LAU	PREFLIGHT	LOAD AV ON STND13T10	E2A1.5.1.1.2.2
EMP	OM LAU	PREFLIGHT	OPEN AV CONTAINISTIO	E2A1.5.1.1.2.1
EMP	6M LAU	SECURE	AV TO LS 13T10	E2A1.5.1.3.3
EMP	OM LAU	SECURE	AVH FM SERVICE 13110	E3A1.5.7.9.1
EMP	OM LAU	SECURE	LS 13T10	E3A1.5.7
EMP	OM LAU	SECURE	RS FM LAU X3 13T10	E3J1 . 5 . 7 . 1
EMP	OM LAU	SECURE	STOW LS AV GER 13T10	E2A1.5.1.3.3
EMP	OM LAU	SETUP	AVH FOR SERVICE13T10	E3A1.5.7 9
EMP	OM LAU	SETUP	ENERGIZE GCS EQ13T10	E3K1.5.4.1
EMP	OM LAU	SETUP	INST LS LADDER XXXXX	E2A1.5.2.1.2
			LS IN LSS ASST XXXXX	•
EMP		SETUP		E2A1.5.2.1.2
EMP	OM LAU	SETUP	PREP LS FOR LAUISTIO	E3A1.5.2.2.4
EMP	OM LAU	SETUP	RIG LS DAVIT 13T10	E2A1.5.1.3
EMP	OM LAU	SETUP	RS FOR LAUNCH 13T10	E3J1.5.5.3
EMP	OM LAU	SETUP	RS !N RSS 13T10	E3J1.5.5.2
EMP	OM LAU	TRANSFER	AV TO LS X3 13T10	E3A1.5.1.3.2
EMF	OM LAU	TRANSIT	AVH TO HIDE XXXXX	E2A1.5.7.4
EMP	OM LAU	TRANSIT	AVH TO RS 13T10	E3J1.5.5.1.1
EMP	OM LAU	TRANSIT	LS TO LSS 13T10	E3A1.5.2.1.1
EMP	OM LAU	TRANSIT	RS TO RSS 13T10	E3J1,5.5.1
EMP	OM MP	ANALYZE	MISSION PROFILE13T30	E6A1.4.2
	= ' ' '			
EMP	OM MP	BRIEF	MISSION ONSITE 13T30	E6A1.4.4
EMP	OM MP	BRIEF	OFFSITE TRAVEL 13T40	E7F1.7.7
EMP	OM MP		PRESENT OFSITE 13T40	
		BRIEF		E7F1.7.7
EMP	OM MP	CHECK	END DATA CK 13T10	E4A1.4.7.1.3
EMP	OM MP	CREATE	MISSION OVERLAY13T10	E3A1.4.5
EMP	OM MP	CREATE	SIT DISP X2 13T10	E31.4.2.1
EMP	OM MP	CREATE	UPDATE INTL SITISTIO	E3A1.4.2
EMP	OM MP	ENTER	ENTER DATA 13T10	E2A1.4.7
EMP	OM MP	ENTER	RECORD MISSION 13T10	E2A1.4.7
EMP	CM MP	OPERATE	SC TK OFSITE XXXXX	E2F1.7.7
EMP	JM MP	SETUP	NAV DISPLAY 13T10	E2 41 . 4 . 7 . 2
EMP	OM SETUP	CONDUCT	VERIFY SITE SEL13T40	E1K1.3.1.2
	OM SETUP			
EMP		CONDUCT	VERIFY SURVEY 13T30	E6K1.3.1.2
EMP	OM SETUP	CONNECT	FOC X2 13T10	E2K1.3.3.1.1.2

Table B.1-1 (Continued)

EMP	OM SETUP	CONNECT	GEN 1 CABLE X2 XXXX	(X E2K1.3.4.1.2
EMP	OM SETUP	CONNECT	RGT GEN CABLX2 13T1	
			<del>-</del>	
EMP	OM SETUP	CONNECT	RS GUIDE CBLX2 13T1	
EMP	OM SETUP	LAY	FOC X3 13T1	10 E3K1.3.3.1.1.1
EMP	CM SETUP	LAY	GEN 1 CABLE X2 XXXX	KX E2K1.3.4.1.1
	OM SETUP		RS GUIDE CBLX2 XXXX	
EMP		LAY		
EMP	OM SETUP	OFFLOAD	AVH TK STUP X2 XXXX	(X E2K1.3.2.2.5
EMP	OM SETUP	OFFLOAD	GCS TK X2 XXXX	(X E2K1.3.2.2.2
			LS TK X2 XXXX	
EMP	OM SETUP	OFFLOAD		
EMP	OM SETUP	OFFLOAD	RGT X2 XXXX	KX E2K1.3.2.2.7
EMP	OM SETUP	OFFLOAD	RS TK XXXX	(X E2K1.3,2,2.3
	OM SETUP	OFFLOAD	SC X2 XXXX	
EMP		•		
EMP	OM SETUP	POSITION	2 30KW GEN XXXX	(X E2K1.3.1.1.6
EMP	OM SETUP	POSITION	ALL TRUCKS X7 XXXX	(X E2K1.3.1
EMP	OM SETUP	POSITION	GCS TRUCK ASST XXXX	
EMP	OM SETUP	POSITION	LEVEL GCS TKX2 XXXX	(X E2K1.3.1.3.2.2
EMP	OM SETUP	POSITION	LEVEL LS TK X2 XXXX	(X E2K1.3.1.3.3.2
EMP	OM SETUP	POSITION	LS TRUCK ASST XXXX	· · · · · · · · · · · · · · · · · · ·
EMP	OM SETUP	POSITION	RGT ASST XXXX	KX E2K1.3.1.3.6.1
EMP	OM SETUP	POSITION	ROT TRAILER XXXX	(X E2K1.3.1.1.6
EMP	OM SETUP	POSITION	RS TRUCK ASST XXXX	
EMP	OM SETUP	POSITION	SC XXXX	KX E2K1.3.1.3.1
EMP	OM SETUP	POSITION	UNHITCH RGT X2 XXXX	KX E2K1.3.1.3.6.2
EMP	OM SETUP	POSITION	UNHTCH 2 30KWX2XXXX	
EMP	OM SETUP	POSITION	WALKERS STONXS XXXX	
EMP	OM SETUP	REMOVE	TARP BOW AVHX2 XXXX	KX E2K1.3.2.1.5
EMP	OM SETUP	REMOVE	TARP BOW LS X2 XXXX	
	***			
EMP .	OM SETUP	REMOVE	TARP BOW RS X2 XXXX	KX E2K1.3.2.1.5
EMP	OM SETUP	REMOVE	TARP RGT X2 XXXX	KX E2K1.3.2.1.2
EMP	OM SETUP	SETUP	GCS ANTENNA 13T1	10 E2K1.3.3.4
EMP	OM SETUP	SETUP	GCS COMM 13T1	
EMP	OM SETUP	SETUP	GCS CRYPTO 13T1	10 E3K1.3.3.2.1.3
EMP	OM SETUP	SETUP	GUS ENVIRON XXXX	(* E2K1.3.5.4
		_		
EMP	OM SETUP	SETUP		
EMP	OM SETUP	SETUP	GCS GND X2 XXXX	KX E2K1.3.4.2
EMP	OM SETUP	SETUP	GCS HARDWARE XXXX	KX E2K1.3.5.4 9.1
EMP	OM SETUP	SETUP	GCS LDR-PLAT XXXX	
EMP	OM SETUP	SETUP	GEN 1 GND X2 XXXX	
EMP	OM SETUP	SETUP	GND RGT GEH X2 XXXX	KX E2K1.3.4.2
EMP	OM SETUF	SETUP	LS FOR LAU X2 13T1	IO E4K1.3.2.2.4.1
EMP	OM SETUP	START	30KH GEN 52D1	· · · · · · · · · · · · · · · · · · ·
EMP	OM SETUP	START	INIT DATA LOAD 13T1	IO E3K1.3.5.4.2.1
EMP	OM SETUP	START	RGT CEN X2 52D	O E2K1.3.4.3.1.1.
		CONDUCT	MAP . ZCON 13T4	
EMP		=		
EMP	OM SS	EVALUATE	PRCPOSED SITE 13TA	40 E7B1.1.2.3
EMP	OM SS	NAVIGATE	CROSS COUNTRY 13T2	20 E5B1.1.2.2
EMP	OM SS	OPERATE	RADIO XXXX	
		•		
EMP	OM SS	OPERATE	VEHICLE XXXX	KX E2B1, 1, 2, 1
EMP	OM SS	SURVEY	ASSIST XXXX	KX E251.1.3
EMP	OM SS	SURVEY	PROPOSED SITE 13T4	
EMP	OTS IMP	LAY	OFFSITE WIRE XXXX	KX XXD1,6,7.1.1
EMP	O'S MP	MAINTAIN	CBR DECON XXXX	KX XXD1.6.6.3
EMP	OTS IMP	PROVIDE	ADMIN SUPPORT XXXX	KX XX1.6.8
EMP	OTS IMP	PRC''IDE	BERTHING FAC XXXX	
EMP	OTS IMP	PRO DE	DEF POSITION XXXX	KX XXD1.6.4.2
EMP	OTS !MP	PROVIDE	DEF WIR XXXX	KX XXD1.6.4.3
	OTS IMP	PROVIDE		· · · · · · · · · · · · · · · · · · ·
EMP			FOXHOLES XXX	
EMP	OTS IMP	PROVIDE	MESS FAC XXXX	
EMP	OTS IMP	PROVIDE	SANI FAC XXXX	KX XXD1.6.5.1
EMP	OTS IMP	PROVIDE	SHOWER FAC XXXX	
EMP	OTS IMP	PROVIDE	SURV SERV XXX	
FLT OPS	OM CONTROL	CONDUCT	ARTYOBS MPC 13T1	IO E3A2.2.3
FLT OPS	OM CONTROL	CONTROL	AV FLIGHT AVO 13T	
•				
FLT OPS	OM CONTROL	CONTROL	AV MISSION MC 13T	30 E6A2.2.3

Table B.1-1 (Continued)

			_	
	<b>6</b> PS	OM RECOVERY	LOAD	AV ON AVH 13110 E4W2.3.2.4
	OPS	OM RECOVERY	LCAD	AV ON AVH X3 XXXXX E2W2.3.3.4
	<b>OPS</b>	OM RECOVERY	REMOVE	AV FM RS 13T10 E4W2.3.3.1
FLT	OPS	OM REJOVERY	REMOVE	AV FM RS X3 XXXXX E2W2.3.3.3.1
FLT	OPS	OM RECOVERY	SECURE	RS FM RECVRYX3 13T10 E3W2.3.2.1.6
FLT	<del>O</del> PS	OM RECOVERY	SETUP	RS FOR RECVRY 13T10 E3W2.C.2.1.6
FLY	OPS .	OM RECOVERY	SUPERVISE	SAFETY 13T20 E5W2.2.5
FLT	OPS .	OM RECOVERY	TRANSIT	AV-AVH TO DEST XXXXX E2W2.3.3
FLT	OPS	OM RECOVERY	TRANSIT	AVH-RSS XXYXX E2W2.3.3.4
ORG	MAIN 1	PM AV	INSP	150 HR ENG MOD 13T10 E3150 HR PM CAA
	MAIN 1	PM AV	INSP	150 HR LHW 13T10P9E4150 HR PM GAD
	MAIN 1	PM AV	INSP	150 HR RHW 13T10P9E415C HR 2M DAE
	MAIN 1	PM AV	INSP	75 HR BLAD 13T10P9E475 HR PM DACE
	MAIN 1	PM AV	INSP	75 HR FS 13T10P9E475 HR PM GAC
	MAIN 1	PM AV	iNSP	75 HR PROP 13T10P9E475 HR PM GAAM
	MAIN 1	PM AV	INSP	75 HR STRUCT 13T10P9E475 HR PM GAA/
	MAIN 1	PM AV	INSP	A/A SENS 13T10P9E4 GAAH
_	MAIN 1	PM AV	INSP	ATTREF ASSY 13T10P9E4 GAAJ
		PM AV		AV REC HORN 13T20P9E5W GOL
			INSP	— ·
	MAIN 1	PM AV	INSP	
	MAIN 1	PM AV	INSP	PRELT AV 13T10 E3A CA
	MAIN 1	PM AV	INSP	PROP AV SS 13T10P9E4W GAJ
	MAIN 1	PM AV	INSP	PSTFLT AV 13T10 E3W DA
	MAIN 1	PM AV	RPL	150 HR ALTR 13T1C 9E4150 HR PM GAA
	MAIN 1	PM AV	RPL	150 HR ALTR 13T2G 9E5150 HR PM GA/
	MAIN 1	PM AV	RPL	150 HR ALTR 13T10P9E4150 HR PM GA/
0RG	MAIN 1	PM AV	RPL	150 HR PROP 13T10P9E4150 HR PM OAA
ORG	MAIN 1	PM AV	RPL	300 HR FPUMP 13T10P9E4300 HR PM GAC
ORG	MAIN 1	PM AV	RPL	75 HR SPK PLG 13T10 E375 HR PM GAAN
ORG	MAIN 1	PM AV	RPL	75 HR SPK PLG 13T13P9E475 HR PM GAAN
ORG	MAIN 1	PM AV	RPL	MPS DAY/FLIR 13T10P954 DE
ORG	MAIN 1	PM AV	RPL .	MPS DAY/FLIR 13T10P954 5E
ORG	MAIN 1	FM AV	svc	150 HR ENG MAIN13T10 E4150 HR PM GA/
<b>SRG</b>	MAIN 1	PM AV	SVC	150 HR ENG MAIN13T10P9E4150 HR PM GA/
	MAIN 1	PM AV	SVC	AV 75 HR 13T10 E375 HR PM 0A
_	MAIN 1	PM AV	SVC	AV 75 HR 13T10P9E475 HR PM 0A
	MAIN 1	PM AV	SVC	CLN SHRD WNDWS 13T10 EZA GEBAB
	MAIN 1	PM AV	SVC	DMPS (3XWK) 13T10 E4 5E
	MAIN 1	PM AV	SVC	FMPS (3XWK) 13T10 E4F0E
	MAIN 1	PM AV	SVC	PRELT AV 13T10 E3A DA
	MAIN 1	PM AVH	INSP	AV CONTAINER 13T10 E2 GAT
	MAIN 1	PM AVH	INSP	AV HOIST FX 13T20 E5 GAN
	MAIN 1	PM AVH	INSP	CRANE 13T10P9E4 DASA
	MAIN 1	PM AV-I	INSP	CRANE KIT 13T10P9E4 DAS
	MAIN 1	PM GCS	INSP	AIR FILTER 13T10P9E4 XODAAK
				· · · · · · · · · · · · · · · · · · ·
	MAIN 1	PM GCS	INSP	AUX SYS PWR 13T10P9E4 XODAAXX .
	MAIN 1		INSP	BLWR CENTR 13T10P9E4 XODAAJCE
	MAIN 1	PM GCS	INSP	DATA LINK 13T10 E4 CDAC
	84 A 2 B C 4		LNCD	FIFOT INOT: 10T10P0F4 VERAAC
ORG	MAIN 1	PM GCS	INSP	ELECT INSTL 13T10P9E4 XODAA3
	MAIN 1	PM GCS	INSP	NAV DISP SYS DA13T10P9E4 ODAJ
	MAIN 1 MAIN 1	PM GCS PM GC3 PM GC3	INSP INSP	NAV DISP SYS DA13T10P9E4 CDAJ PSG-2A 13T10 E4 XCDAB3
ØRG	MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS	insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG	MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS	insp insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	insp insp insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	insp insp insp insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	insp insp insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	insp insp insp insp insp insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	Insp Insp Insp Insp Insp Insp Insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	Insp Insp Insp Insp Insp Insp Insp Insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG ORG ORG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS	INSP INSP INSP INSP INSP INSP INSP INSP	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG ORG URG URG	MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1 MAIN 1	PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS PM GCS	Insp Insp Insp Insp Insp Insp Insp Insp	NAV DISP SYS DA13T10P9E4
ORG ORG ORG ORG ORG CRG CRG	MAIN 1	PM GCS PM GCS	INSP INSP INSP INSP INSP INSP INSP INSP	NAV DISP SYS DA13T10P9E4
ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN 1	PM GCS PM GCS	INSP INSP INSP INSP INSP INSP INSP INSP	NAV DISP SYS DA13T10P9E4
ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN 1	PM GCS PM GCS	INSP INSP INSP INSP INSP INSP INSP INSP	NAV DISP SYS DA13T10P9E4

Table B.1-1 (Continued)

ORG	MAIN	PM GCS	SVC	COM/SIG RK	13T20FyE5	XODAL
ORG	MAIN 1	PM GCS	SVC	GCS DOOR	13T20P9E5	XODAAR
	MAIN 1	PM GCS	SVC	GCSIU F SCN	13T20P9E5	ODA' C
DRG	MAIN 1	PM GC3	SVC	GCSIU S SCN	13T20P9E5	<b>ODAL</b> D
ORG	MAIN 1	PM GCS	SVC	MCPE	13T10P9E4	XODAAX
ORG	MAIN 1	PM GCS	SVC	PRC 68 BAT 5XH	XXXXX E2	CDAB:
	MAIN 1	FM GCS		T/C TERM	13T20F 3E5	6D4
			SVC			
DRG	MAIN :	PM GCS	SVC	VRA	13T10 E4	ODAFK
ORG	MAIN 1	PM GCS	SVC	<b>∀RA</b>	13T20P9E5	ODAFK
ORG	MAIN 1	PM GCS	TEST	AUX SYS PWR	13T10P9E4	XODAAXX
	MAIN 1	PM GCS	TEST	AV C+D	13T20P9E5	DADH
	MAIN 1	PM GGS	TEST	B'.WR CENTR	13T10P9E4	XCDAAJCE
ORG	MAIN 1	PM GC3	TEST	MC C+D	13T20: 9E5	ODAFH
ORG	MAIN 1	PM GCS	TEST	MP C+D	13T20P9E5	ODAEH
	FAIN 1	PM GCS	TEST	POWER CABLE	13T10 E4	XODALQ
	MAIN 1	PM GCS	TEST	PRC-66 (5XHR)	XXXXX E2	XCDAB1
ORG	MAIN 1	PM GC3	TEST	PWR MONITOR	13T:0P9E4	XODAASAE
<b>GRG</b>	MAIN 1	PM GCS	TEST	SHELTER ASSY	13T10P9E4	XCIDA.
GRG	MAIN 1	PM GOS	TEST	T/C _RM	13T20P9E5	<b>3</b> D4
		PM LS	SVC	LAUNCH SYS MO	13T10P9E4	OB .
ORG	MAIN 1	PM LS	TEST	SHUTTLE	13T10P9E4A	OB .
ORG	MAIN 1	PM MS	INSP	AC PWR PNL	13T10P9E4	t-GQC
ORG	MAIN 1	PM MS	INSP	ADT TESTSET	13T10P9E4	GGQH
	MAIN 1	PM MS	INSP	AIR COND	13T10P9E4	DGAAN
						-
	MAIN 1	PM MS	INSP	AIR FILTER	XXXXX E2	GGAAP
ORG	MAIN 1	PM MS	INSP	AV FAULT CK	13T10P9E4	<b>ପ</b> ଧ୍ୟପ
ORG	MAIN 1	PM MS	: NSP	AV WING STE	13T1C E2	<b>G</b> GX
	MAIN 1	PM MG	INSP	AV WING STE WK		OGX
-	77.IN 1	PM MS	INSP	AV WING STE WK		OGR
ORG	MAIN 1	PM MS	! NSP	AV WORKSTAND	13710 E2	<b>∂</b> GZ
JRG	MAIN 1	PM MS	INSP	AVF! TRG IF	13110P9E4	<b>08</b> 0J
GRG	MAIN 1	PM MS	INSP	BLOWER INST	13T10P9E4	OGAAK
	MAIN 1	PM MS		CLN BLOWER		OGAAK
		_	INSP			-
	MAIN 1	PM MS	insp	DC FWR ASSY	13T10P9E4	OGQKBX
ORG	MAIN 1	PM MS	INSP	DOOR INST	XYXXX E2	OGAAM
ORG	MAIN 1	PM MS	INSP	ELECTRIC INST	13T10P9E4	OGAAL
	MAIN 1	PM MS	INSP	ELEVON TCAB	10T10P9E4	GGQKA
	MAIN 1	PM MS	INSP	HOIST	1STID E2	OGY
ORG	MAIN 1	PM MS	INSP	INSP NPS	13T10P9E4	<b>GGR</b>
ORG	MAIN 1	PM MS	INSP	LOGIC DRAWR	13T10PSE4	GGQB
CRG	MAIN 1	PM MS	INSP	MPS LIFT FX	XXXXX E2	GEV
-	MAIN 1	PM MS				
			INSP	OPER ASSY	13T10P9E4	1GQD
	MAIN 1	PM MS	INSP	POWER MONT	13T1079E4	GGAALAE
ORG	MAIN 1	PM MS	INSP	PWR SUPLY A	13710P9E4	<b>GGQF</b>
ORG	MAIN 1	PM MS	INSP	PWR SUPLY B	13T10P9E4	CGQG -
	MAIN 1	PM MS	INSP	RACK ASSY	13T10P9E	COQEX
	MAIN 1	PM MS	INSP	RELAY ASSY	13T10P9E4	GGGBJX
DRG	MAIN 1	PM MS	INSP	SELF TEST FX	13T10P9E4	53QCX
ORG	MAIN 1	PM MS	INSP	SHELT	XXXXX E2	OGAA
SRG	MAIN 1	PM MS	INSP	TEST CABLE	13T10P9E4	GGQK
	MAIN 1	PM MS	INSP		13T10P9E4	QGQF
ORG	MAIN 1	PM MS	INSP	UMB TESICAB	13T10P9E4	o(≈.)KB
<b>GRG</b>	MAIN 1	PM MS	insp	VIDES MONTR	13T10P9E4	<b>6</b> .
CRG	MAIN 1	PM MS	SVC	F/B ASSY	13T20P9E5	₹
	MAIN 1	PM MS	SVC	M-13 DECEN		
					XXXXX E2	1 - 7 1
	MAIN 1	PM MS	SVC	TEST EU CAL PM		OG .
ORG	MAIN 1	PM MS	SVC	TEST EQ CAL PM	13T20P9E5	<b>O</b> G
ORG	MAIN 1	PM MS	TEST	AC PWR PNL	13T10P9E4	OGQ("
	MAIN 1	PM MS	TEST	AV FAULT	13T10P9E4	960
	MAIN 1	PM MS	TEST	DC PWR ASSY	13T10PSE4	DOOKBX
ORG	MAIN 1	PM HS	TEST	LOGIC DRAWR	13T1C.29E4	OGGB
ORG	MAIN 1	PM MS	TEST	OPER ASSY	13" OP954	<b>530</b> D
	MAIN 1	PM MS	TEST	RELAY ASSY	107 0 758 4	OGGBJX
	MAIN 1	PM RS	svc		1,2100044	
UNG		111 113	340	RECOV SYS MO	2 t	<b>0</b> 0

Table B.1-1 (Continued)

UNG	MA.N 1	PM VH	INSP	1.5KW GEN X2	52D10 E4 MGRGT
CRG	MAIN 1	PM VH	INSP	30KW GEN 1	52D10 E2 GGS
	MAIN 1	PM VH	INSP	30KW GEN 2	52D10 E2 GGS
	MAIN 1	PM VH	INSP		XXXXX E2 GRG
	NAIN 1	PM VH	INSP	· · · · · · · · · · · · · · · · · · ·	XXXXX E2 GRG
	MAIN I	PM VH	INSP	•	52D10 E2 GRG
	MAII. 1	PM VH	INSP		XXXXX E2 GRG
	MAIN	PM VH	INSP	TRLR, M200 DY2	_
	MAIN 1	PM VH	INSP	TRLR, M200 M02	
	MAIN I	PM VH	INSP	TRLR, M200 WK2	
-	MAIN 1	PM VH		TRUCK, M882 DY	
		PM VH	INSP	•	
	MAIN 1		INSP	TRUCK, M882 M6	
	MAIN 1	PM VH	INSP	TRUCK, M882 WK	
	MAIN 1	PM VH	INSP	TRUCK, M927 DY	
	MAIN 1	PM VH	INSP	TRUCK, M927 DY	· -
	MAIN 1	PM VH	INSP	TRUCK, M927 DY	
	MAIN 1	PM VH	INSP	TRUCK, M927 DY	
	MAIN	PM VH	INSP	TRUCK, M927 MO	
	MAIN 1	PM VH	INSP	TRUCK, M927 MO	
	MAIN 1	PM VH	INSP	TRUCK, M927 10	
GRG	MAIN T	PM VH	INSP	TRUCK, M927 MG	
ORG	MAIN 1	PM VH	INSP	TRUCK, M927 WK	XXXXX E2 GCS
ORG	MAIN 1	PM VH	! NSF	TRUCK, M927 WK	XXXXX E2 GCV
ORG	MAIN 1	PM VH	INSP	TRUCK, M927 WK	XXXXX E2 GHV
ORG	MAIN 1	PM VH	INSP	TRUCK, M927 WK	XXXXX E2 GMV
ORG	MAIN 1	PM V!	INSP	TRUCK, M942 DY	XXXXX E2 GLV
ORG	MAIN 1	PM VH	INSP	TRUCK, M942 DY	XXXXX E2 GRV
ORG	MAIN 1	PM VH	INSP	TRUCK, M942 MO	XXXXX E2 GLV
ORG	MAIN 1	PF VIU	INSP	TRUCK, M942 MO	
	MAIN 1	Pf	INSP	TRUCK, M942 WK	
	MAIN 1	01	INSP	TRUCK, M942 WK	XXXXX E2 GRV
	MAIN 1	PM	LUBE	TRUCK, M882 DY	
	MAIN 1	PM VE	LUBE	TRUCK, M927 DY	
	MAIN 1	PM VH	'LUBE	TRUCK, M927 DY	
	MAIN 1	PM VH	JBE	TRUCK, M927 DY	
	MAIN	PM VH	LUBE	TRUCK, M927 DY	
	MAIN 1	PM VH	LUBE	TRUCK, M927 MO	
	MAIN 1	PM VH	LUBE	TRUCK, M927 MG	
	MAIN 1	PM VH	LUBE	TRUCK, M927 MO	
	MAIN 1	PM VH	LUBE	TRUCK, M927 MO	
	MAIN 1	PM VH	LUBE	TRUCK, M942 DY	
	MAIN 1	PM VH	LUJE	TRUCK, M942 DY	
	MAIN 1	PM Vrl	LUBE	TRUCK, M942 MO	
	MAIN 1	PM VH	LUBE	TRUCK, M942 MO	
	MAIN 2	CM AV	ADJ	PROPUL SYS	13T10P9E40AAM
	MAIN 2	CM AV	INSP	AF AV RPR	13T10P9E46A
	MAIN 2	CM AV	INSP	AV PWR CAB	13T20 ESGAAE
	MAIN 2	CM AV	INSP	DMPS	13T10P9E40E
	MAIN 2	CM AV	INSP	FMPS	13T10P9E4F0E
	MAIN 2	CM AV	INSP	FUEL SYS	13T10 E3GAC
	MAIN 2	CM AV	INSP	FUEL SYS	13T1UP9E40AC
	MAIN 2	CM AV	INSP	PROPUL SYS	13T10P9E4GAAM
-		CM AV	R/R	A/A SENS	13T10P9E46AAHX
	MAIN 2			ADT ELECTRON	
	MAIN 2	CM AV	;		
	MAIN 2	CM AV	R/R	ADT ELECTRON	13T10P9E4GAAWAF
	MAIN 2	CM AV	R/R	ATTREF ASSY	13T10P9E4GAAJ
	MAIN 2	CM AV	R/R	AV PWR CAB	13T20 E56AAE
	MAIN 2	CM AV	₹/R	DMPS	13T10 E40E
	MAIN 2	CM AV	R/R	DMPS	13T10P9E46E
-	MAIN 2	CM AV	R/R	ENGINE ASSY	13T10 E3GAAMABAH
	MAIN 2	CM AV	Ř/Ř	ENGINE ASSY	13T10P9E40AAMABAH
	MAIN 2	CM AV	R/R	ENGINE MODULE	13T10P9E4GAAMAB
	MAIN 2	CM AV	R/R	FCEP	13T10P9E4GAAL
URG	MAIN 2	CM AJ	R/R	FMPS	13T10 E4F6E

Table B.1-1 (Continued)

<b>60</b> 0	MA 131 2	CM AV	B / B	EMDe	107106 4065
	MAIN 2	CM AV	R/R	FMPS	13710F = E4F0E
	MAIN 2	CM AV	K, R	FUEL SYS COMP	13T10 E40ACX
	MAIN 2	CM AV	R/R	FUEL SYS COMP	13T10P9E46ACX
ORG	MAIN 2	CM AV	R/R	LH WING	13T10 E3GADX
ORG	MAIN 2	CM AV	R/R	LH WING	13T10P9E46ADX
ORG	MAIN 2	CM AV	R/R	NIR	13T10P9E4GAAK
	MAIN 2	CM AV	R/R	PWR ASSY	13T10P9E46AABX
	MAIN 2	CM AV	R/R	RH WING	13T10 ESCAEX
	MAIN 2	CM AV			
			R/R	RH WING	13T10P9E46AEX
	MAIN 2	CM AV	RPR	A/A SENS	13T10P9E46AAHX
	MAIN 2	CM AV	RPR	FUEL BLADDER	13T10P9E40ACB
	MAIN 2	CM AV	RPR	FUSELAGE	13T1CP9E4GAAAX
ORG	MAIN 2	CM AV	RPR	LH WING	13T10 E3GADX
ORG	MAIN 2	CM AV	RPR	LH WING	13T10P9E46ADX
ORG	MAIN 2	CM AV	RPR	NIR	13T10P9E4GAAK
ORG	AIN 2	CM AV	RPR	RH WING	13T10 E36AEX
ORG	MAIN 2	CM AV	RPR	RH WING	13T10P9E46AEX
	MAIN 2	CM AV	RPR	SURFACES	13T10P9E46ADX
	MAIN 2	CM AV	RPR	SURFACES	13T10P9E40AEX
	MAIN 2	CM AV	TEST	AV PWR CAB	13T20 E56AAE
				_	
	MAIN 2	CM AVH	INSP	SUPP STAND	13T10 E46AJ X
-	MAIN 2	CM AVH	R/R	AV HOIST FX	13T20P9E56AN X
ORG	MAIN 2	CM AVH	R/R	CRANE KIT	13T10P9E40AS
ÖRG	MAIN 2	CM AVH	R/R	FUEL SERV	13T10 E46AH
ORG	MAIN 2	CM AVH	R/R	REC SYS COMP	13T20P9EEGAL X
ORG	MAIN 2	CM AVH	RPR	AV HOIST FX	13T20P9E56AN X
ORG	MAIN 2	CM AVH	RPR	AV SUPP STD	13T20P9E50AJ X
	MAIN 2	CM AVH	RPR	FUEL SERV	13T10P9E4GAH
-	MAIN 2	CM AVH	TEST	AV HOIST FX	13T10 E46AN X
	MAIN 2	CM AVH	TEST	FUEL SERV	13T10P9E46AH
				IMAGE SIMU	
	MAIN 2	CM GCS	INSP		
	MAIN 2	CM GCS	INSP	MAIN COMPUTER	13T2OP9E5@DALBAA
	MAIN 2	CM GCS	INSP	MC C+D ASSY	13T20P9E56DAFA
	MAIN 2	CM GCS	INSP	MCPE	13T10P9E4XODAAX
ORG	MAIN 2	CM GCS	R/R	AV C+D COMP	13T2OP9E5@DADH
₩£G	MAIN 2	cm GCS	R/R	DATA LOADER	13T10 E46DALC
ORG	MAIN 2	CM GCS	R/R	AV C+D ASSY	13T10 E40DADX
ORG	MAIN 2	CM GCS	R/R	AV C+D ASSY	13T20P9E5JDADX
CRG	MAIN 2	CM GCS	R/R	DATA LOADER	13T20P9E56DALC
	MAIN 2	CM GCS	R/R	GCS CPU	13T10 E4CDALB X
	MAIN 2	CM GCS	R/R	GCS CPU	13T20P9E5@DALB X
	MAIN 2	CM GCS	R/R	GCS IU	13T10 E40DALD
	MAIN 2	CM GCS	R/R		
				MAIN COMP PCB	13T2OP9E5CDALBAA
_	MAIN 2	CM GCS	R/R	MC C+D ASSY	13T10 E46DAFA
	MAIN 2	CM GCS	R/R	MC C+D ASSY	13T20P9E50DAFA
	MAIN 2	OM GCS	R/R	MC C+D COMP	13T20P9E56DAFH
ORG	MAIN 2	CM GCS	R/R	MCPE	13T10P9E4X6DAAX
JRG	MAIN 2	CM GCS	R/R	MP C+D COMP	13T20P9E56DAEH
ORG	MA'N 2	CM GCS	R/R	MP R/R ASSY	13T1C E4CDAEX
ORG	MAIN 2	CM GCS	R/R	MP R/R ASSY	13T20P9E50DAEX
ORG	MAIN 2	CM GCS	R/R	NAV DISP UNIT	13T10P9E46DAJ X
	MAIN 2	CM GCS	R/R	NAV DISP UNIT	13T10P9E46DAJ X
	MAIN 2	CM GCS	R/R	PORT DATA DEV	13T10P9E46D7
	MAIN 2	CM GCS	R/R		13T20 E5XCDALPX
-					
	MAIN 2	CM GCS	R/R	SHELT ASSY	13 10P3E4XODAA
	MAIN 2	CM GCS	R/R	SHELT MISC	13T10P9E4KODA X
	MAIN 2	CM GCS	R/R	T/C TERM	13T20P9E5X6D4
	MAIN 2	CM GCS	R/R	TRNG IU	13T10P9E40DEA
ORG	MAIN 2	CM GCS	R/R	VRA COMP	13T10 E46DAFK
ORG	MAIN 2	UM GCS	R/R	VRA COMP	13T20P9E5@DAFK
	MAIN 2	CM GCS	RPP	AV C+D CNSOLE	13T10 E40DAD
	MAIN 2	CM GCS	RPR	AV C+D CNSOLE	13T2OP9E5ODAD
	MAIN 2	CM GCS	RPR	AV C+D COMP	13T20P9E55DADH
	MAIN 2	CM GCS	RPR	COM/SIG RK	13T10 E4XODAL
_,,,		<b></b>			

Table B.1-1 (Continued)

ORG	MIN	2	CM	GCS	RPR	COM/SIG RK	13T20F9E5X6DAL
ORG	MAIN	2	CM	GCS	RPR	DATA LOADER	13T20P9E50DALC
GRG	MAIN	2	CM	GCS	RPR	DC PWR COMM	13T10P9E4X6DAB6
	MAIN	_	-	GCS	RPR		13T20P9E56DALD
		-					13T20P9E56DADG
	MAIN			GCS	RPR		
	MAIN			GCS	RPR		13T2OP9E55DALBAA
ORG	MAIN	2	CM	GCS	RPR	MC C+D CN	13T20P9E56DAF
ORG	MAIN	2	CM	GCS	RPR	MC C+D COMP	13T20P9E56DAFP
	MAIN			GCS	RPR		13T10P9E4X6DAAX
-		2		GCS	PPR		13T10 E46DAE
		_	-				
	MAIN			GUS	RPR		13T20P9E56DAE
ORG	MAIN	2		GCS	RPR		13T20P9E5@DAEH
ØRG	MAIN	2	" M	GCS	RPR	NAV DISP UNIT	13T10P9E46DAJ X
<b>GRG</b>	MAIN	2	:M	GCS	ŘPR	SHELT ASSY	13T10P9E4XCDA X
ORG	MAIN	2	CM	GCS	RPR	VRC-46 (X4)	13T10P9E4X6DAB4
	MAIN			GCS	TEST		13T10 E46DAD
				GCS	TEST		13T20P9E56DAD
	MAIN						· · · - · · · · · · · · · · · · · · · ·
	MAIN			GCS	TEST		13T20P9E50DADX
ORG	MAIN	2	CM	GCS	TEST	C+D ASSY	13T20P9E5@DADX
ORG	MAIN	2	CM	GCS	TEST	DATA LOADER	13T2GP9E56DALC
<b>GRG</b>	MAIN	2	CM	GCS	TEST	IMAGE SIMU	13T20 E56D6X
	MAIN	2		GCS	TEST		13T20P9E56DAFA
		2		GCS	TEST		13T10 E46DAF
		_					
	MAIN	-		GCS	TEST		13T20P9E56DAF
	MAIN			GCS	TEST		13T20P9E56DAEX
ORG	MAIN	2	CM	GCS	TEST	MP C+D CNSCLE	13T10 E4ODAE
ORG	MAIN	2	CM	GCS	TEST	MP C+D CNSOLE	13T20P9E56DAE
ORG	MAIN	2	CM	GCS	TEST	NAV DISP UNIT	13T10P9E4CDAJ X
	MAIN	2		GCS	TEST	• • • • • • •	13T20P9E56DAFK
	MAIN						13T10 E40BAX
		_		LS	INSP		
	MAIN	_		LS	INSP		13T10P9E46BAX
ORG	MAIN	2	CM	LS	R/R	AV LOAD ASSY	13T10P9E46BAX1
ORG	MAIN	2	CM	LS	R/R	HYD PUMP	13T20P9E50BMA
ORG	MAIN	2					
		~	CM	LS	R/R	LAUNCH ASSY	13T20P9E5C3C X
CRG				LS	R/R R/R		13T20P9E5C3C X
	MAIN	2	CM	LS	R/R	LAUNCH SYS COMP	13T10P9E46BAX
ORG	MAIN MAIN	2	CM CM	LS LS	R/R RPR	LAUNCH SYS COMP AV LOADER	13T10P9E46BAX 13T10 E46BAX
ORG ORG	MAIN MAIN MAIN	2 2 2	CM CM CM	LS LS LS	R/R RPR RPR	LAUNCH SYS COMP AV LOADER R/R ASSY COMP	13T10P9E46BAX 13T10 E46BAX 13T20P9E56BC X
ORG ORG ORG	MAIN MAIN MAIN	2 2 2	CM CM CM	LS LS LS	R/R RPR RPR TEST	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER	13T10P9E46BAX 13T10 E46BAX 13T20P9E56BC X 13T10 E46BAX
ORG ORG ORG	MAIN MAIN MAIN	2 2 2	CM CM CM	LS LS LS	R/R RPR RPR	LAUNCH SYS COMP AV LOADER R/R ASSY COMP	13T10P9E46BAX 13T10 E46BAX 13T20P9E56BC X 13T10 E46BAX
ORG ORG ORG ORG	MAIN MAIN MAIN MAIN	2 2 2	CM CM CM CM	LS LS LS	R/R RPR RPR TEST	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK	13T10P9E46BAX 13T10 E46BAX 13T20P9E56BC X 13T10 E46BAX
ORG ORG ORG ORG	MAIN MAIN MAIN MAIN	2 2 2 2 2 2	CM CM CM CM CM	LS LS LS MIC	R/R RPR RPR TEST R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY	13T10P9E46BAX 13T10 E46BAX 13T20P9E56BC X 13T10 E46BAX 13T10P9E46DAG
ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2	CM CM CM CM CM CM	LS LS LS MIC MIC MIC	R/R RPR RPR TEST R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT	13T10P9E4GBAX 13T10 E4GBAX 13T20P9E5GBC X 13T10 E4GBAX 13T10P9E4GDAC 13T10P9E4MBB1 13T10P9E4MRGT
ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	CM CM CM CM CM CM	LS LS LS Mic Mic Mic Mic	R/R RPR RPR TEST R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40DAC
ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	CM CM CM CM CM CM CM CM	LS LS LS MIC MIC MIC MIC MIC MIC	R/R RPR RPR TEST R/R R/R R/R RPR R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAU 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40DAC 13T10P9E40GAAN
ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		LS LS LS MIC MIC MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R RPR R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GQ X
ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		LS LS LS MIC MIC MIC MIC MIC MS MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GQ X 13T10P9E40GX
ORG ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	22222222222222		LS LS LS MIC MIC MIC MIC MS MS MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MBGT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GA 13T10P9E40GAA
ORG ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2		LS LS LS MIC MIC MIC MIC MIC MS MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GQ X 13T10P9E40GX
ORG ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	22222222222222		LS LS LS MIC MIC MIC MIC MS MS MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MBGT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GA 13T10P9E40GAA
ORG ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	2222222222222222		LS LS LS MIC MIC MIC MIC MIC MS MS MS MS MS	R/R RPR RPR TEST R/R R/R R/R R/R RPR R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MRB1 13T10P9E4MRGT 13T10P9E40BAC 13T10P9E40GAAN 13T10P9E40GX 13T10P9E40GX 13T10P9E40GAA 1 13T10 E40GP 13T10P9E40GQ 1
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ORG ORG ORG ORG ORG ORG ORG ORG ORG ORG	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222		LS LS LS MIC MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R R/R RPR R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E40DAC 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA
ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	COM	LS LS LS MIC MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R R/R R/R R/R R/R R/	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MBGT 13T10P9E40GAAN 13T10P9E40GQ X 13T10P9E40GAA 1 13T10P9E40GAA 1 13T10P9E40GA 1 13T10P9E40GQ 1 13T10P9E40GQ 1
ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	COM	LS LS LS MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R R/R RPR R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX MS HOIST	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MCT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GAAN 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAAL X
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ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	COM	LS LS LS MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R R/R RPR R/R R/R R/R R/R R/R	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX MS HOIST SHELT	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MCT 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GAAN 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAAL X
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ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	$\begin{array}{c} \texttt{CM} & \texttt{CM} & \texttt{CM} \\ \texttt{CM} \\ \texttt{CM} & \texttt{CM} \\ \texttt{CM} & \texttt{CM} \\ \texttt{CM} & \texttt{CM} \\$	LS LS LS MIC MIC MIC MIC MS	R/R RPR RPR TEST R/R R/R R/R R/R R/R R/R R/R R/R R/R R/	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX MS HOIST SHELT INTERFACE RECOVR ASSY RECOVR ASSY	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E4MRGT 13T10P9E40GAAN 13T10P9E40GAAN 13T10P9E40GAA 1 13T10P9E40GAA 1 13T10P9E40GQ 1 13T10P9E40GQ 1 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40CB 13T10P9E40CB
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ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	$\begin{array}{c} \mathbf{M}  $	LS LS LS MICC MICC MS MS MS MS MS MS MS MS RS RS RS RS RS RS RS RS RS RS RS RS RS	R/R RPR RPR TEST R/R R/R R/R R/R R/R R/R R/R RPR RPR RPR	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX MS HOIST SHELT INTERFACE RECOVR ASSY RECOVR ASSY RECOVR INTFCE R/R RECOVR ASSY PWR REEL/CBL 1.5KW GEN 1	13T10P9E40BAX 13T10 E40BAX 13T10 E40BAX 13T10 E40BAX 13T10 E40BAX 13T10P9E40DAC 13T10P9E40BB1 13T10P9E40BAC 13T10P9E40CA 13T10P9E40CA 13T10P9E40CA 13T10P9E40CB
ORGO ORGO ORGO ORGO ORGO ORGO ORGO ORGO	MAIN MAIN MAIN MAIN MAIN MAIN MAIN MAIN	222222222222222222222222222222222222222	$\begin{array}{c} \mathbf{M} & $	LS LS LS MICC MICC MS	R/R RPR RPR TEST R/R R/R R/R RPR R/R R/R RPR R/R R/R RPR RP	LAUNCH SYS COMP AV LOADER R/R ASSY COMP AV LOADER DATA LINK RACK INIT ASSY RGT DATA LINK R/R AIR CONDITN AV FAULT ISOL AV WING STE SHELT MISC AV COOL ASSY AV FAULT ISOL A' WORKSTAND ELECTRIC SYS MPS LIFT FX MS HOIST SHELT INTERFACE RECOVR ASSY RECOVR ASSY RECOVR INTFCE R/R RECOVR ASSY PWR REEL/CBL 1.5KW GEN 2 30KW GEN 2	13T10P9E40BAX 13T10 E40BAX 13T20P9E50BC X 13T10 E40BAX 13T10 E40BAX 13T10P9E40DAC 13T10P9E4MBB1 13T10P9E40DAC 13T10P9E40DAC 13T10P9E40GAAN 13T10P9E40GAA 13T10P9E40GAA 13T10P9E40GQ 1 13T10P9E40GQ 1 13T10P9E40GQ 1 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40GAAL X 13T10P9E40CA

# APPENDIX C SUMMARY OF MOS ASSIGNMENTS BY EQUIPMENT

Table C-1 contains all of the MOSs required for the RPV equipment configurations. Changes from the previous study are identified by the delta symbol ( $\Delta$ ). The FLIR mission payload assembly was the only new equipment added.

Table C-1

Summary of MOS Assignments by Equipment

LOGISTICS

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<b>a</b>	) Ol		∆13T /	13T	13T		13T	13T	13T	1.3T		13T	13T	13T	13T	13T	13T			13T	13T	1 3/1	101	1 3.I.		13T				Δ52D		13T	
£ì	DS		;	44B	63G		32E	35E	35E	34Y		34Y	52D	<u> </u>	26T	45G	35E			63W 63G	633	ME 9		448		6 3W	63G	ļ	ME 9	52D		6 3W	<b>9</b> 3G
REFERENCE	01		A13TP9	13TP9	13TP9	63B	13TP9	13TP9	13TP9	13TP9		13TF9	13TP9	13TP9	13TP9	13TP9	13TP9			6 3B	13mP9	1 34799	04401	13779		63B			∆ 52D	A 52D		63B	
<b>LL</b>	' ပ၊		Δ13T	13T	13T		13T	13T	13T	13T		13T	13T	13T	13T	13T	13T			13T	13T	1 34	101	T 3.I.		13T				∆52D		13T	
EQUIPMENT NAME		END ITEM: AIR VEHICLE	FLIR Mission Payload Assembly	Fuselage Structure, Exterior Surfaces	Engine Fuel and Electrical Systems			Airspeed and Altitude Sensors	Attitude Reference Assembly	Flight Control Electronic Package,	Control Actuators	Central Processing Unit Module Assembl	Propulsion System, Engine Module	Airborne Data Terminal	Television Camera	Laser System	Missich Payload System Assemblies	,	END LTEM: AIR VEHICLE HANDLER	Truck	Fuel Service Assembly		·	AV Recovery Harness, AV Container	END ITEM: CARGO VEHICLE	Truck		END ITEM: GENERATORS	Trailer	Generator Set 30 KW	END ITEM: GROUND CONTROL STATION		
CONTROL NUMBER			FOE	UAAA, OAD, OAE	OAAB, OAAE, OAAMABAF,	ONAMABAH, OAC	OAAG	OAAH, CAAX	OAAJ	OAAL, OADA, OAEA		OAALAB	OAAM, OAAMAB	OAAWAF	OEAAB, OEAAD	OEAAC, OEAEE	OEAAF-OEBAA			GHV	024	280		OAL, OAT		GCV			GGT	965		ecs	

∆Change from previous study.

<u>EQUIPME</u> Shelter	IPMENT NAME	) I	REFERENCE 0 13TP9	E DS 44B	C 13T	BASELINE O 13TP9	DS 44B
	Ass	13T	13TP9	52C	13T	13rp9	52C
	Protective Entrance	1 3T	LSTP9	52C 43M	1.3T	LSTP9	52C 43M
	Chemical Agent Detector M13	13T	310	31E	13T	A31V	31E
	Radiac Meters	13T	13TP9	35H	13T	13TP9	35H
	Power Monitor	13T	13TP9	34Y	13T	13TP9	<b>∆31E</b>
	Radio Set AN, PRC-68	13T	310	31E	13T	Δ31V	31E
	Antenna OE-254	13T	310	31E	13T	<b>∆31V</b>	31E
	Digital Message Device AU/PSG-2A	13T	310	34Y	13T	Δ31V	34Y
	Radio Set AN/VRC-46	13T	310	31E	13T	A31V	31E
	Secure Equipment TSEC/KY-57 & HYX-57/TSEC	13T	310	318	13T	Δ31V	318
	Direct Current Cor 'cations Power	13T	310	31E	13T	Δ31V	31E
	Communications Mode Selector Control,	13T	31V	31E	13T	Δ31V	31E
	Misc. Comm.						
	Telephone Set TA-312/PT	13T	310	36н	13T	Δ31ν	36н
	Data Link Power Supply	13T	13TP9	31E	13T	13TP9	;
	Video Reconstruction Unit	13T	13TP9	26T	13T	13TP9	! !
	Master Interface Unit	13T	13TP9	<b>7</b> 97	13T	13TP9	 
	Video Monitor Assembly	13T	1.3TP9	26T	13T	13TP9	!
	Communications Panel Assembly	13T	310	31E	13T	Δ31V	;
	Ground Data Terminal Ground Display	13T	13 i'P9	34Y	13T	13TP9	!
	AV Control & Display Assembly	13T	13TP9	3 <b>4</b> Y	LOT	13TP9	ļ
	Mission Payload Control & Display Assembly	13T	13TP9	34Y	13T	13TP9	!
	Mission Commander's Control & Display	13T	1.3TP9	34Y	13T	13TP9	!
	Assembly	•		(		1	
		1 3T	13TP9	Z6T	13T	13TP9	1
	Teleprinter Assembly AN/UGC-74A	13T	13TP9	317	13T	13TP9	317
	Navigation Display Unit	13T	13TP9	∆26B	13T	13TP9	<b>∆</b> 26B
	Main Computer, Cable Assembly	13T	13TP9	341	13T	13TP9	1
	Data Loader	13T	13TP9	34Y	13T	13TP9	}
	Interface Unit	13T	13TP9	3 <b>4</b> Y	13T	13TP9	1
	Π	13T	13TP9	1 1	13T	13TP9	1
	Portable Data Entry Davice	13T	13TP9	3 <b>4</b> Y	1.3T	13TP9	!

 $\Delta$  Change from previous study.

LOGISTICS CONTROL NUMBER	EQUIPMENT NAME	œ.	REFERENCE	ы	щ	BASELINE	
		ပ <u>ု</u>	01	DS	OI	01	DS
CΓΛ	END ITEM: LAUNCHER SUBSYSTEM Truck	13T	63B	6 3W	13T	6 3B	6 3W
				636			636
OBA	Air Vehicle Loader	13T	13TP9	6 3W	13T	13TP9	6 3W
OBB	Initializer Assembly, Hydraulics	13T	13TP9	26L	13T	1.3TP9	<b>26L</b>
OBC	Launcher Assembly	13T	13TP9	6 3W	13T	13TP9	6 3W
OBCAAAF	Launcher Control Panel, Power Supply	13T	13TP9	∆ 26B	13T	13TP9	Δ 26B
080	Launcher Command Module	13T	13TP9	Д 26В	13T	13TP9	1
	END ITEM: MAINTENANCE SHELTER						
GMV	Truck	13T	6 3B	6 3W	13T	63B	6 3W
				<b>6</b> 3G			636
OGAA	Shelter Assembly	13T	13TP9	44B	13T	13TP9	44B
OGAALAE	Power Nonitor	13T	13TP9	Д 26В	13T	13TP9	Д 26В
OGAAN, OGP	Air Conlitioner, Air Vehicle Cooling Assembly	1.3T	13TP9	52C	13T	13TP9	52C
<b>0</b> 50	AV Fault Isolator	13T	13TP9	!!	13T	13TP9	1
OGDA	Video Monitor	13T	13TP9	26T	13T	13TP9	1
OGOL, OGOM	Power Supply	13T	13TP9	∆26B	1.3T	13TP9	!
OGR	Nitrogen Purge Set	13T	13TP9	1	13T	13TP9	
XWL 1	Binnculars	13T	13TP9	<b>4</b> 1C	13T	13TP9	41C
XWL 2	Radiac Changer	13TP9	13TP9	35H	13TP9	13TP9	35H
XWL4	Grenade Launcher M203	13T	13T	45B	13T	13T	45B
XALS	Machine Gun	13T	13T	<b>4</b> 5B	13T	13T	45B
XWL6, XWL.7	Multimeters	13TP9	13TP9	35H	13TP9	13TP9	35H
XWL3, XWL8, XWL9	Compass, Survey Set, Theodolite	13T	13TP9	<b>4</b> 1B	13T	13TP9	41B
XWL10	Too1	13TP9	13TP9	31E	13ТР9	13TP9	31E
	END ITEM: PRIM3 MOVER	13T	6 3B	WE 9	13T	63B	6 3W
GPV	Truck			63G			63G
	END ITEM: RECOVERY SUBSYSTEM						
GRV	Truck	1.3T	63B	6 3W	13T	63B	WE 9
				63G			636
OCA, OCLA, OCAB	Recovery Assembly, Hydraulics, Crane Structure	13T	13TP9	6 3W	13T	13TF9	<b>9</b> 8

 $\Delta$  Change from previous study.

DS	Δ35E	63W 52D 
BASELINE	13TP9 A	63B 52D 13TP9 13TP9
조 조	137	13T 63B Δ52D Δ52D 13T 13TP9 13T 13TP9
w 2	45G	63W 52D 26L 26L
REFERENCE	13TP9	13T 63B Δ52D Δ52C 13T 13TP9 13T 13TP9
C	$\bar{z}$	13T A 5 2D 13T
EQUIPMENT NAME	Recovery Guidance Assembly	END ITEM: REMOTE GROUND TERMINAL Traile: Generator Set 1.5 KW Antenna Remote Ground Terminal Electronics
LOGISTICS CONTROL NUMBER	OCB	GGT MGRGT MRG1 MAGT 1

 $\Delta$  Changes from previous study.

## APPENDIX D PERSONNEL REQUIREMENTS ANALYSIS

#### D. 1 PERSONNEL FLOW RATES

This appendix includes the detailed results of the Personnel Requirements Analysis. The contents of Table D.1-1 are the personnel flow rates; (1) attrition; (2) promotion; and (3) trainees, transients, holdees and students (TTHS) overhead percentages. The variation of rates among MOSs and paygrades are a result of Career Management Field (CMF) structure differences, bonus levels, internal or external policy changes. The importance of measuring the foregoing rates is to estimate the quantities and qualities of personnel replacements needed to support present or future system specific manpower requirements.

# D.2 INTERACTIVE MAN POWER-PERSONNEL ASSESSMENT AND CORRELATION TECHNOLOGY (IMPACT) MODEL RESULTS

Table D.2-1 contains the personnel requirements by MOS/paygrade for the baseline systems, 3/2 shift concept including Platoon Headquarters requirements. Similar information was prepared for the Sustained Tempo of operations. Per onnel requirement structures will vary according to input rates and the level and quantity of manpower requirements within each MOS.

Table D.1-1. Personnel Flow Rates

-			•	
m	IOS.	=	- 1	31

PAYGRADE	MANPOWER	ATTRITION	<u>UPGRADE</u>	TTHS
E-1	٥.	0.518	1.311	0.
E-2	0.	7.360	1.757	0.050
E-3	406.0	0.266	0.907	0.046
E-4	168.0	0.363	0.269	0.048
E-5	112.0	0.243	0.241	0.030
E-6	112.0	0.146	0.151	0.027
E-7	70.0	0.164	0.149	0.

#### MCS = 13T P9

PAYGRADE	MANPOWER	ATTRITION	<u>UPGRADE</u>	TTHS
E- 1	0.	0.518	1.311	0.
E-2	٥.	0.360	1.757	0.050
E-3	0.	0.266	0.907	0.046
E-4	56.0	0.363	0.269	0.048
E-5	56.0	0.243	0.241	0.030

#### MOS = 26B

PAYGRADE	MANPIWER	ATTRITION	<u>UPGRADE</u>	TTHS
E-1	0.	0.260	1.603	0.
E-3	O.	0.160	1.699	0.070
E-3	0.	0.198	1.223	0.060
E-4	14.0	0.422	0.271	0.068

#### MOS = 26L

PAYGRADE	MANPOWER	ATTRITION	UN GRADE	<u>TTHS</u>
E-1	0.	0.428	1.761	0.
E-2	0.	0.183	1.580	0.129
E-3	0.	0.159	1.113	0.129
E-4	٥.	0 247	0.368	0.068
E-5	14.0	€ 363	0.199	0.043

Table D.1-1 (Continued)

M	ľ	S	=	.3	1	F

PAYGRADE	MANPOWER	ATTRITION	<u>UPGRADE</u>	TTHS
E1	0.	0.556	1.414	0.
E-2	0.	0.340	1.432	0.013
E3	٥,	0.182	1.045	0.121
E-4	14.0	0.327	0.359	0.062

#### MOS = 31J

PAYGRADE	MANPOWER	ATTRITION	<u>UPGRADE</u>	TTHS
E-1	0.	0.430	1.726	0.
E-2	٥.	0.237	1.632	0.088
E-3	0.	0.121	1.021	0.088
E-4	14.0	0.292	0.230	0.067

#### MOS = 31S

PAYGRADE	MANPOWER	ATTRITION	<u>UPGRADE</u>	TTHS
E-1	0.	0.257	1.843	0.
E-2	0.	0.341	1.256	0.170
E-3	0.	0.204	1.067	0.169
E-4	14.0	0.367	0.470	0.110

### MOS = 34Y

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTHS
E-1	٥.	0.262	1.718	0.
E-2	0.	0.370	1.241	0.080
E-3	•	0.249	1.080	0,078
E-4	٥.	0.321	0.457	0.043
E-5	14.0	0.602	0.214	0.023

Table D.1-1 (Continued)

MOS	#	35E
-----	---	-----

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTHS
E-1	٥.	0.323	1.458	٥.
E-2	0.	0.159	1.964	0.050
E-3	0.	0.178	1.048	0.048
E-4	0.	0.410	0.383	0.063
E-5	14.0	0.420	0.205	0.115

### MOS = 35H

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTHS
E-1	٥.	0.287	1.703	0.
E-2	0.	0.272	1.531	0.210
E-3	o.	0.215	1.067	0.201
E-4	0.	0.267	0.510	0.120
E-5	14.0	0.385	0.385	0.068

#### MOS = 36H

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTKS
E-1	0.	0.382	1.553	0.
E-2	0.	0.290	1.344	0.163
E-3	0.	0.161	1.025	0.163
E-4	14.0	0.247	0.386	0.115

#### MOS = 41B

PAYGRADE	MANPOWER	ATTRITION	<u> JPGRADE</u>	TTHS
E-1	0.	0.474	1.263	٥.
E-2	0.	0.226	2.264	0.050
E-3	0.	0.367	1.265	0.050
F-A	14.0	0.493	2.274	0.019

Table D.1-1 (Continued)

M	n		=	4	1	r
1.1	u	_	•==	-		ட

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTHS
E-1	0.	0.505	1 . 424	0.
E-2	0.	0.455	1.485	0.050
E-3	0.	0.192	0.927	0.042
E-4	14.0	0.374	0.297	0.043

### MOS = 43M

PAYGRADE	MANPOWER	<u>ATTRITION</u>	UPGRADE	TTHS		
E-1	0.	0.605	1 ,, 538	0.		
E-2	<b>c.</b>	0.361	1.783	0.041		
E-3	0.	0.219	0.914	0.041		
E-4	14.0	0.245	0.074	0.024		

#### MOS = 48

PAYGRADE	MANPOHER	<u>ATTRITION</u>	<u>UPGRADE</u>	TTHS
E-1	0.	0.315	1.446	0.
E-2	o.	0.331	1.717	0.05
E~3	٥.	0.243	1.043	0.043
E-4	٥.	0.266	0.250	0.035
E~5	14.0	0.277	0.117	0.026

#### MOS = 45B

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	<u>TTHS</u>		
E-1	0.	0.320	1.628	٥.		
E-2	0.	J. 258	1.980	0.042		
E-3	0.	0.143	1.058	0.032		
E-4	14.0	0.184	0.179	0.052		

Table D.1-1 (Continued)

MOS = 520

PAYGRADE	MANPOWER	<u>ATTRITION</u>	UPGRAD_	<u>TTHS</u>
E-1	0.	0.388	1.323	0.
E-5	0.	0.294	1.917	0.051
E-3	0.	0.223	0.972	0.043
E-4	0.	0.404	0.087	0.031
E-5	14.0	0.199	0.084	.030

MOS = 52D

PAYGRADE	MANFOWER	ATTRITION	<u>UPGRADE</u>	TTHS		
E-1	C.	0.416	1.482	٥.		
E-2	0.	0.407	1.611	6.055		
E-3	0.	0.281	0.999	0.045		
E-4	14.0	0.542	0.200	0.037		

\* MOS = 52D

PAYGRADE	MANPOWER	ATTRITION	<u>UE GRADE</u>	TTHS
E-1	0.	0.416	1.482	0.
E-2	c.	0.407	1.611	0.055
E-3	56.0	.281	0.599	0.045
E-4	56.0	0.542	0.200	0.037

MOS = 63G

PAYGRADE	MANPOWER	ATTRITICIS	UPGRADE	TTHS		
E-1	٥.	0.338	1.514	0.		
E-2	0.	0.372	1 666	0.055		
E-3	0.	0.274	0.901	0.045		
E-4	o.	0.527	0.263	0.048		
E-5	14.0	0.341	0.206	o.		

<sup>\*</sup>Includes 52D Section Requirements

Table D.1-1 (Continued)

MUS = 63J

PAYGRADE	MANPOWER	ATTRITION	UPGRADE	TTHS
E-1	0.	0.420	1.610	0.
E-2	0.	0.345	1.735	0.050
E-3	0.	0.256	0.942	0.040
E-4	14.0	0.270	0.133	0.033

MOS - 53W

PAYGRADE	MANPOWER	<u>ATTRITION</u>	<u>UPGRADE</u>	TTHS	
E-1	0.	0.279	1.137	0.	
E-2	0.	0.298	1.963	0.051	
E-3	14.0	0.305	0.995	0.041	
E-4	0.	0.432	0.261	0.039	
E-5	14.0	0.437	0.174	0.	

Table D.2-1. Personnel Requirements Output

MOS = 13T RECR	RECRUITS PER YEAR =	837.4					
PAYGHADE	"ERSONNEL REQUIREMENTS	UNADJUSTED	TTHS ADJUSTED MANPOWER	PERSONNEL TO BE IRAINED PER YR	MANFOWER LOSSES PER YR	OVERHEAD LOSSES PER VR	
₽, F	457.8	•	0,	837.4	3		
\ ₩ ₩	283.5	· ;	•	600.2	ċċ	837.4	
) <del>4</del>	1009 1009	149.0	424.7	478.2	498.1	0.0	
E-3	338.7	112.0	1.0/1	385.2	111.3	273.9	
8-B	274.9	112.0		163.9	8.5 1	108.1	
E-7	132.6	70.0	70.0	4	34.2	47.5	
MOS = 13T . TCR	CRUITS PER YEAR =	142.4					
PAYGRADE	PERSONNEL REQUIREMENTS	UNADJUSTED	TTHS ADJUSTED	PERSUMNEL TO BE	MANPOWER	OVERHEAD	
		Carry Carry	X III	TRAINED PER YR	LOSSES PER YR	LOSSES PER YR	
E-1	78.0	<b>°</b>	•	142.6	ć		
, E	72.3	o d	ċ	102.2	ó	102.2	
# H	103.8	26.0	38.7	80 4 80 4	•	84.8	
n ≻	57.7	26.0	57.7	27.9	27.9	28.3 0.0	
MOS = 26B RECR	RECRUITS PER YEAR =	15.3					
PAYGRADE	PERSONNEL REQUIREMENTS	UNADJUSTED	TTHS ADJUSTED HANPOWER	PERSONNEL TO BE IRAINED PER YR	MANPOWER LOSSES PER YR	OVERHEAD LOSSES PER VR	
E-1	8.2	o.	c				
F - 2	7.1	ó	<i>; ;</i>	13.2	<b>ં</b> c		
E - G	က ( ()	•	ò	12.0	; <b>;</b>	13.2	
<b>.</b>	2	0 <b>*</b>	13.0	10.4	10.4	0.0	
MOS = 26L RECRI	RECRUITS PER YEAR =	17.9					
PAYGRADE	PERSONNEL REQUIREMENTS	UNADJUSTED	TTHS ADJUSTED MANPOWER	FERSONNEL TO BE IRAINED PER YR	MANPOWER LOSSES PER YR	OVERHEAD LOSSES PER YR	
E-1	8.5	o.	ć	0	c		
E-2	8.5	; o (		T T T		1. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4.	
п С 4-	18.3	င်င်	o c	12.9	ं०	12.9	
R-R	14.6	14.0	14.6	6.7	6.7	0.0	

Table D.2-1 (Continued)

DVERHEAD LOSSES PER YR 20.7 14.8 12.0	OVERHEAD LOSSES FER YR 12.5 10.0 8.7 0.0	0VERHEAD LOSSES PER YR 22.5 19.7 15.5 0.0	OVERHEAD LOSSES PER YR 36.8 31.9 24.6 20.0
HANPOWER LOSSES PER YR 0. 0. 0.	MANPOWER LOSSES PER YR LO 0. 0. 0. 7.8	MANPOWER 0 1.0SSES PER YR 1.0S 0.0.0.0.13.0	MANPOWER 0 LOSSES PER YR LOS 0. 0. 0. 0.
PERSONNEL TO BE IRAINED PER YR 20.7 14.8 12.0 10.2	PERSONNEL TO BE IRAINED FER YR 1 12.5 10.0 8.7 7.8	PERSONNEL TO BE IRAINED PER YR. L. 22.5 19.7 15.5 13.0	PERSONNEL TO BE IRAINED PER YR. 36.8 31.9 24.6 20.0
MANPOWER  0. 0, 0, 14,9	MANPOWER 0.0.0.0.14.9	MANPOWER 0. 0. 0. 13.3	MANPOWER 0. 0. 0. 0.
20.6 UNADJUSTED MANPOHER 0. 0. 0. 14.0	12.5 UNADJUSTED HANPOWER 0. 0. 14.0	22.5 UNADJUSTED MANPGMER 0.0.0.0.0.14.0	36.8 UNADJUSTED PANFOMER 0. 0. 0. 0.
RECRUITS PER YEAR = FERSONNEL  DE REGUIREMENTS  10.5  8.4  9.8  14.9	RECRUITS PER YEAR F FERSONNEL DE RECUIREMENIS 5.8 5.4 7.6 15.0	RECRUITS PER YEAR = FERSONNEL  DE REQUIREMENTS  10.7  12.3  12.2  15.5	RECRUITS PER YEAR = PERSONNEL DE REQUIREMENTS 18.6 19.8 18.5 25.7 14.4
MOS = 31E RECRI PAYORADE E-1 E-2 E-3 E-3	MOS = 31J RECRU <u>PAYORADE</u> E-1 E-2 E-3 E-3 E-4	MOS = 315 RECRU	MOS = 34Y RECRU

	YR LUSSES PER YR	31.2	23.6				OVERHEAD YR LOSSES PER YR	29.0	21.1	17.5		OVERHEAD YR LOSSES PER YR	17.3	13.9	0.0		OVERHEAD YR LOSSES PER YR	21.4	16.6	0.0
1	LOSSES PER YR		600	<b>8</b> .5			MANPOWER LOSSES PER YR	óc		11.5		MANPOWER LOSSES PER	·	o c	6.0		MANPOWER LOSSES PER YR	°	ंंं	10.9
	TRAINED PER YR	31.2	23.6	4 60			PERSONNEL TO BE IRAINED PER YR	29.0 24.8	21.1	17.5		PERSOWNEL TO BE IRAINED PER YR	17.3	0. 10 st	6.6		PERSONNEL TO BE IRAINED PER YR	21.4	15.3	10.9
	MANPOWER	• •	600	15.6			TTHS ADJUSTED MANPOWER	• •	00	15.0		TTHS ADJUSTED MANPOWER	•	<i>ò</i> ở	15.6		TTHS ADJUSTED MANPOWER	•		14.3
31.2	MANPOWER	<b>ં</b> છે	600	14.0		29.0	UNADUUSTED		ं	14.0	17.3	UNADJUSTED	ò	<i>.</i> 0	14.0	21.3	UNADJUSTED	ं		14.0
RECRUITS PER YEAR	REGUIREMENTS	17.5	19.3	15. 5.		MEURUIIS PER YEAR =	PERSONNEL REQUIREMENTS	14.6 13.8	16.4	15.0	RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	9.0	e 0	15.6	RECRUITS PER YEAR =	PERSONNEL REGUIREMENTS	12.3	6.2 8.7	14.3
MOS = 35E RECF	PAYGRADE	E - 1	. F. Y	ត់ សា 3 − 1 3 − 1	i	#050 II	PAYGRADE	E-1 E-2	E = 3	п п	MOS = 36H RECI	PAYGRADE	E-1	E ::3	E-4	MOS # 41B RECR	PAYGRADE	ш.	E - 2	E-4

Table D.2-1 (Continued)

(Continued)		OVERHEAD LOSSES PER YR	20.9 15.3 10.0		OVERHEAD LOSSES PER YR	8 6 10 0 10 8 7 0		OVERHEAD LOSSES FER VR	20.01 0.04.1 0.04.1		OVERHEAD LOSSES PER YR	0.6.6.0 0.100
		MANPOWER LOSSES PER YR	0000		MANPOWER LOSSES PER YR	000 <del>4</del>		MANPOWER LOSSES PER YR	<b>.</b>		MANPOWER LOSSES PER YR	ဝံဝံဝ၏
		PERSC. CL TO BE IRAINED PER YR	20.9 15.5 11.8 9.8		PERSONNEL TO BE IRAINED PER YR	0.00.4. 10.00 V.0.		PERSONNEL TO BE TRAINED PER YR.	20.9 17.2 14.4		PERSONNEL TO BE TRAINED PER YR	ଷ୍ଟୁ ଅଟି ଅବସ୍ଥାନ
Table D.2-1 (Con		TTHS ADJUSTED MANPOWER			TTHS ADJUSTED HANPOWER			TTHS ADJUSTED MANPOWER	<b>.</b>	,	TTHS ADJUSTED MANPOWER	
	20.9	UNADJUSTED		iņ. 6	UNADJUSTED	· · · · · ·	20.9	UNADJUSTED	<b></b>	8.5	UNADJUSTED	
	RECRUITS PER YEAR =	PERSONNEL. REQUIREMENTS	10.9 8.0 10.4 14.6	RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	4 W D W	RECRUITS PER YEAR =	PERSCHNEL REGUIREMENTS	9.48 9.49 9.45 9.45	RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	4 8 8 8 4 8 4 8 4 8 4 8 4 8 4 8 4 8 4 8
	MOS = 41C RECR	PAYGRADE	н п п п п п п п 	MOS = 43M RECRI	PAYORADE	교 메 패 메 	MOS = 44R RECRI	PAYGRADE	л п п п п н н н н н н н н н н н н н н н	MOS = 458 RECR	PAYGRADE	Э М М П — — — — — — — — — — — — — — — — —

Table D.2-1 (Continued)

OVERHEAD IN LOSSES FER YR	42.2 32.7 23.0		OVERHEAD LOSSES PER YR	22.1 17.3 13.8 0.0		OVERHEAD YR LOSSES PER YR	120.2 93.8 0.0 15.4		OVERHEAD R LOSSES PER YR	44.9 36.7 0.00
MANPOWER LOSSES PER YR	0000	•	MANPOWER LOSSES PER YR			MANPOWER LOSSES PER Y	0. 74.9 43.1		MANPOWER LOSSES PEH YR	6666
PERSONNEL TO BE TRAINED PER YR	42.2 32.7 28.3 23.0	į	PERSONNEL TO BE IRAINED PER YR	22.1 17.3 13.8 10.8		PERSONNEL TO BE TRAINED PER YR	120.2 93.8 74.9 58.5		PERSONNEL TO BE IRAINED PER YR	9.44 W.6.7 0.00 0.00
TTHS ADJUSTED MANPOWER			TTHS ADJUSTED MANEOWER			TTHS ADJUSTED MANPOWER	0. 38.3 38.1		TTHS ADJUSTED MANPOWER	
UNADJUSTED		· · · · · · · · · · · · · · · · · · ·	UNADJUSTED		120.1	UNADJUSTED MANPOWER	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	4.9	UNADJUSTED	0000
PERSONNEL RECUIREMENTS	24.7 14.8 23.7 46.9	RECRUITS FER VEAD #		7.11 9.60 8.04 8.05	RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	63.4 56.5 78.8 8	RECRUITS PER YEAR =	PERSONNEL REGUIREMENTS	24.0 20.0 20.0 20.0 20.0 20.0 20.0 20.0
PAYGRADE	ጠ ጠ ጠ ጠ ጠ ረነ ነጋ ፋ የህ		PAYGRA	- A M 4 - L L L L L L L L L L L L L L L L L L L	*MOS = 520 RECR	PAYGRADE	щ п п п - : : - п - : : 4	MOS = 630 RECRU	PAYGRADE	ППП 

\*52D Section Requirements

Table D.2-1 (Continued)

	OVERHEAD LOSSES PER YR	11.2 8.3 7.4 0.0		OVERHEAD LOSSES PER YR	42.6 34.6 10.7 22.7 0.0
	MANFOWER LOSSES PER YR	့ ထ ဝဝဝက်		MANPOWER LUSSES PER YR	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
	PERSONNEL TO BE TRAINED PER YR	11. 2.00 4.7 8.00		PERSONNEL TO BE TRAINED PER YR	34.2 34.2 29.7 22.7 8.6
	TTHS ADJUSTED MANPOWER			TTHS ADJUSTED MANPOWER	
11.2	UNADJUSTED MANPOWER		42.5	UNADJUSTED	0.0404
RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	හ. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4. 4.	RECRUITS PER YEAR =	PERSONNEL REQUIREMENTS	30.1 15.1 22.8 32.8 14.0
MOS = 63J RECR	PAYGRADE	ян   	MOS = 63W RECR	PAYGRADE	ጠ ጠ ጠ ጠ ጠ 